



# Chapter 8

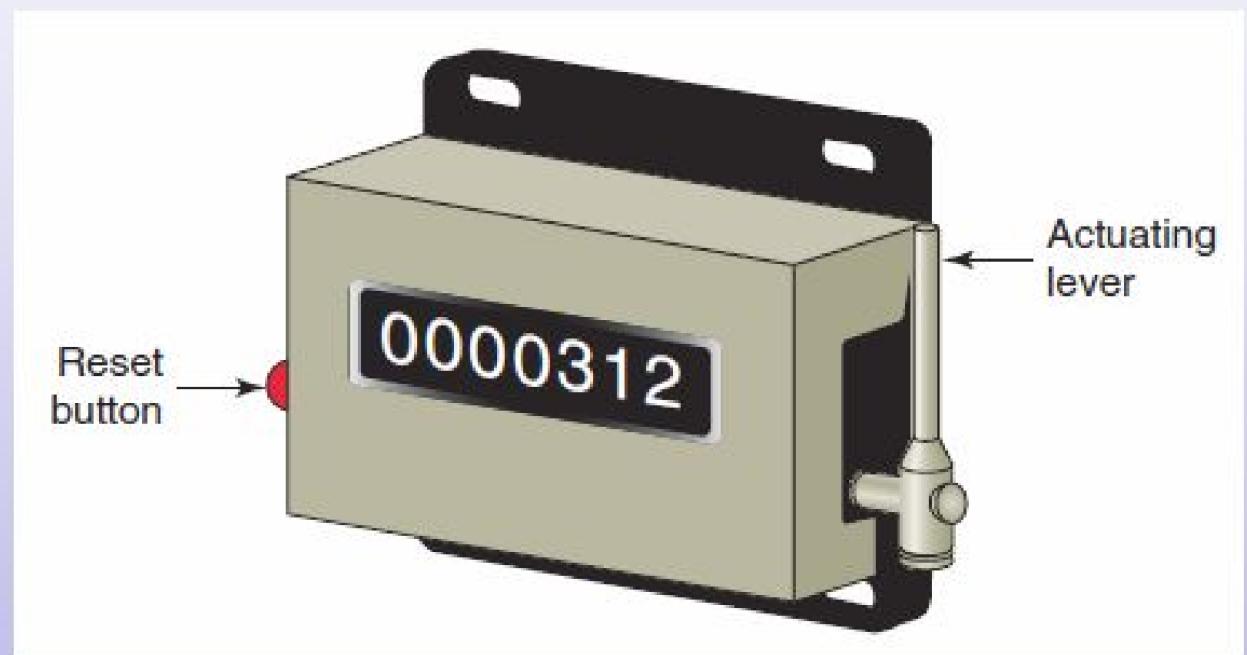
## Programming Counters

## 8.1



# Counter Instructions

*Programmed counters*  
serve the same  
function as  
*mechanical counters*.



Every time the actuating lever is moved over, the counter **adds one number**.

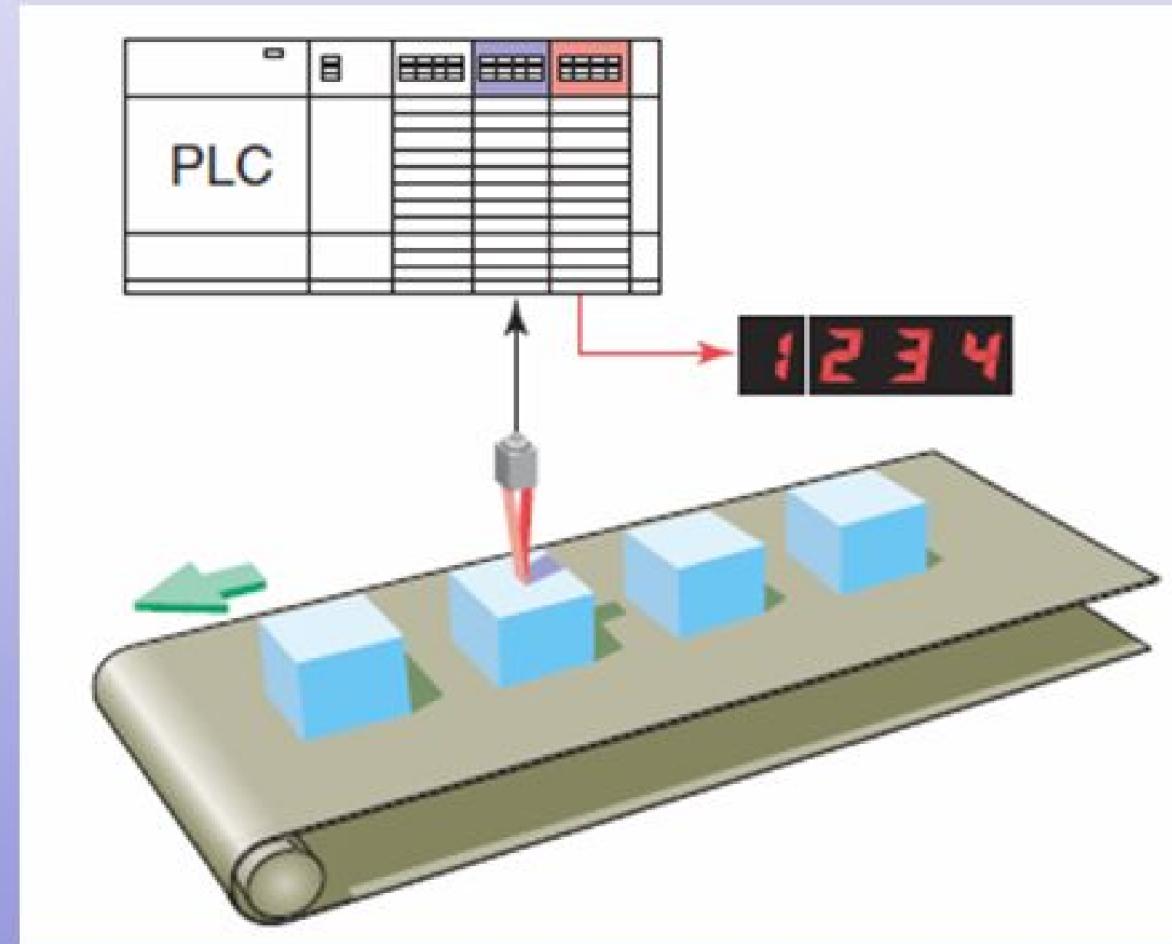
**Resetting to zero** is done with a pushbutton located on the side of the unit.

*Electronic counters*  
can count up, count  
down, or be  
combined to count  
up and down.



Although the majority of counters used in industry are **up-counters**, numerous applications require the implementation of **down-counters** or of combination **up/down-counters**.

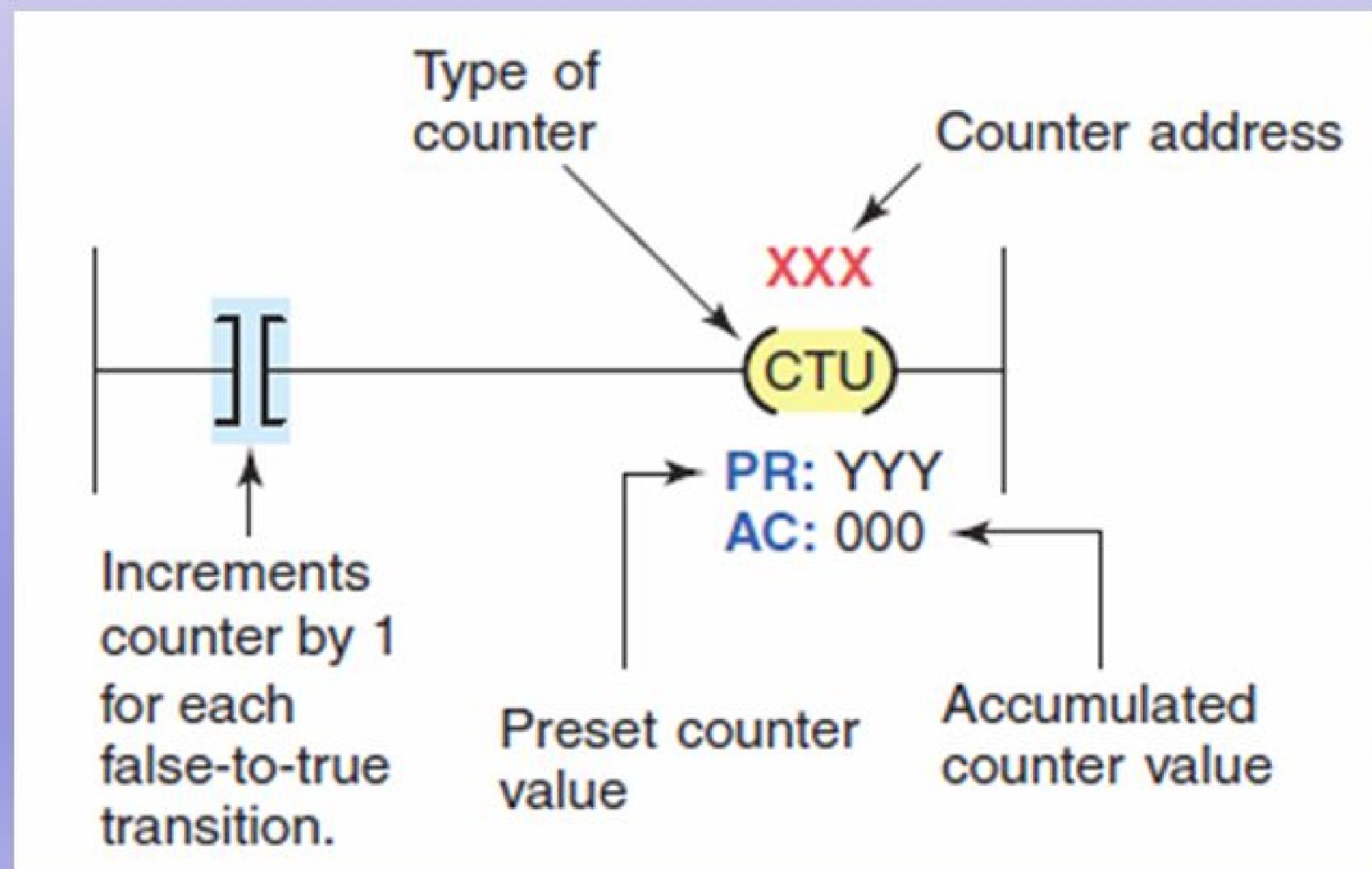
# All PLC manufacturers offer some form of counter instruction.



