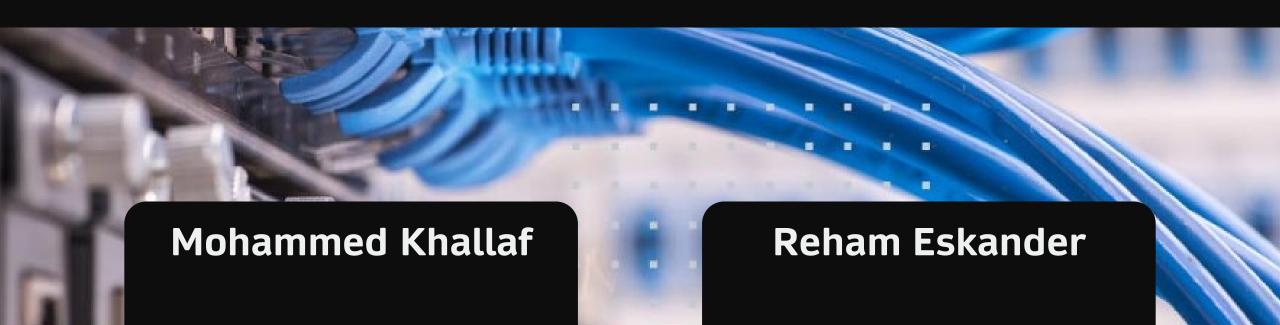
Industrial Communication



Contents

Introduction

Basics

OSI Model

Serial Link Standards

Industrial Protocols

Modbus

HART

AS-I

TCP / IP

Device-Net

Introduction

Basics

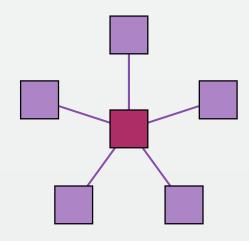
Network Topology

Point to Point



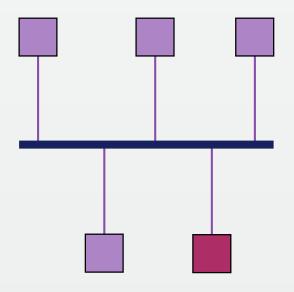
Only two devices are connected together

Star



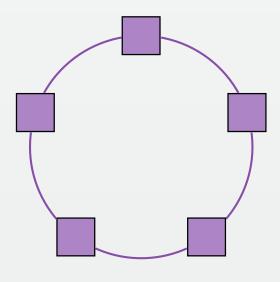
Centralized controller connected to several transmitters and actuators

Bus



Several devices share the same wires

Ring



Devices occupying positions along the ring

Topology mainly depends upon the communication method

Basics

Communication Modes

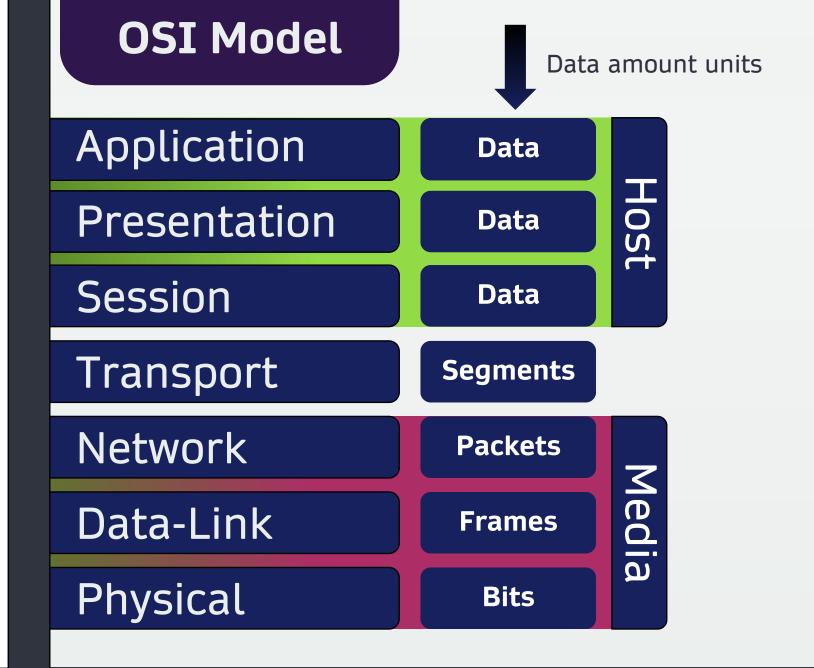
Full duplex **Simplex** Half duplex In one direction In both directions In both directions Not simultaneously Simultaneously

Basics

Open Systems Interconnect (OSI) Reference Model

Universal framework for all communication systems

Not all network protocols use every layer.