One common counter application is **keeping track** of the number of items moving past a given point.

PLC counter instructions are *similar to timers* except that they do not operate on an internal clock but are dependent on *external or program sources* for counting

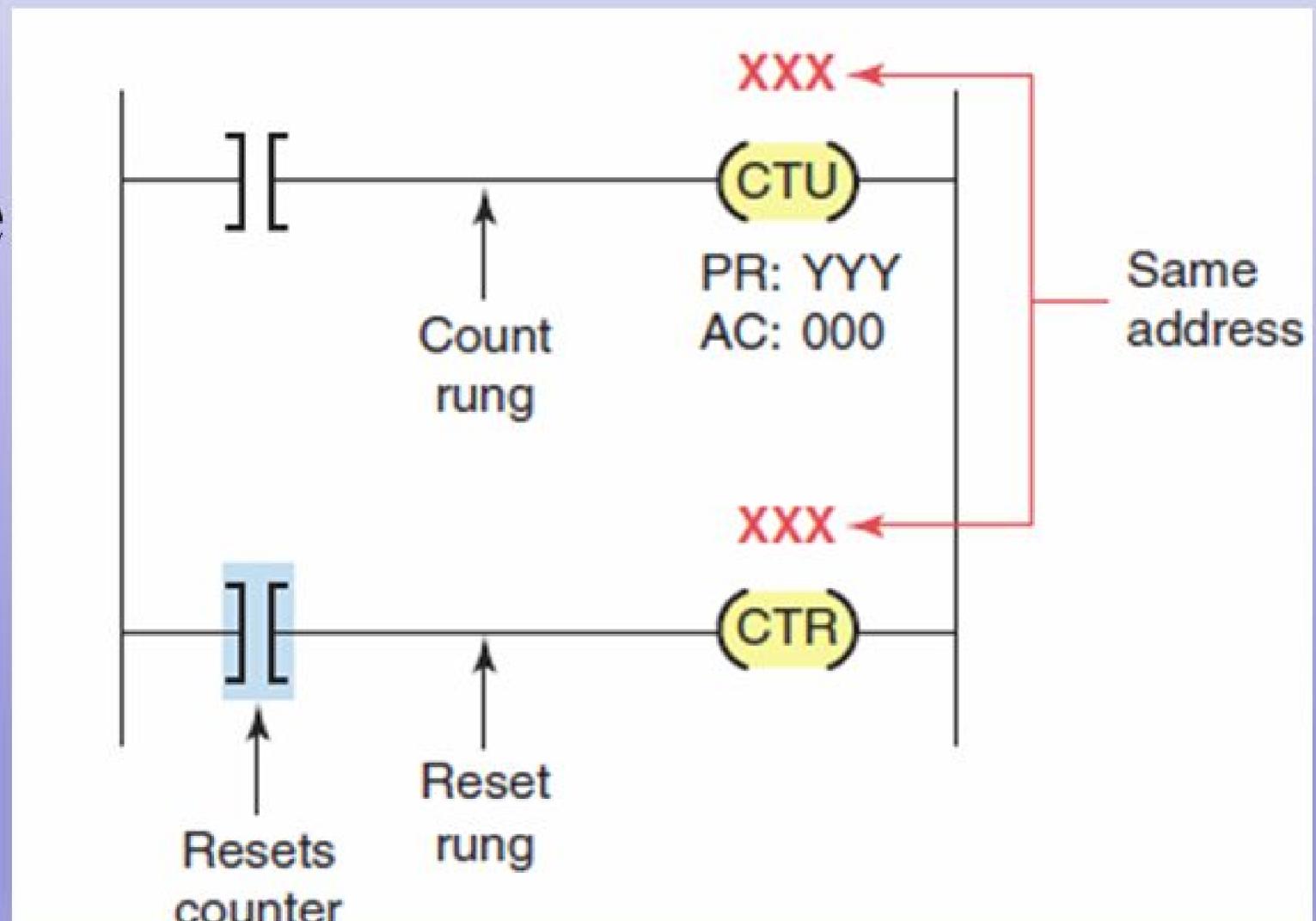
Generic **coil-formatted** up-counter instruction.



The *counter reset instruction* must be used in conjunction with the counter instruction.

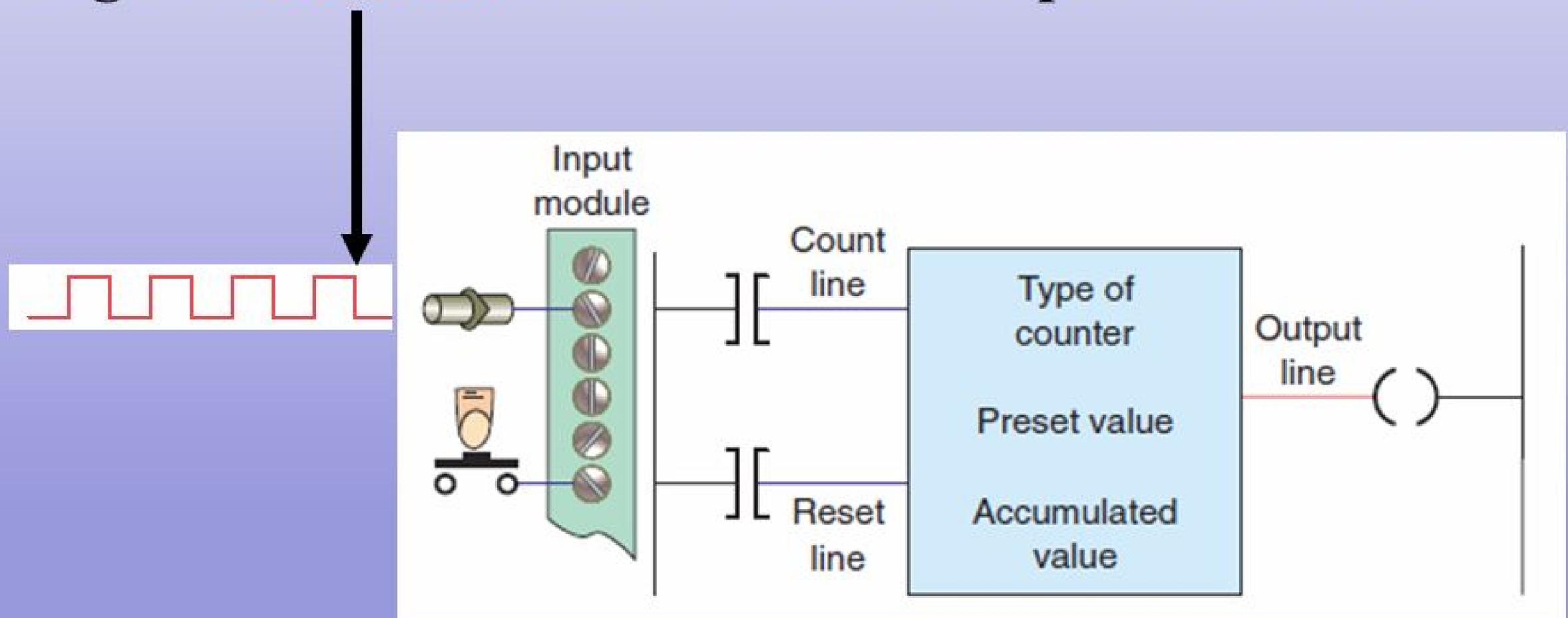
The **counter reset coil** is given the **same address** as the counter that it is to reset.

**Up-counters** are always reset to **zero**.

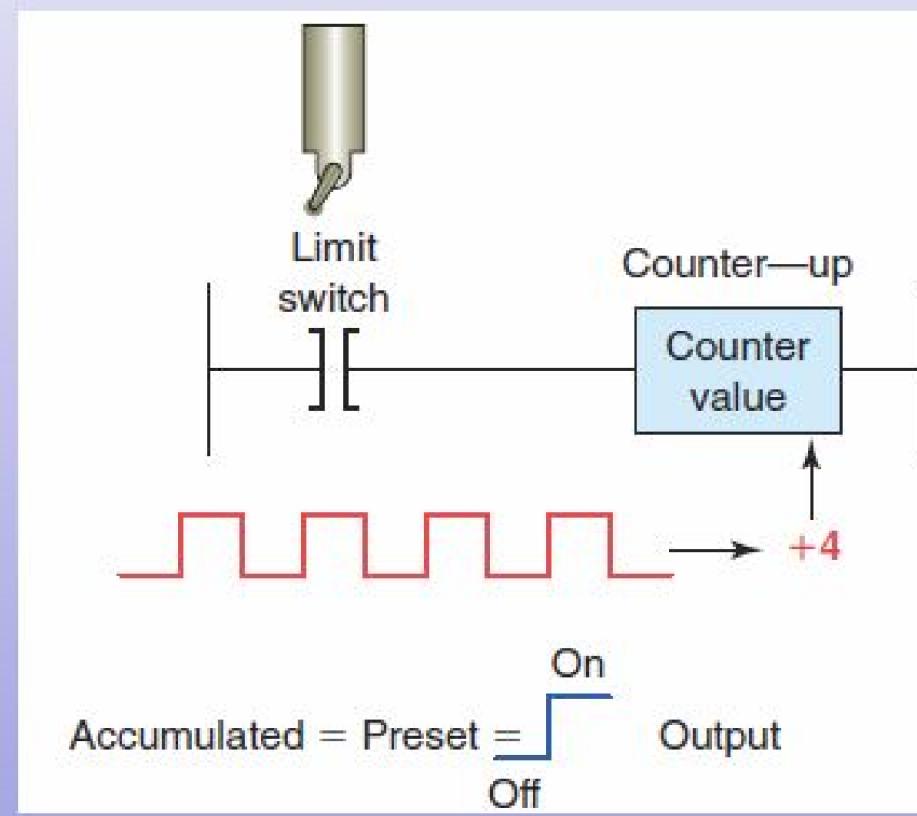


# Generic *block-formatted* counter.

All PLC counters operate, or count, on the leading edge or **off-to-on** transition of the input condition.

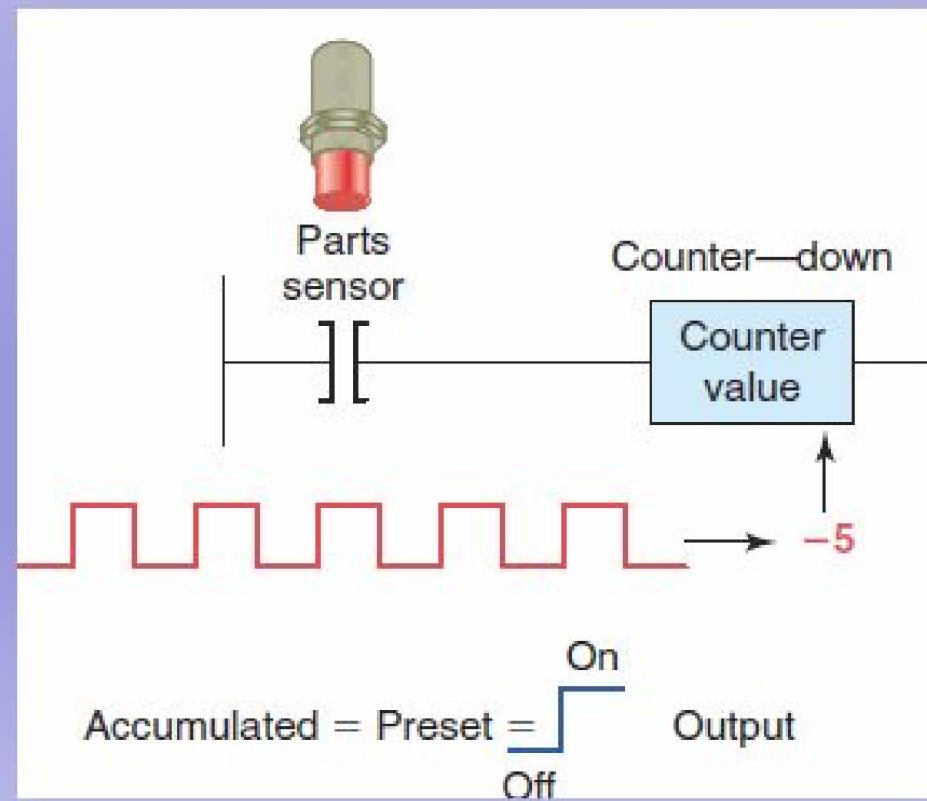


PLC counters can be programmed to *count up* to a preset value or to *count down* to a preset value.



The **up-counter** is **incremented** by 1 each time the rung containing the counter is energized.

The **down-counter** **decrements** by 1 each time the rung containing the counter is energized.

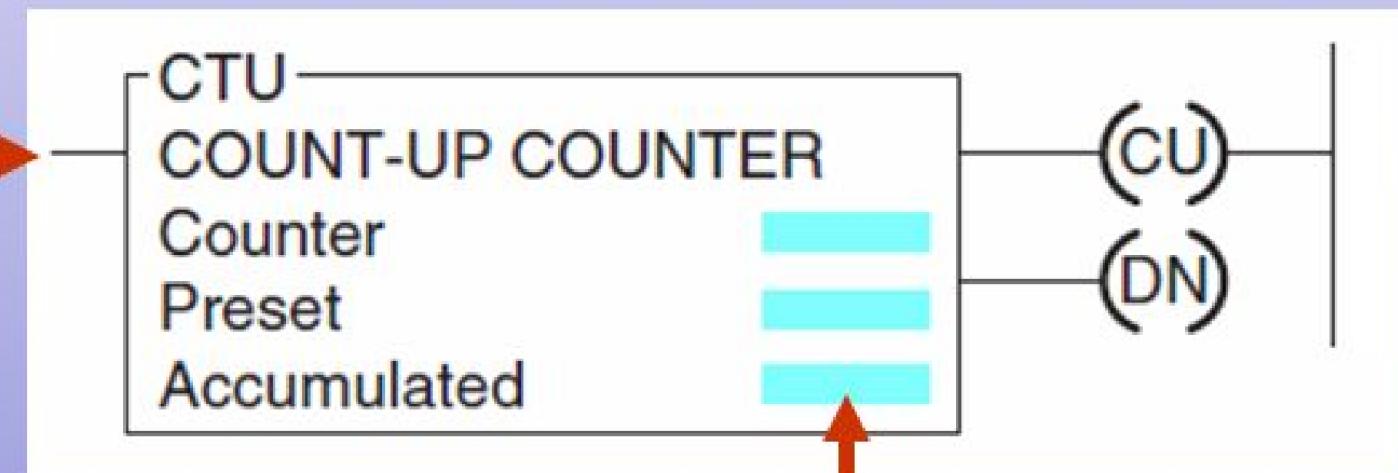


# 8.2



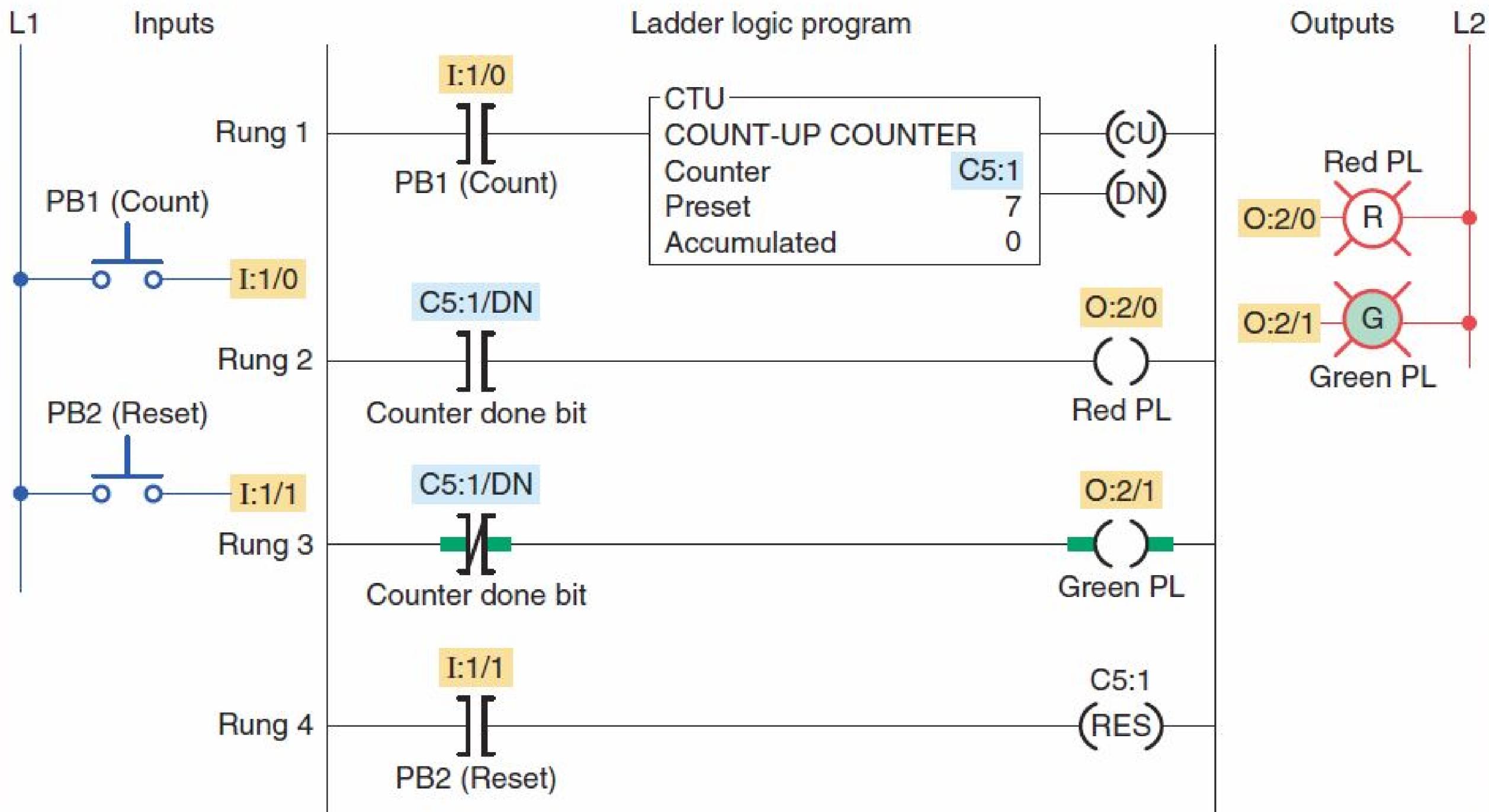
# Up-Counter

The *up-counter* is used to *count false-to-true* transitions of an input instruction and then *trigger an event* after a required number of counts or transitions.