Signal Layer

Electrical specifications

Cable specifications

Physical medium

Copper wires

Optical fibers

Physical

Protocol Layer

Physical addressing

MAC

LLC

Error detection

Media Access Control -MAC

Logic Link Control -LLC

Data-Link

Packet Layer

Network



Logical addressing

Path determination

Sends data to the correct destination

Data Transmission

Transport

Determines:

- How much data to send
- How fast
- Where it goes

Interhost communication

Session

Data transfer organizing

Determines:

- The start and the end of a specific transmission
- The response rate

Presentation

Data Representation Encryption

Translating data for the application layer

Application



User Interaction

Providing network services to the end user

Application

Presentation

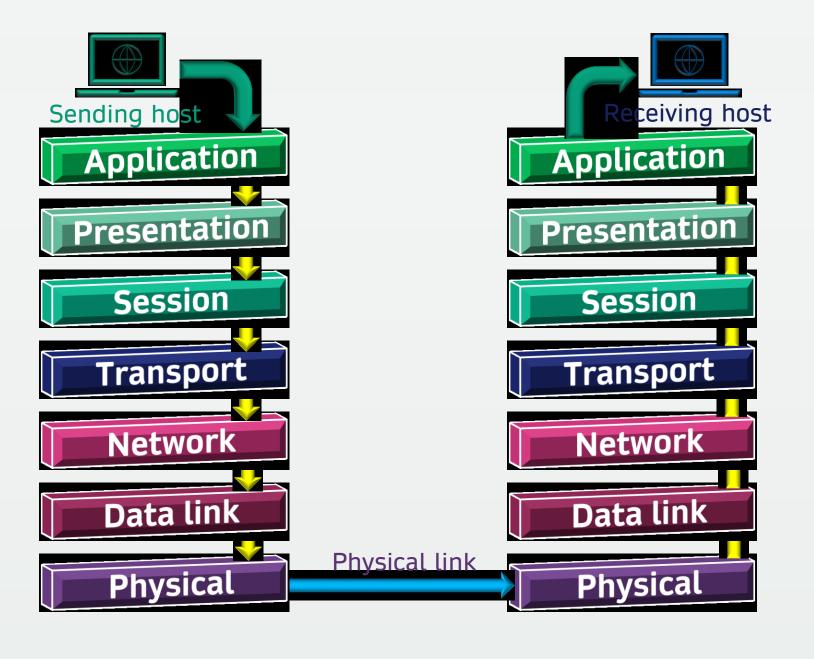