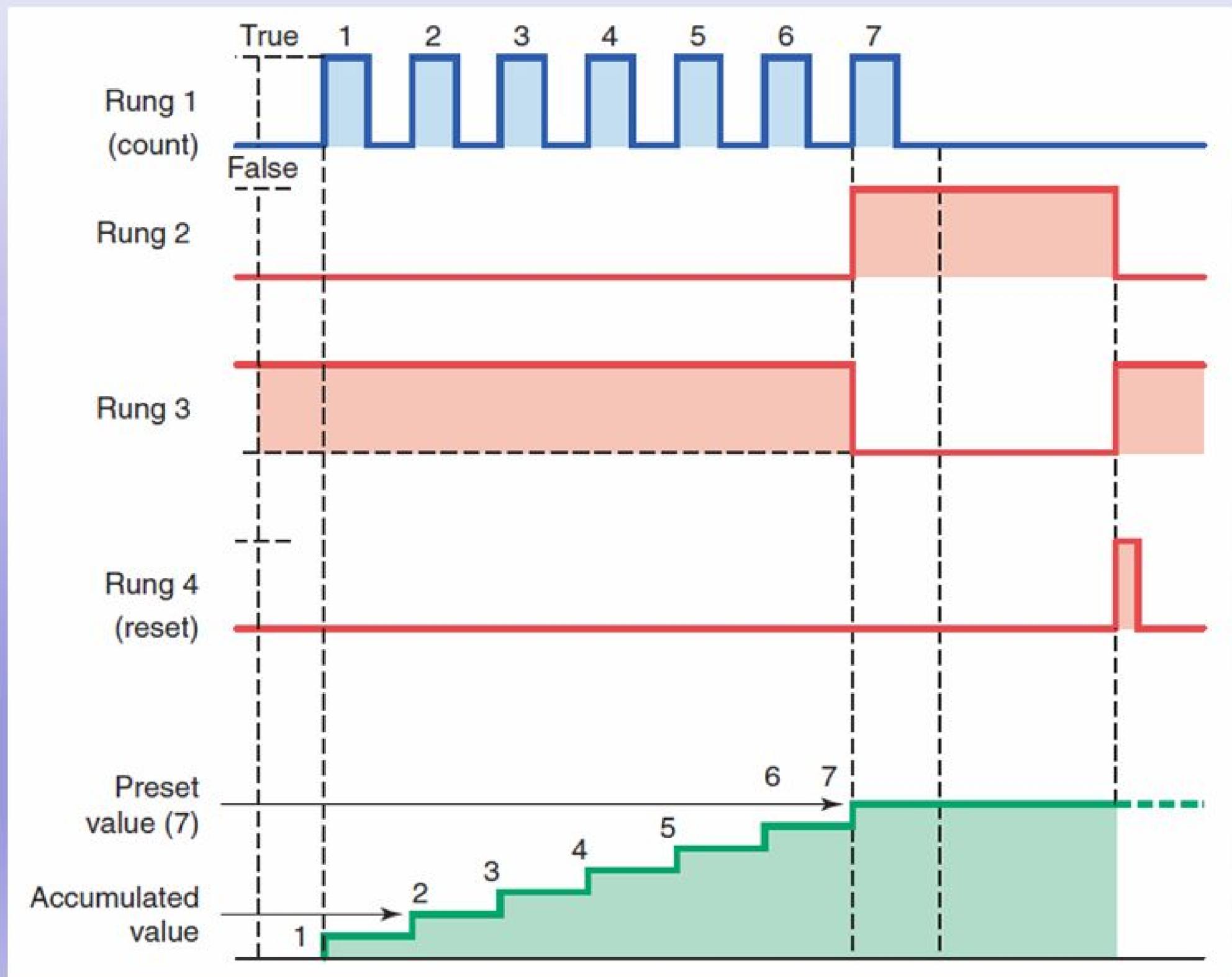


The up-counter output instruction will **increment** its accumulated **value** by 1 each time the counted event occurs.

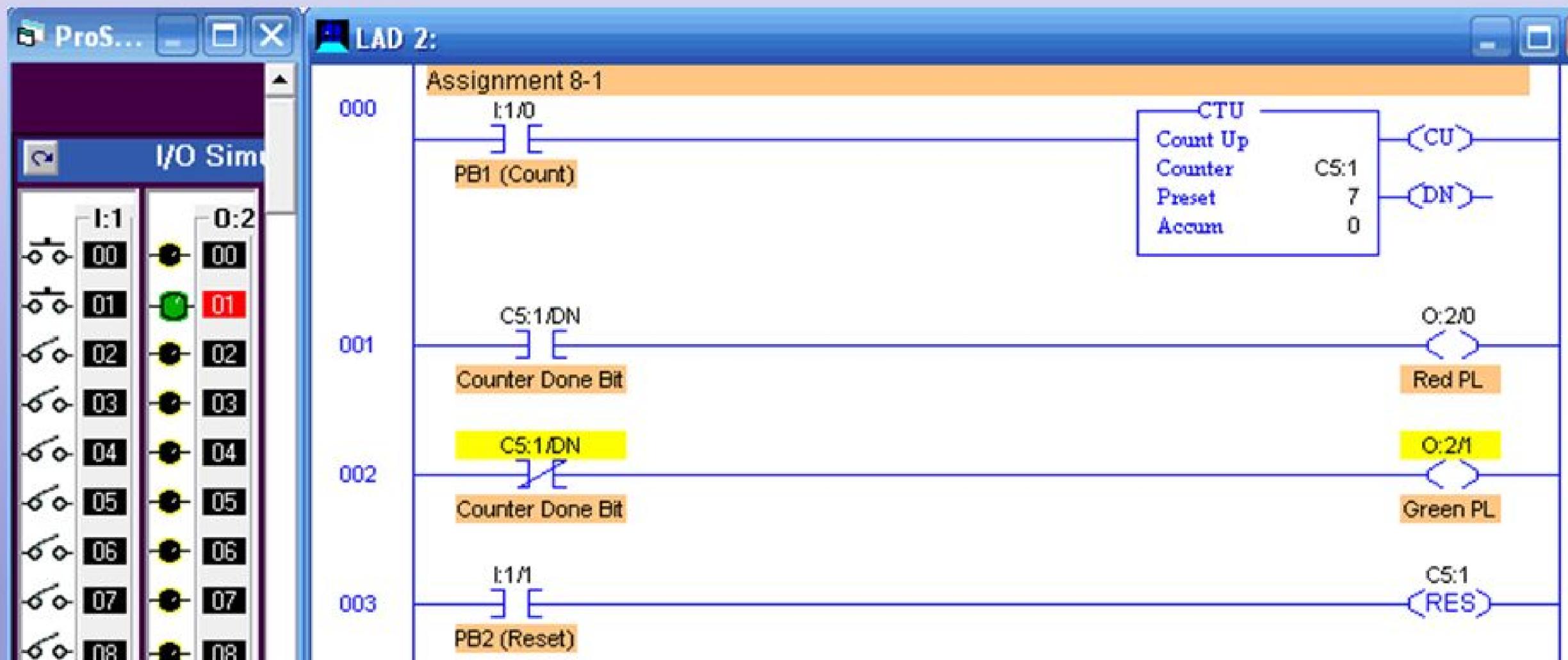
# SLC 500 Up-Counter program



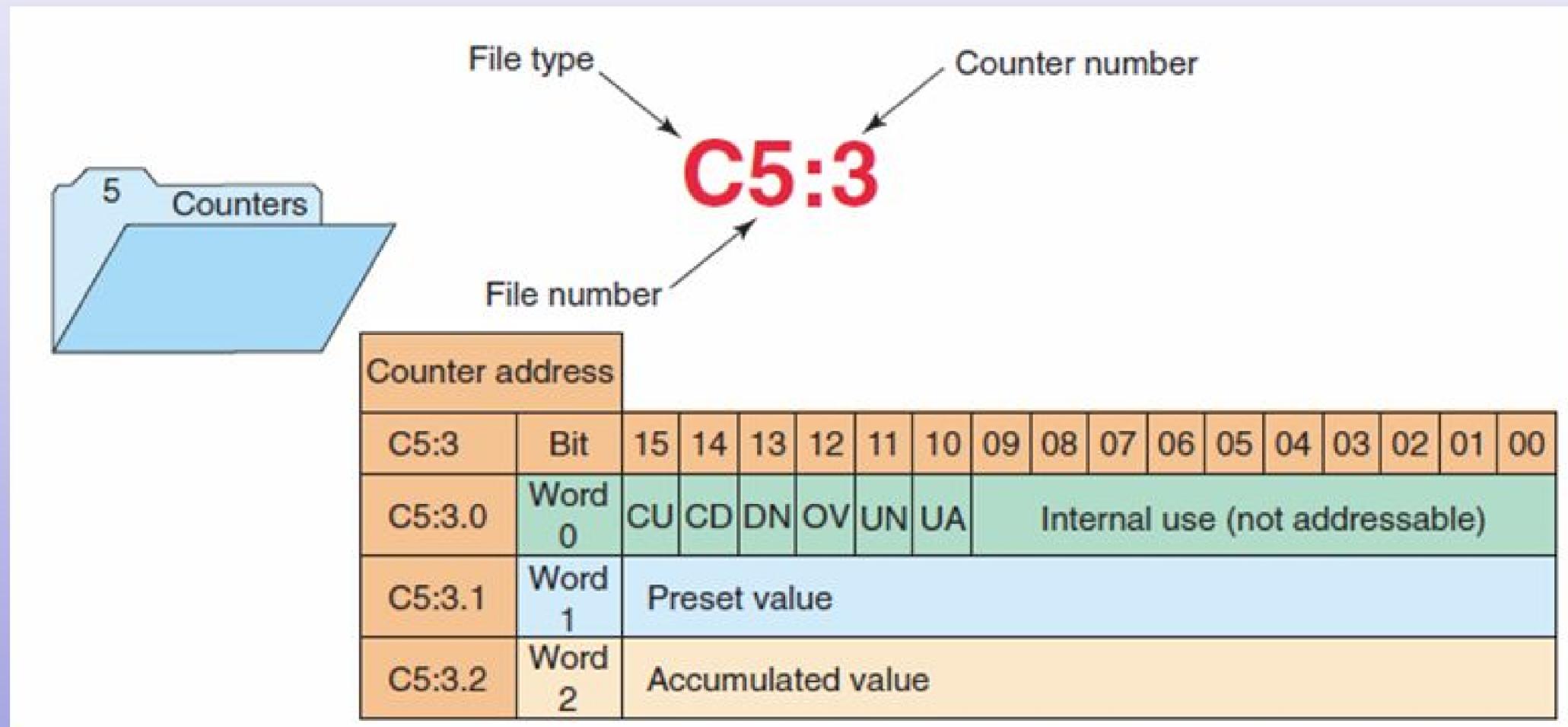
# SLC 500 Up-Counter *timing diagram*



# Simulated Up-Counter program



# The Allen-Bradley SLC 500 counter file is *file 5*.



**Counter Table**

	/CU	/CD	/DN	/OV	/UN	/UA	.PRE	.ACC
C5:0	0	0	0	0	0	0	0	0
C5:1	0	0	0	0	0	0	0	0
C5:2	0	0	0	0	0	0	0	0
<b>C5:3</b>	0	0	0	0	0	0	50	0
C5:4	0	0	0	0	0	0	0	0
C5:5	0	0	0	0	0	0	0	0

Address:  Table:  ▾



**Overflow (OV) bit is - true (1) whenever the counter counts past its maximum value, 32,767.**

**On the next count, the counter will wrap around to -32,768 and will continue counting to 0.**

**Underflow (UN) bit is - true when the counter counts below -32,768. The counter will wrap around to +32,767 and continue counting down toward 0.**

	/CU	/CD	/DN	/OV	/UN	.PRE	.ACC
C5:0	0	0	0	0	0	0	0
C5:1	0	0	0	0	0	0	0
C5:2	0	0	0	0	0	0	0
<b>C5:3</b>	0	0	0	0	0	0	0
C5:4	0	0	0	0	0	0	0
C5:5	0	0	0	0	0	0	0

**Update  
Accumulator  
(UA) bit-** is used  
in conjunction  
with an external  
high-speed  
counter.

**The preset value  
(PRE) word -**  
specifies the value  
that the counter  
must count to  
before it changes  
the state of the  
done bit.

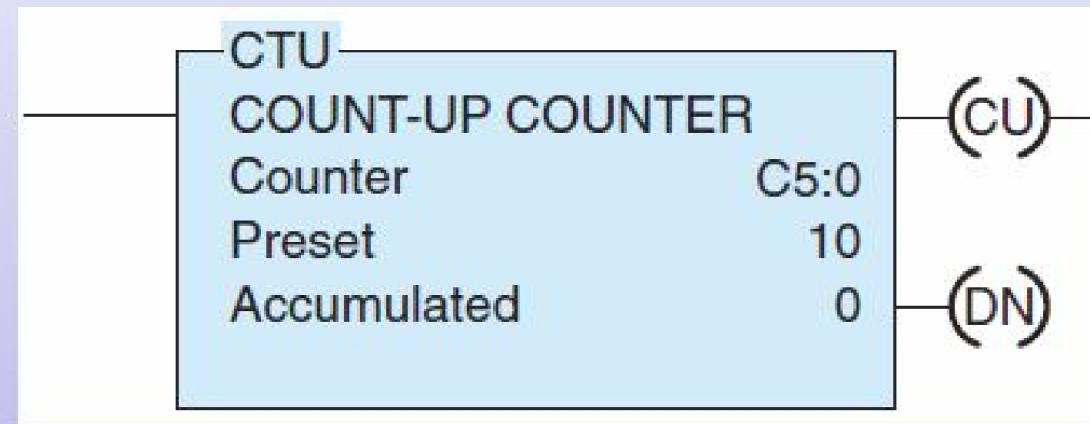
**The  
accumulated  
value (ACC)  
word -** is the  
current count  
based on the  
number of  
times the rung  
goes from false  
to true.

**Counter Table**

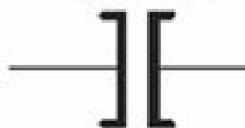
	/CU	/CD	/DN	/OV	/UN	/UA	.PRE	.ACC
C5:0	0	0	0	0	0	0	0	0
C5:1	0	0	0	0	0	0	0	0
C5:2	0	0	0	0	0	0	0	0
<b>C5:3</b>	0	0	0	0	0	0	50	0
C5:4	0	0	0	0	0	0	0	0
C5:5	0	0	0	0	0	0	0	0

Address: C5:3      Table: C5: Counter

# SLC 500 up-counter instruction.



C5:0/CU



Counter enable bit

C5:0/DN



Counter done bit

C5:0/OV

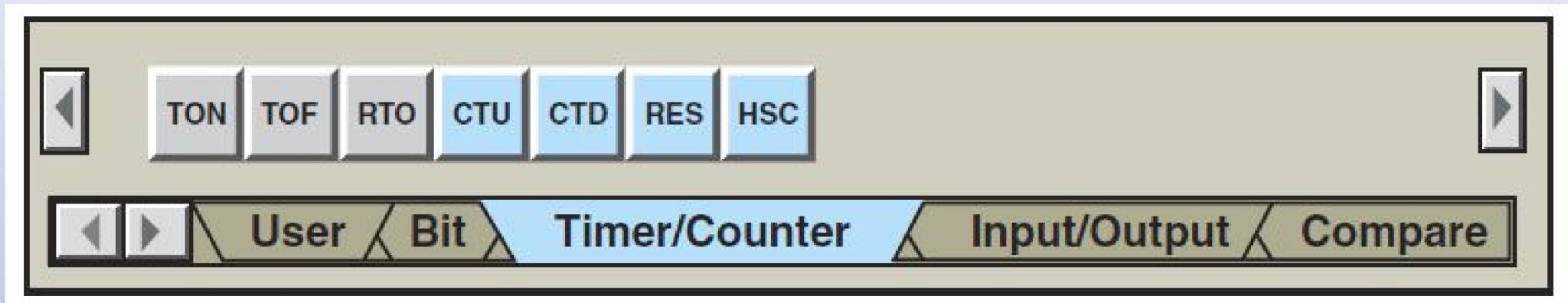


Overflow status bit

C5:0  
(RES)

The reset instruction resets the counter's accumulated value back to zero.

# Timer/counter menu from the RSLogix toolbar.

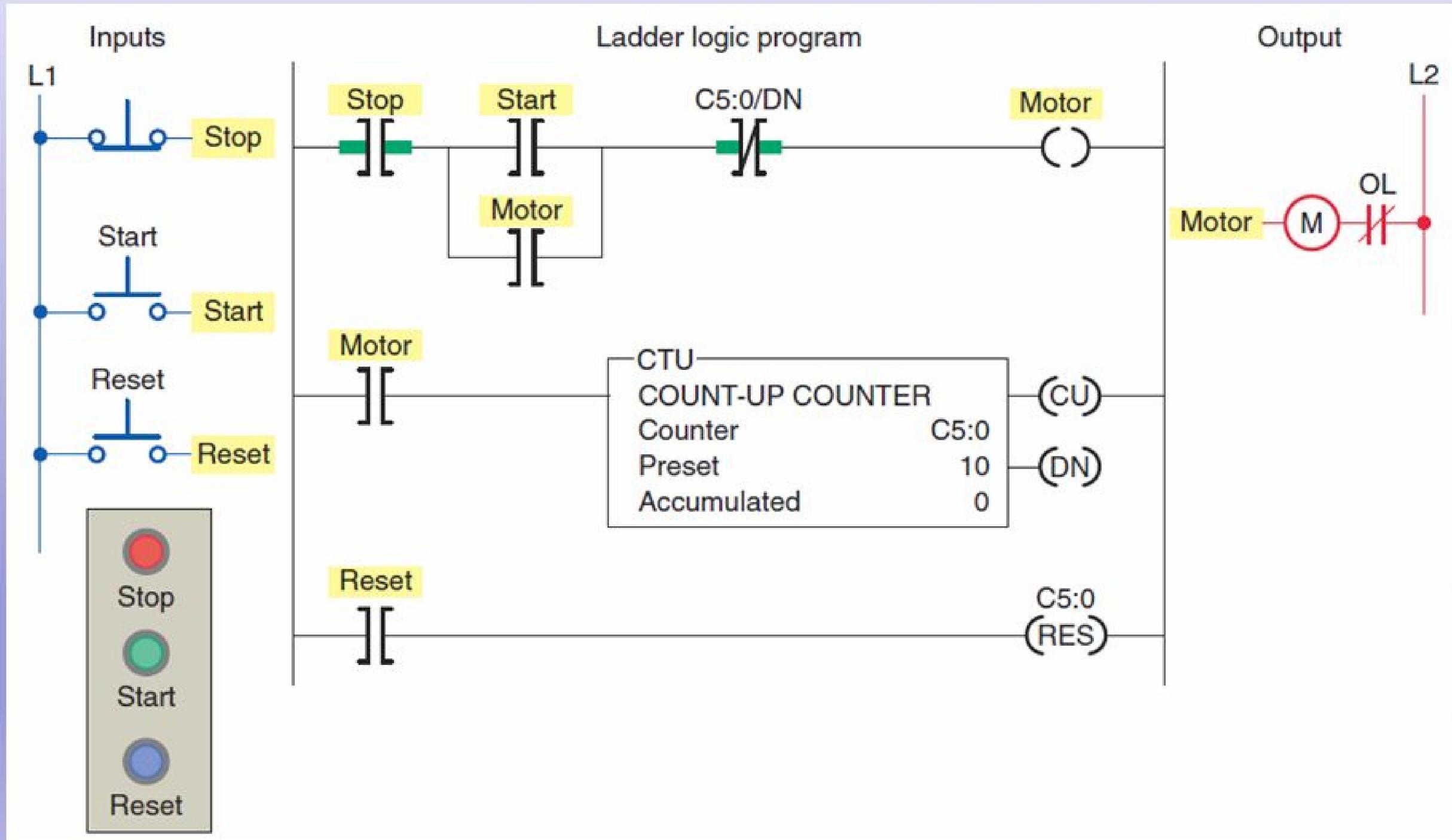


**CTU (Count-Up)** Increments the accumulated value at each false-to-true transition and retains the accumulated value when an off/on power cycle occurs.