Session

Transport

Network

Data-Link

Physical



Application

Presentation

Session

Transport

Network

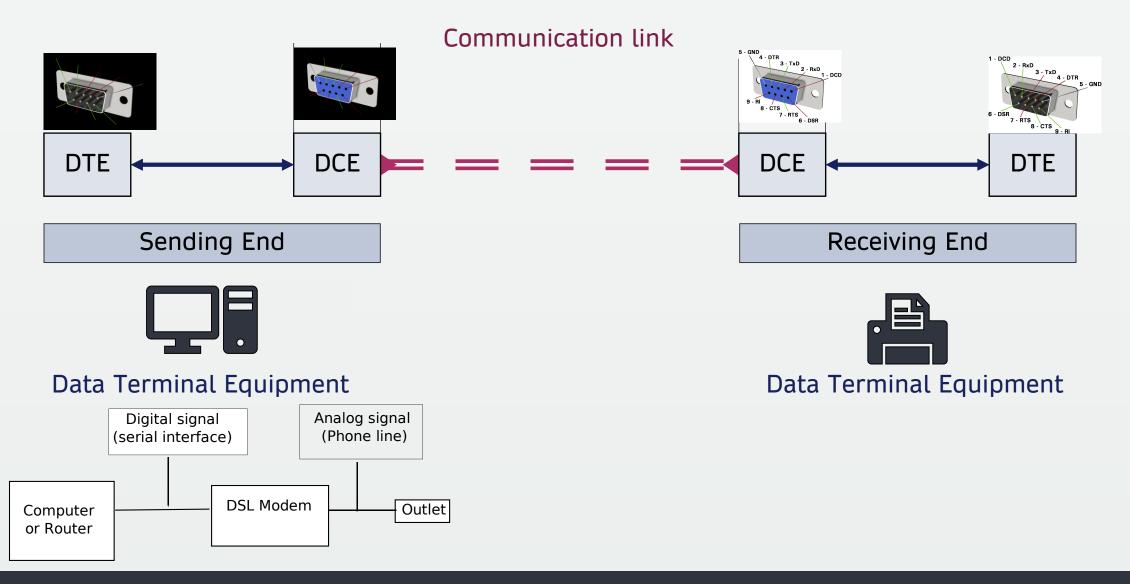
Data-Link

Physical

Industrial

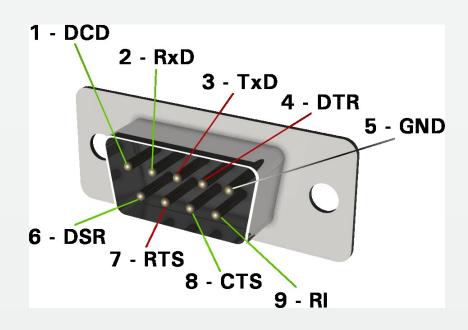
Serial Communication Standards

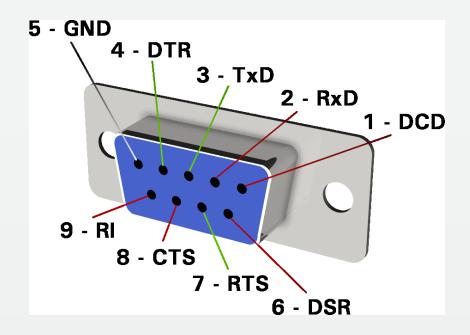
Serial data communication



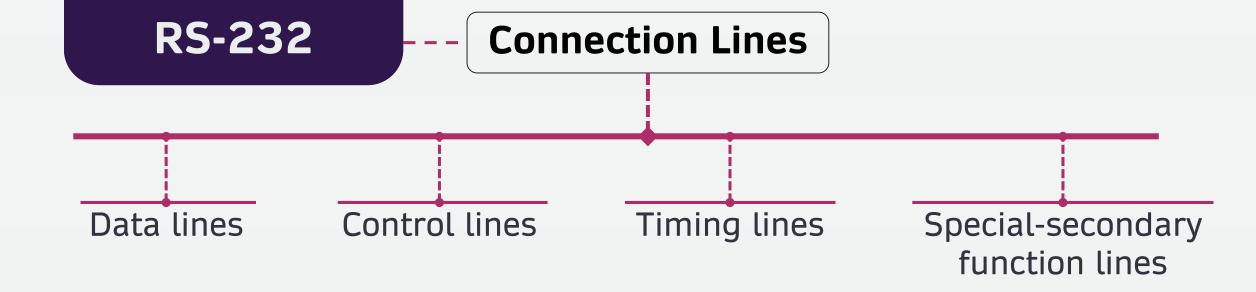
RS-232

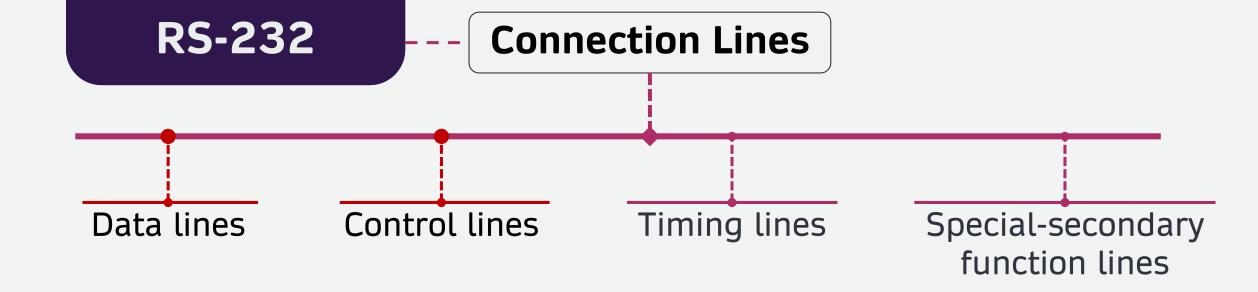
Serial data communication

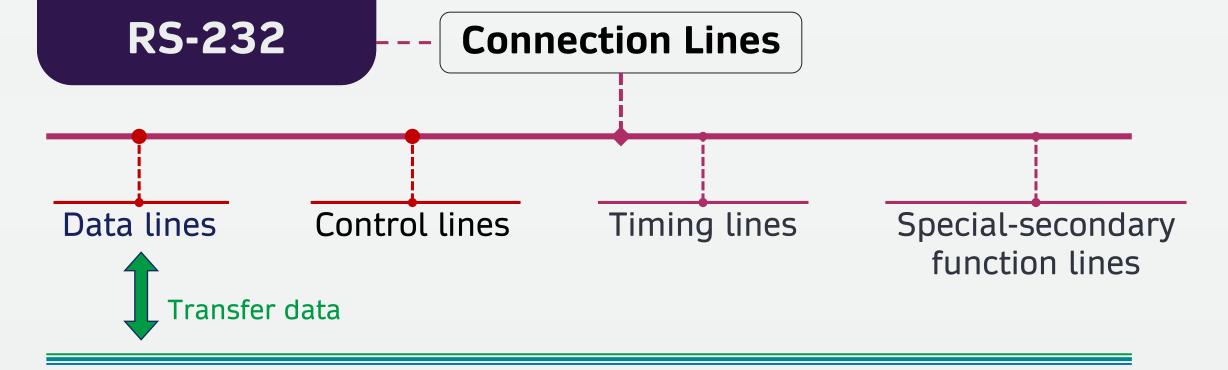


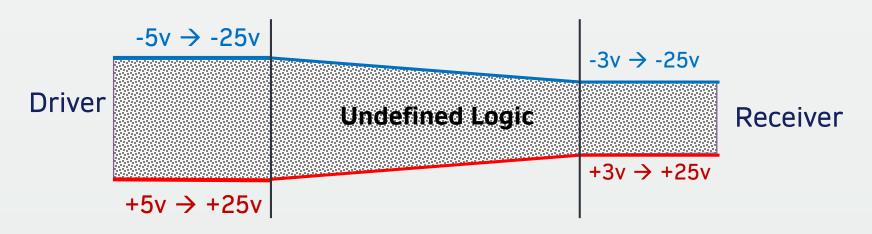


RS-232 DB-9 connector

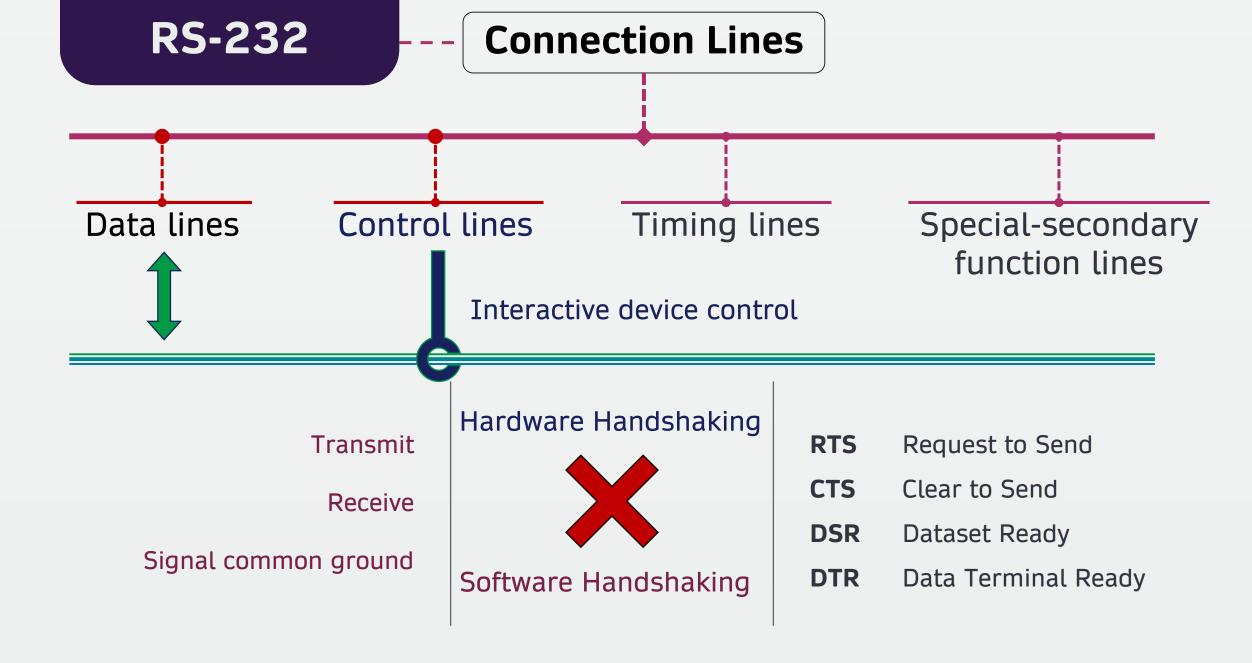






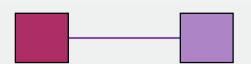


* Logic level referenced to ground



Limitations

Point to Point Restriction



Distance Limitation



Baud rate



Modern Supply Incompatibility



* For baud rate 12kbps