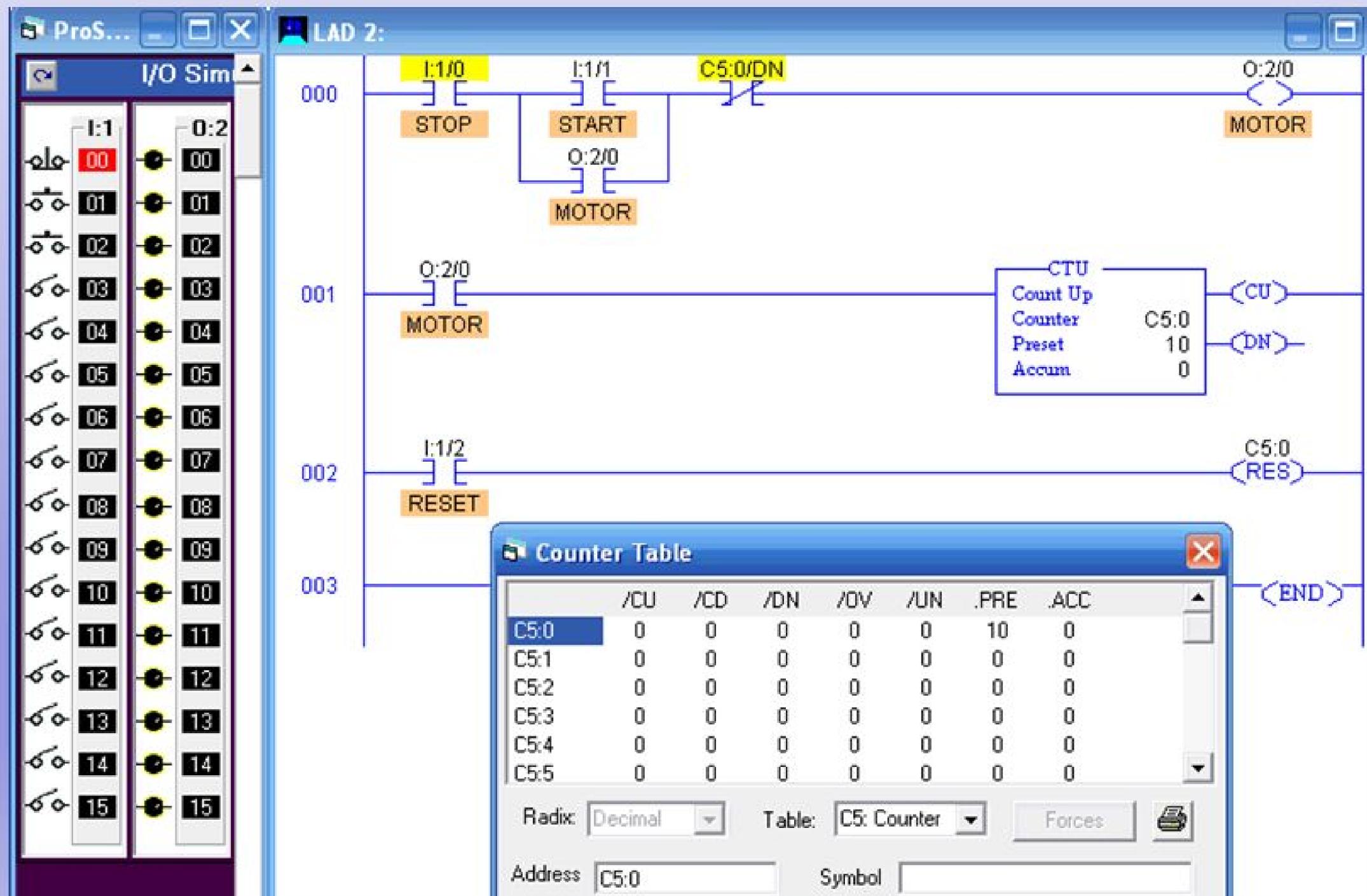
**CTD (Count-Down)** Decrements the accumulated value at each false-to-true transition and retains the accumulated value when an on/off power cycle occurs.

**HSC (High-Speed Counter)** Counts high-speed pulses from a high-speed input.

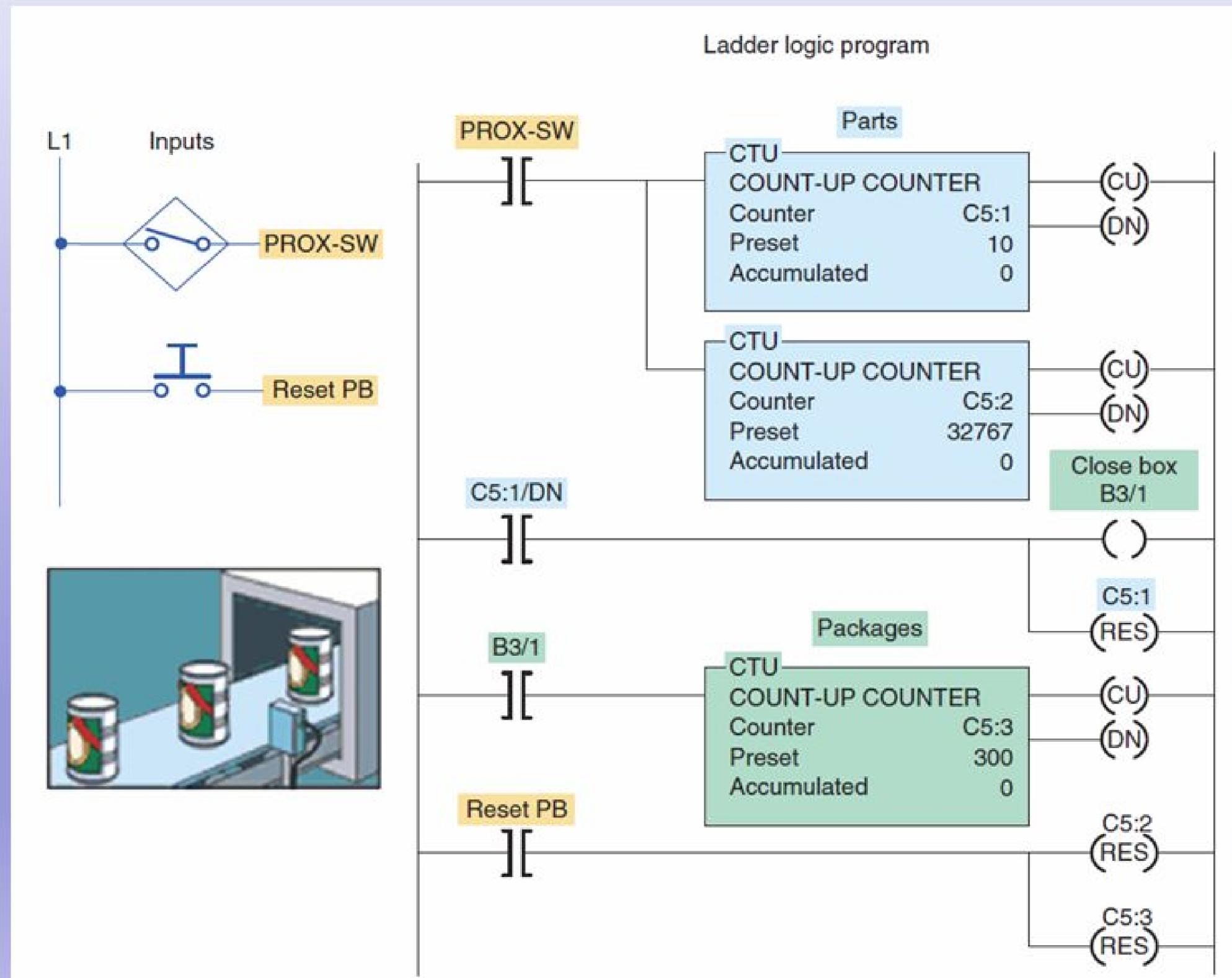
# PLC counter program used to stop a motor from running after 10 operations.



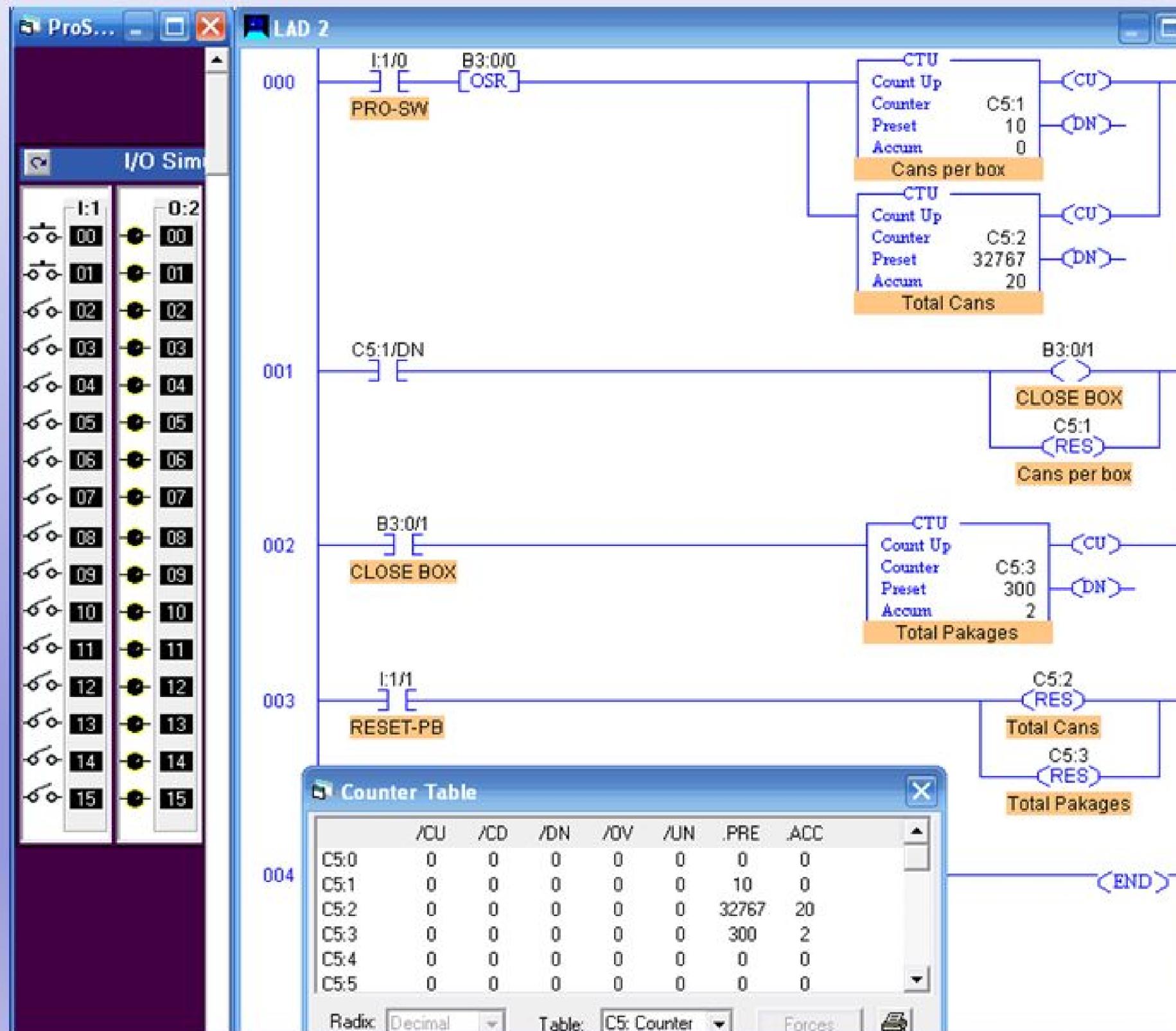
# Simulated counter program used to stop a motor from running after 10 operations.



# Can-counting program that uses three up-counters.

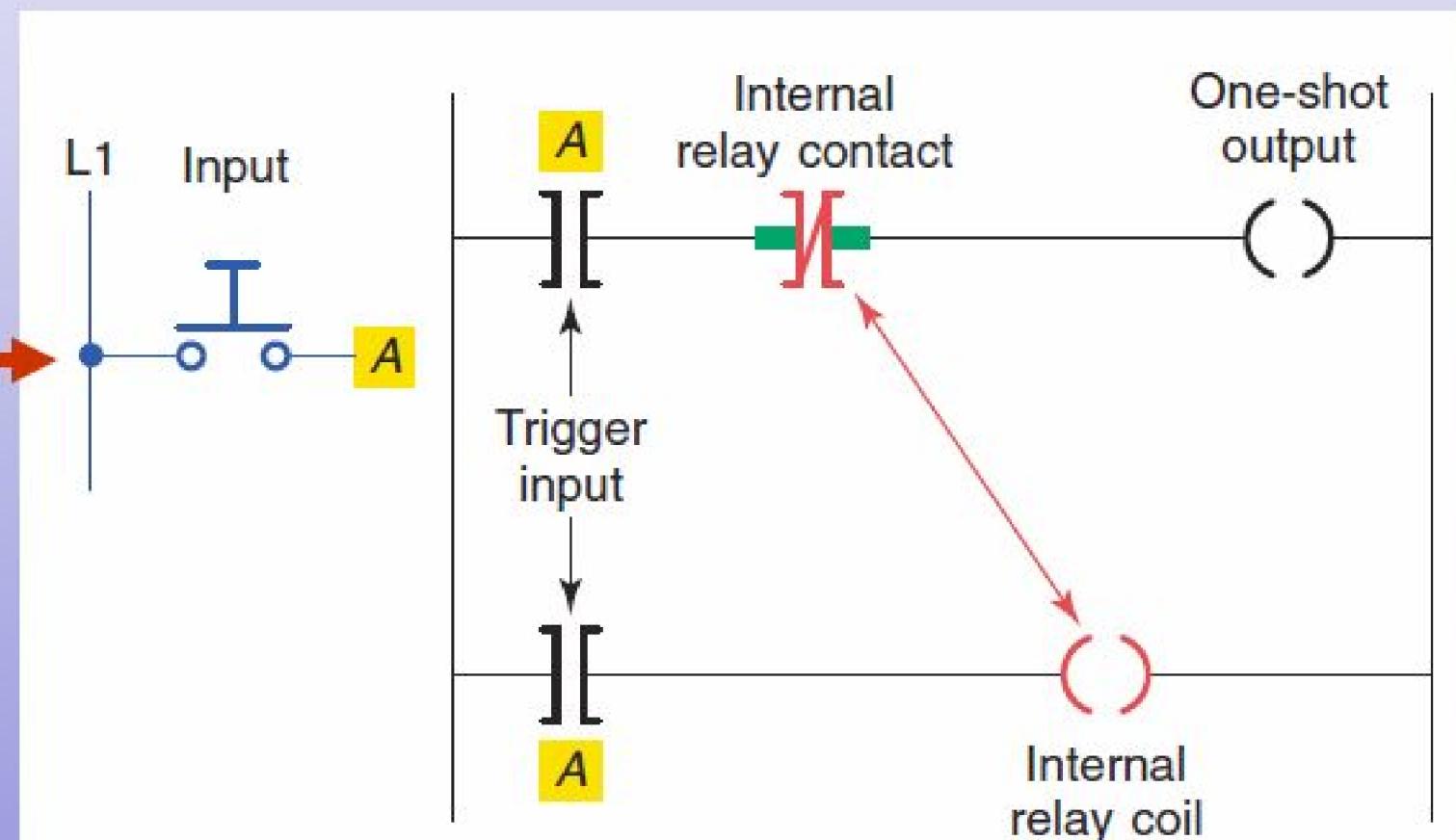


# Simulated can-counting program.



**A *one-shot*, or *transitional*, contact is often used to automatically clear or reset a counter.**

The **one-shot** can be triggered from a **momentary** signal or from a signal that **comes on and stays on** for some time.

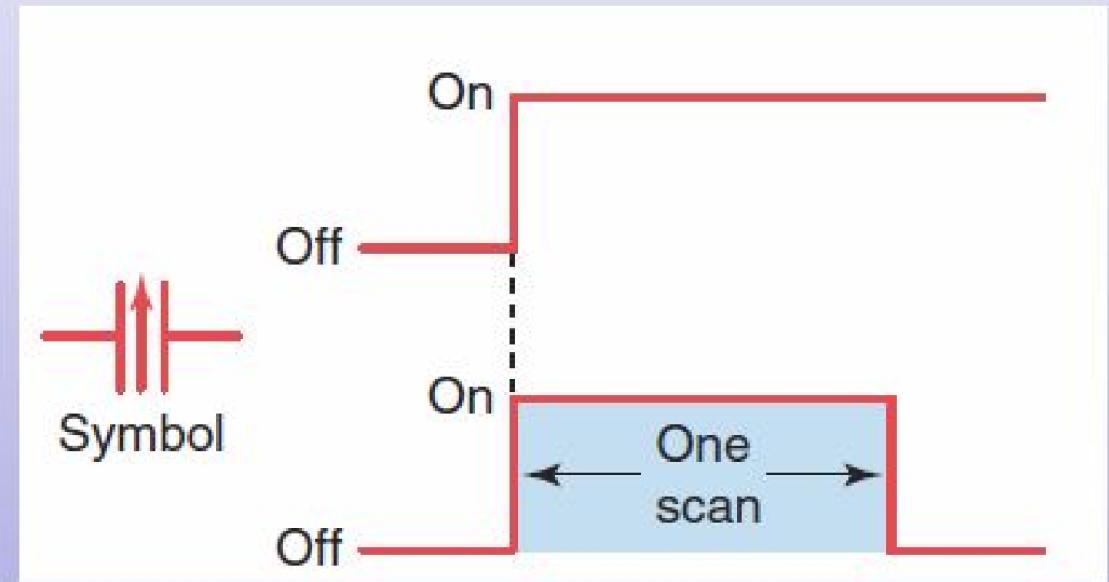


It stays on for **one scan only** and then goes off.

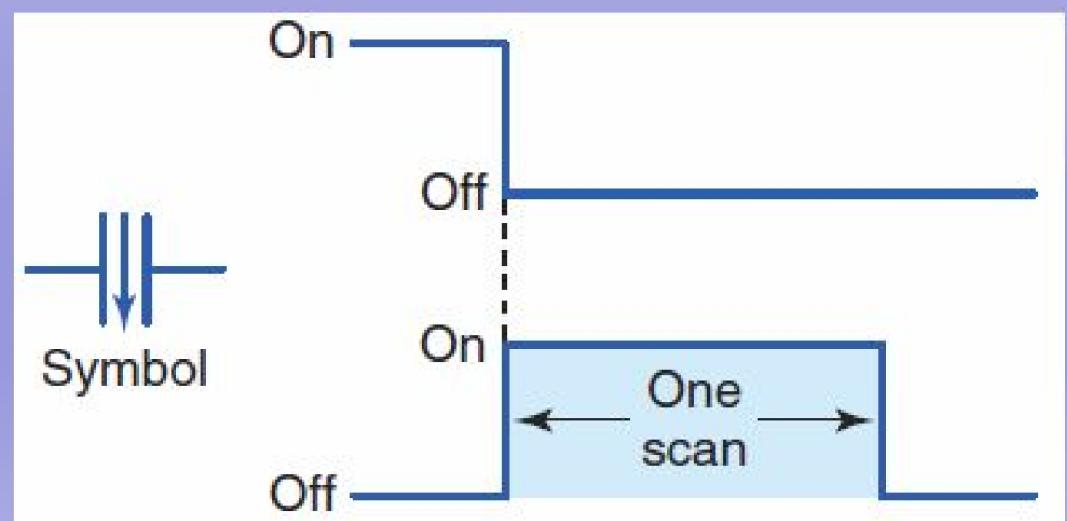
It stays off until the trigger goes off, and then comes on again.