RS-485

Extension of RS-422

- Multi-drop on 2 wires
- Distance up to 1200m **
- Data rates up to 10Mbps **

Supports multiple modules

- Up to 32 driver/receiver on the same line
- Repeater adds more modules

** Maximum bit rate and maximum length cannot be achieved at the same time

RS-485

Differential voltage* for logic level

Less suspectable to noise

Tri-state line driver

Allows multi-drop

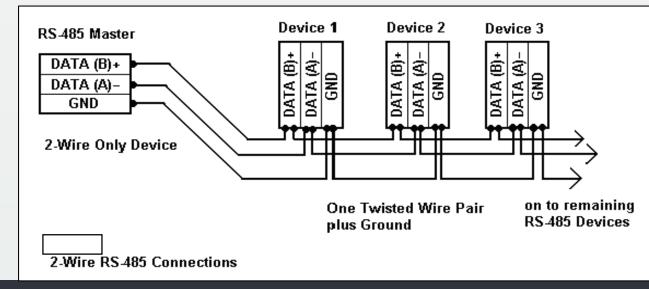
OFF state MARK SPACE Logic 1 Logic 0 -1.5 : -6v +1.5 : +6v

ON state

High impedance state

Disabled

*A terminal respect to B terminal



Current loop

0 20mA

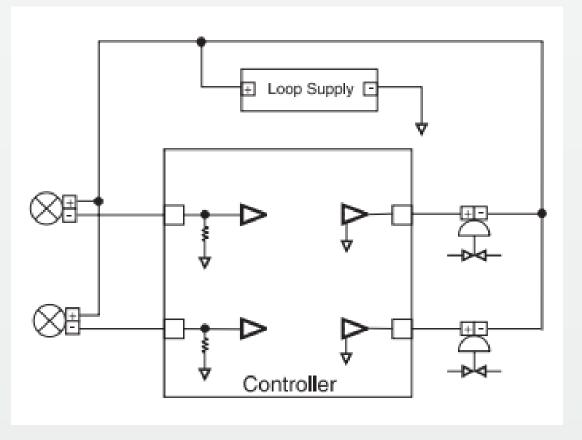
4 - 20mA

On most devices the current powers the device

Requires only two wires

Excessive Field Wiring – Minimum one wire per field device point to the centralized controller

Single loop power supply

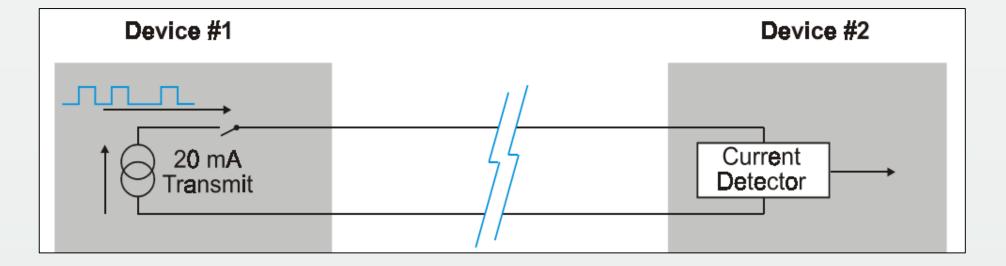


Current loop

Current measurement Voltage drop due to long distances don't employ measurement error

Can drive lines up to 1km

In reasonably slow bit rates





Industrial Protocols

Industrial Protocols

Modbus

HART

AS-I

TCP / IP

Device-Net

Modbus

Modbus

Transmission protocol

Describes the messaging communication dialog

No physical interface

Serial link

RS-232

RS-485

Open protocol

Multi-vendor integration

Point-to-Point and Multi-drop

Relatively slow

115200 baud

Single master

Multi slaves

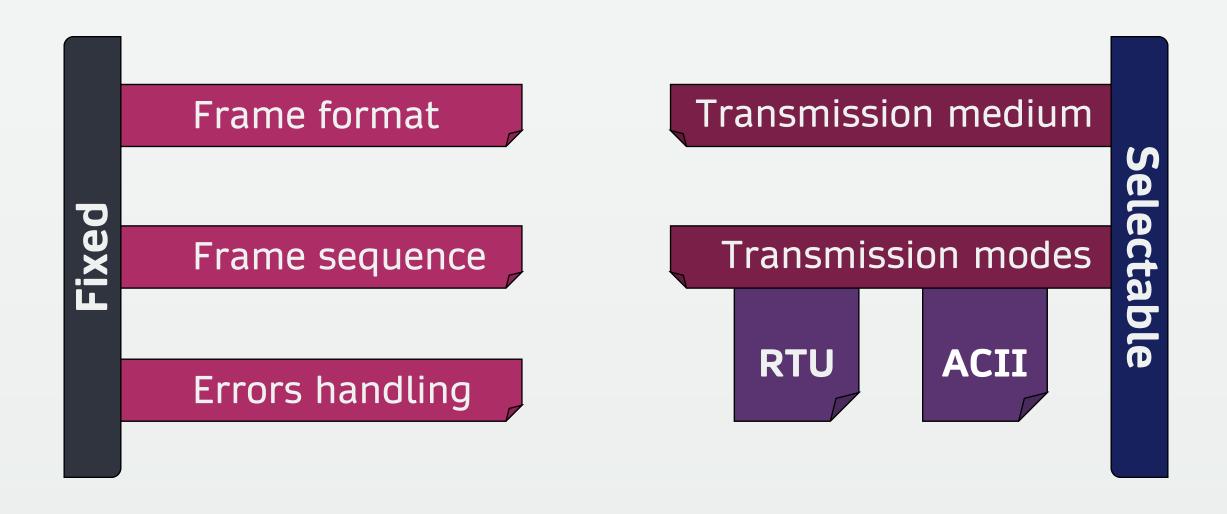
Extension : over Ethernet

Characteristics

Fixed

Selectable

Characteristics



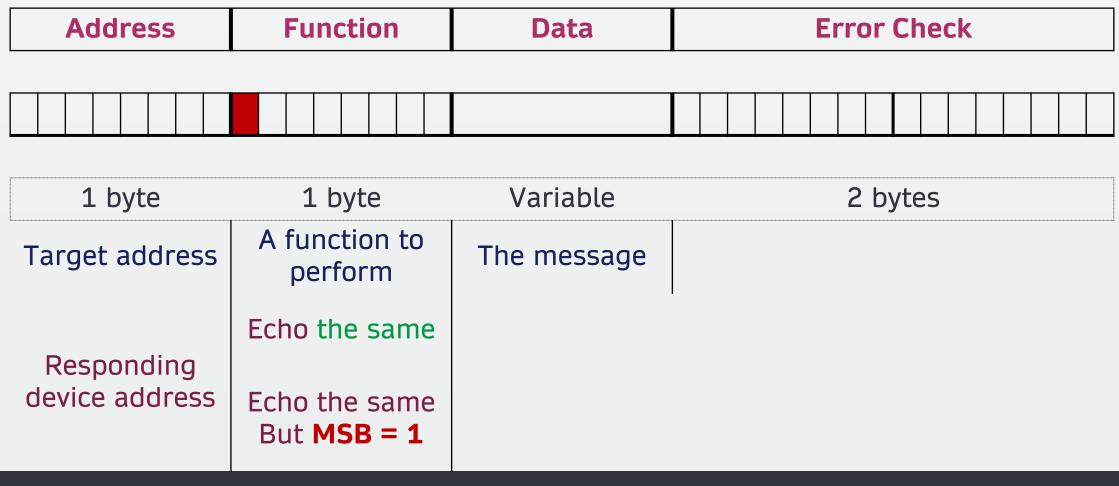
Structure

Frame format

Address	Function	Data	Error Check
1 byte	1 byte	Variable	2 bytes
Target address	A function to perform	The message	
Responding device address	Echo the same		
	Echo the same But MSB = 1		

Structure

Frame format





HART

Challenge

The Knowhow of data transfer for two different types:

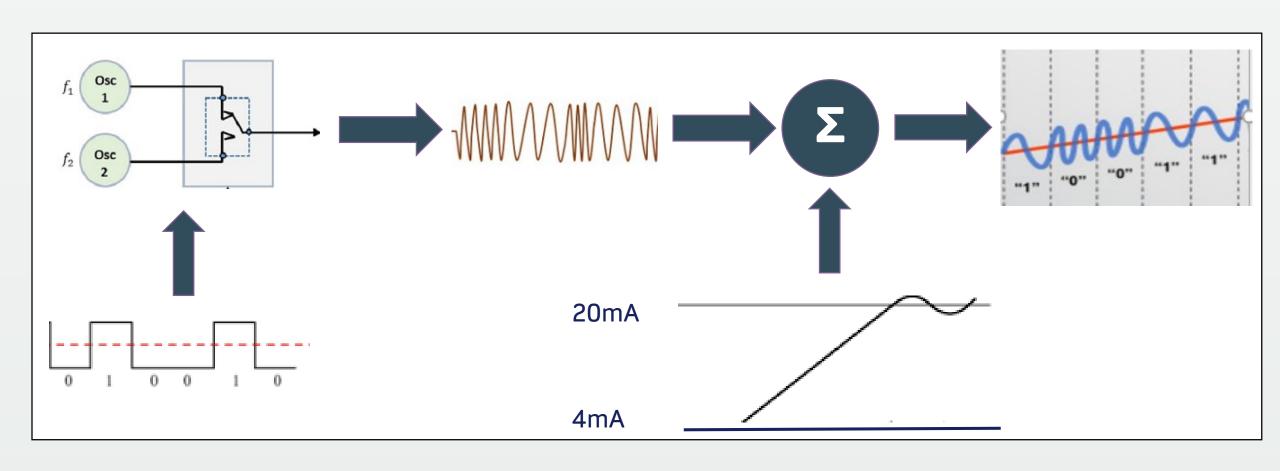
Analog Signal Digital Signal

With no interference

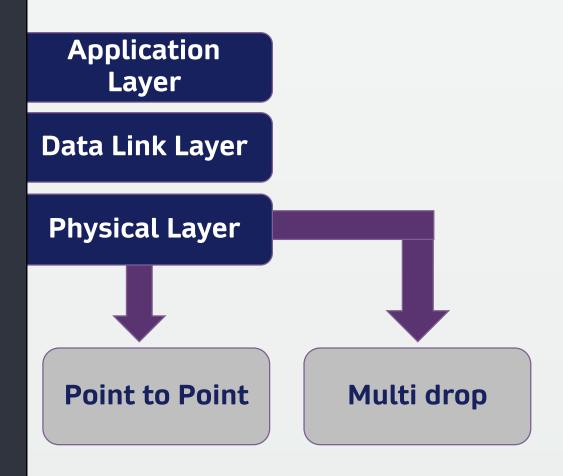
HART: Highway Addressable Remote Transducer

Frequency Shift Keying

In 1990s, FSK (Frequency Shift Modulation) technique has been certified



HART Network



HART Network

Hardware Implementation

- Power Supply
- Field Device

Smart sensor with an output current signal in range of 4-20mA

Host

Primary controller can be sufficient, such as PLC or DCS, and a handheld can be a secondary controller

HART Network

The FSK technique must be used for digital data sharing such as the ID related to each field device



Cat 5 shielded, twisted pair wire is recommended

Communication Modes

Polling / Master-Slave Mode



Master



Slave

Burst / Broadcast Mode

Burst Mode

Communication Mode

Smart devices

Host

- No message request needed
- High data transfer rate (3-4 data per second)
- Can be integrated with point to point network

Preamble

Delimiter

Address

Command

Byte Count

Command Response
Code

Field Device Status

Checksum

Preamble

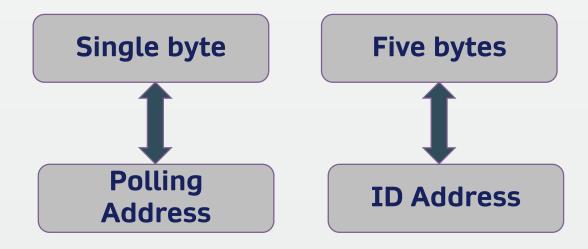
- First field in sent message
- Wake up and synchronize all connected receivers in the network

Delimiter

- Single byte field
- Indication to the end of preamble field
- Considered to be the Start field
- Classifies the message type to a
 - Request from Mestense of Slave

Address

Specifies the destination address and its type



Command

- Single byte field
- Represents which command to be executed, but without any data analysis

Byte Count

- Single byte field
- Counts the rest bytes for the message to be completely received
- Receiver can check the end of the message through the data gathered from this device

Command Response Code

- Single byte field
- Error type detection in the received message is available "Response Messages"
- Corrective messages are included as a result of each detected error type

Field Device Status

- Single byte field
- Included in the response messages as an indication to the health level of the field device

Checksum

- Single byte field
- Correctly received data causes the transmitting end check value to be identical to the receiving end check value

Universal commands

Common Practice Command

Device Specific Command







Universal commands

Provide functions that must be implemented in all field devices such as:

- Reads manufacturer and device type
- Reads primary variable and its unit
- Reads current output and its percentage in range
- Reads device range

Common Practice Command

Provides functions that are common to many but not to all field devices:

- Writes damping time constant
- Calibrates (set 0 reference and set span)
- Sets fixed output current
- Sets DAC** zero and gain

** Digital to Analog Converter

Device Specific Command

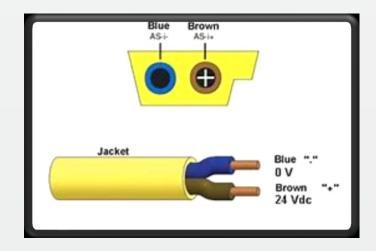
Provides functions that are unique to a particular field device (Specified by the device manufacturer):

- Reads or Writes low flow cut-off value (Flow apps)
- Reads or Writes density calibration value
- Chooses mass flow (density or flow)

AS-Interface

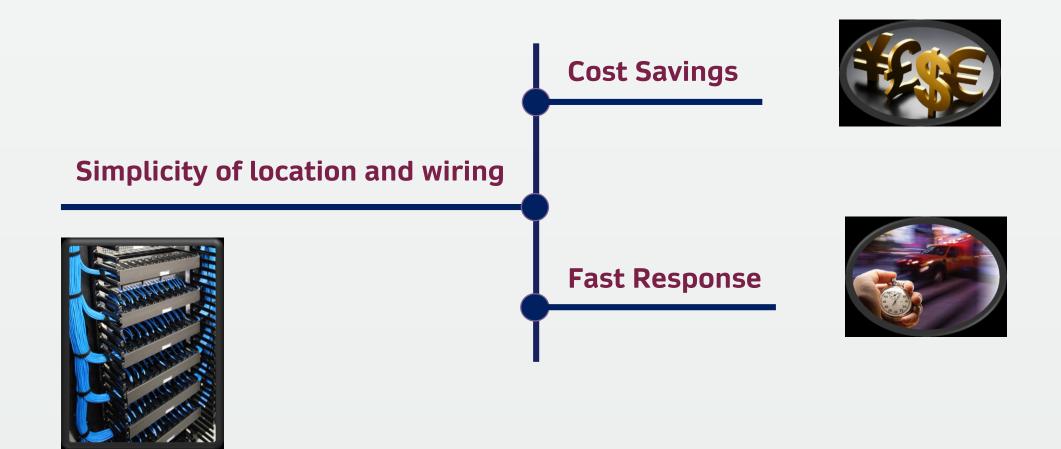
Specifications

- Master-Slave mode
- 62 slave devices can be connected
- Simultaneously, different data type can be transmitted and received
- Can be installed up to 100-600 m with repeaters



AS-I: Actuator-Sensor Interface

2 Wire untwisted, unshielded cable (16AWG, 1.5mm) can be used



Power and data can be merged in the same cable, then:

- Less cables need to be wired out in the field
- No need for external power supply

Cost Savings



Simplicity of location and wiring



Devices can be connected, with a higher flexibility, in multiple wiring systems such as:

- Star connection
- Line arrangement
- Line with layer switches
- Tree configuration

Response time of slave device is shorter than the single data acquisition cycle of PLC, then it is used in

critical timing applications such as: Packaging systems

- Bottling line
- Elevators
- Safety systems

Fast Response



Device-Net

Network and Transport Layers

Data Link Layer

Physical Layer

Network and Transport Layers

Duplicate the data gathering capability, to get a successful network, then required data are:

- MAC ID
- Message (signal to user)

Data Link Layer

 Use CAN protocol (CSMA/CD) to reduce data collisions and increase successful rate of data transmission

Physical Layer

Main hardware components:

- Cables
- Nodes
- Taps
- Termination resistors
- Trunk line Drop line topology

Software interface:

- RS Networx license
- EDS (Electronic Data Sheet)

Physical-Hardware

Data Rate	Thick round	Thin round	Kwik Link flat	Kwik Link lite flat
125 kbps	500 m	100 m	240 m	350 m
250 kbps	250 m	100 m	200 m	150 m
500 kbps	100 m	100 m	75 m	55 m

Physical-Software

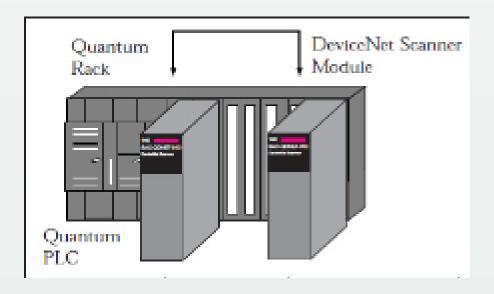
RS Networx license

Map and assign addresses of all devices to the device-net scanner, in the form of:

- Graphical interface
- Spreadsheet layout

EDS (Electronic Data Sheet)

A text file containing all information about devices

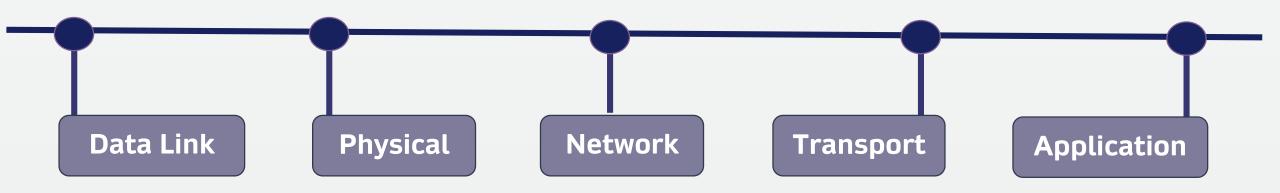


Device-net scanner connected with PLC

Pros and Cons

Pros	Cons	
Cost effective	Limited message size	
Wide spread acceptance	Limited maximum cable length (6m)	
High reliability		
Available power on network		

TCP/IP



TCP/IP: Transmision Control Protocol/Internet Protocol

1

Application Layer

User interface such as web browsers





2

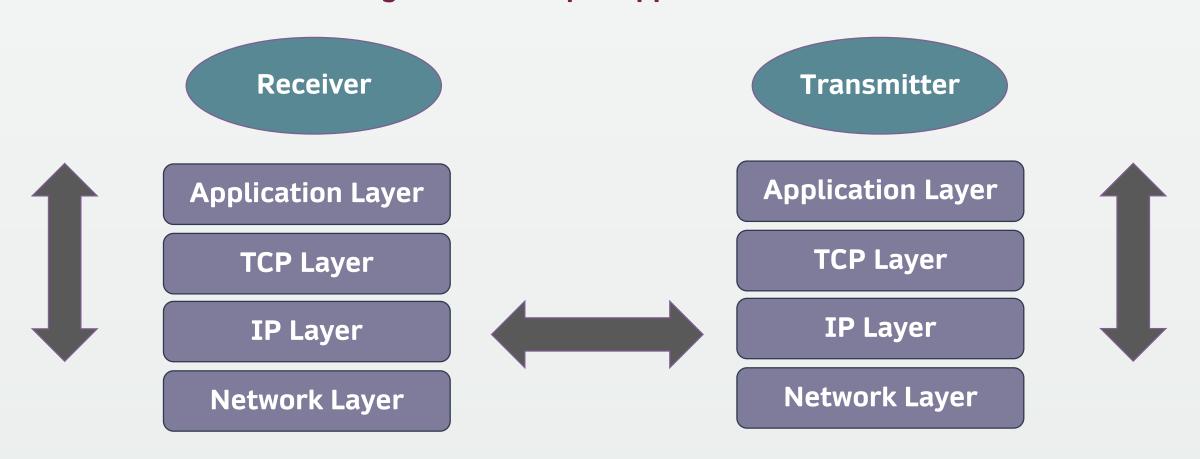
Transport Layer

Responsible for chopping data into packets, each packet is labeled with a header for data reception guarantee



TCP Protocol

Send-Receive acknowledge relationship is applicable



3

Network Layer



Physical Layer

IP addresses of the sender and receiver must be shared for accurate data handling

Finally data is transmitted to the controller, via the ethernet packages

Category	Data transfer rate
Cat 6	1 Gbps
Cat 6a & Cat 7	10 Gbps
Cat 5 & Cat 5e	10-100 Mbps
Rj-45	Full-duplex



Summary

Summary

We have introduced a basic knowledge in a large scale of industrial network fields, representing:

OSI Model

Serial Link Standards

RS-232

RS-485

Current Loop Modbus

HART

AS-I

TCP / IP

Device-Net

References

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- 2.Practical Industrial Data Networks: Design, Installation and Troubleshooting, by: Steve Mackay
- 3. Publication of International CAN Conference, sponsored by: Motorola Semiconductor, National Semiconductor, Philips Semiconductors
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- 6.TCP/IP Tutorial and Technical Overview, supported by IBM
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Thanks