# Some PLCs provide *transitional contacts* or one-shot instructions.

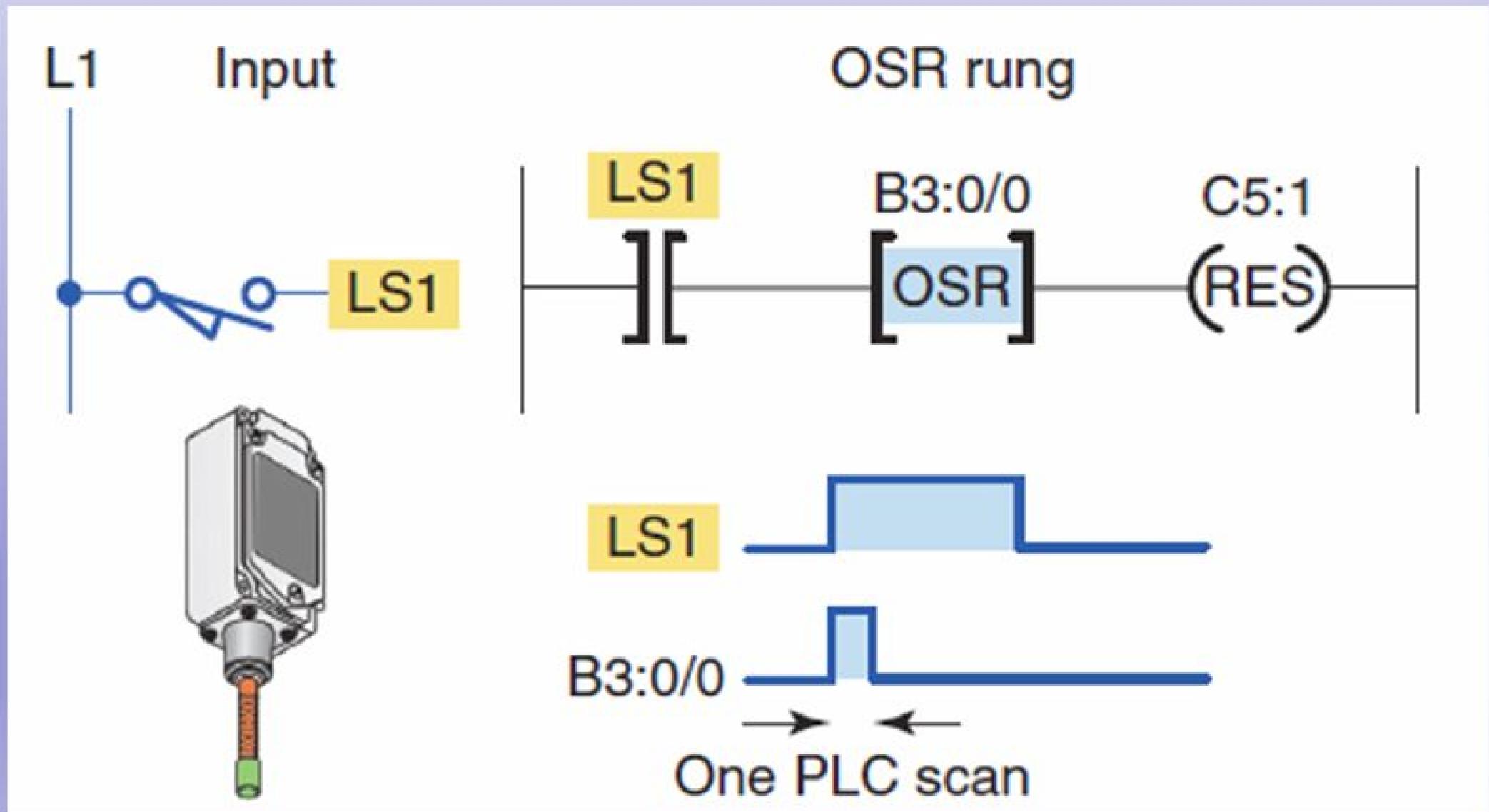
The **off-to-on** transitional contact provides a one-shot pulse when the trigger signal makes a off-to-on transition.



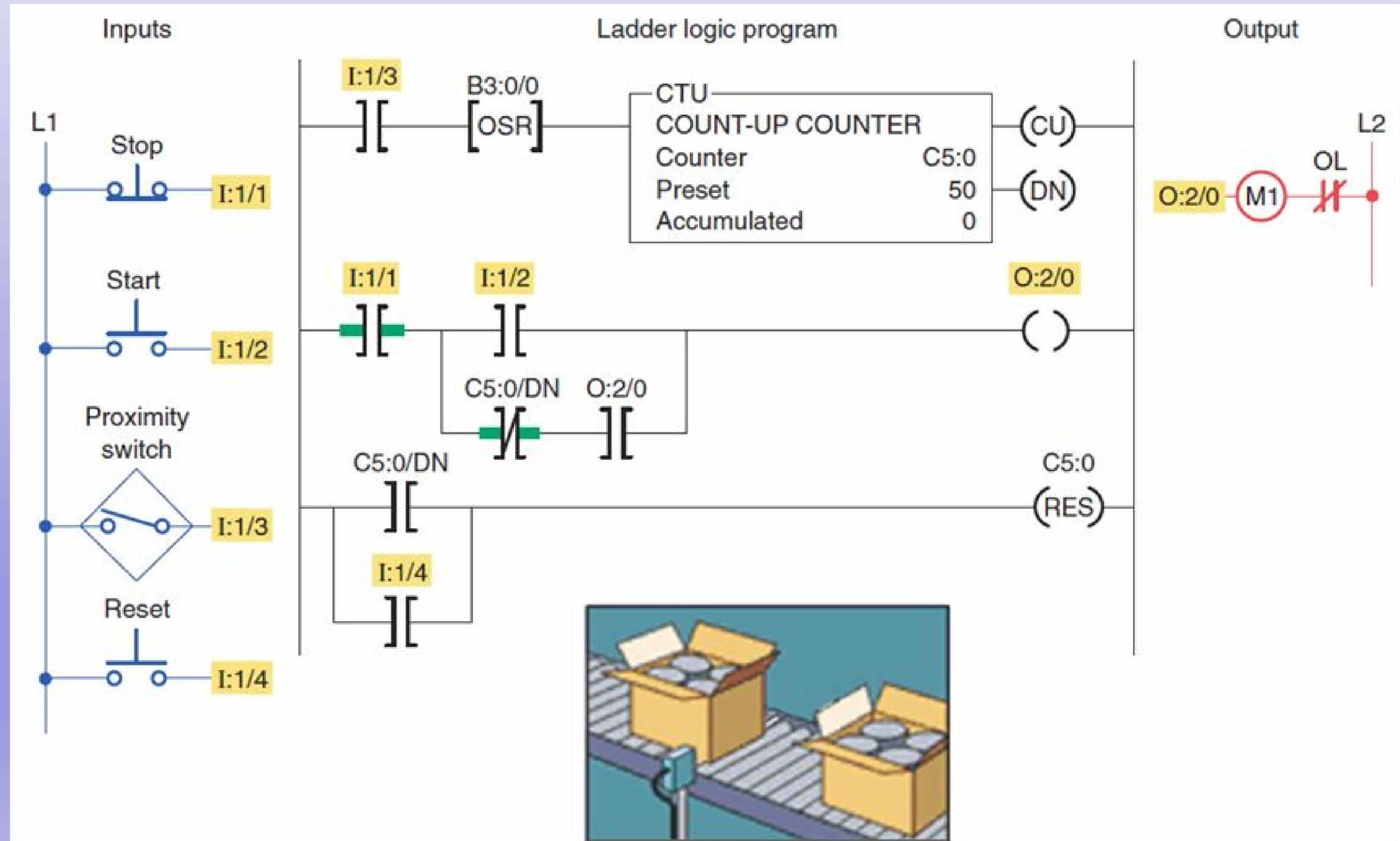
The **on-to-off** transitional contact provides a one-shot pulse when the trigger signal makes a on-to-off transition.



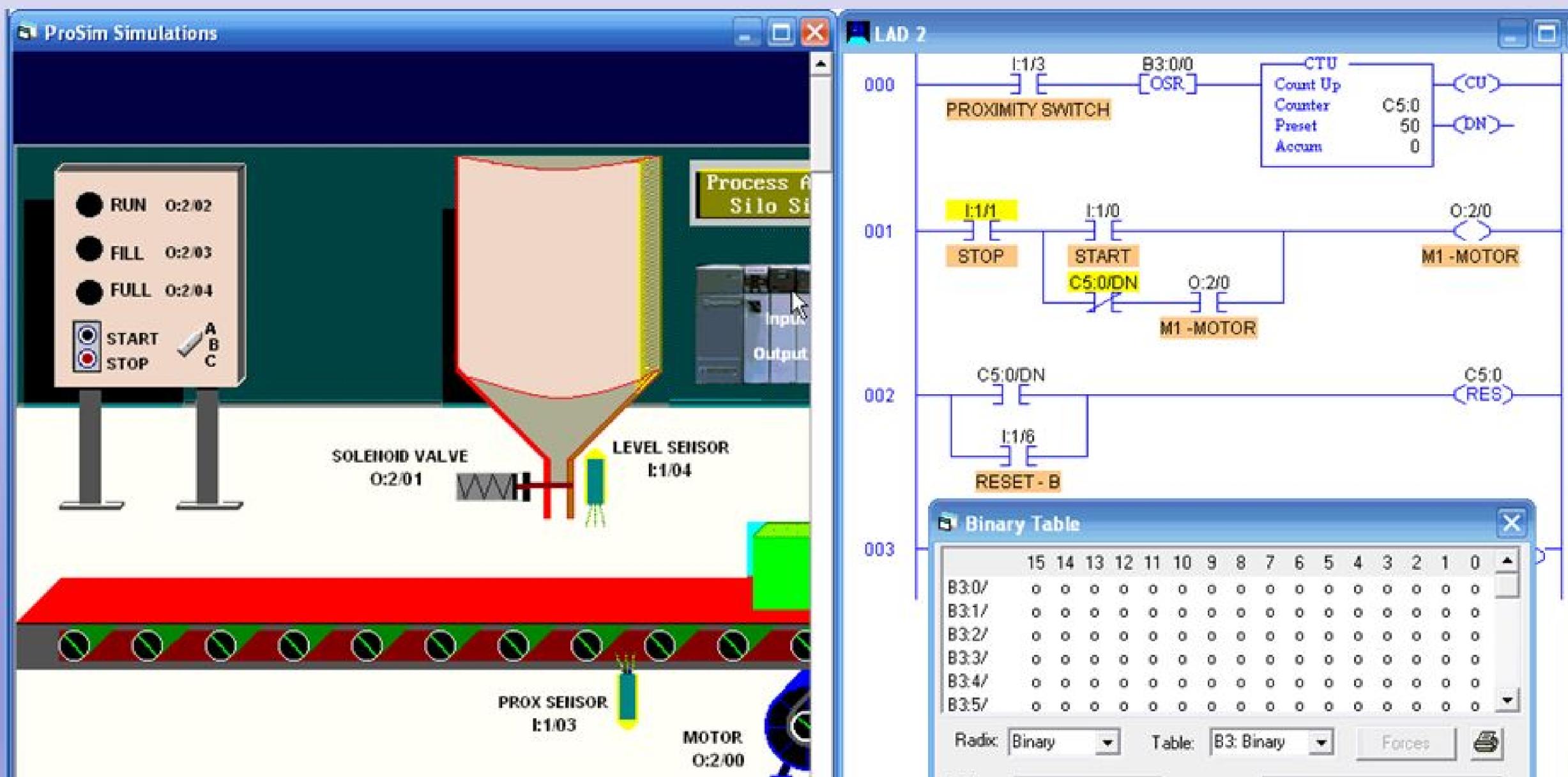
The Allen-Bradley SLC 500 one-shot rising (OSR) instruction is an input instruction that triggers an event to occur one time.



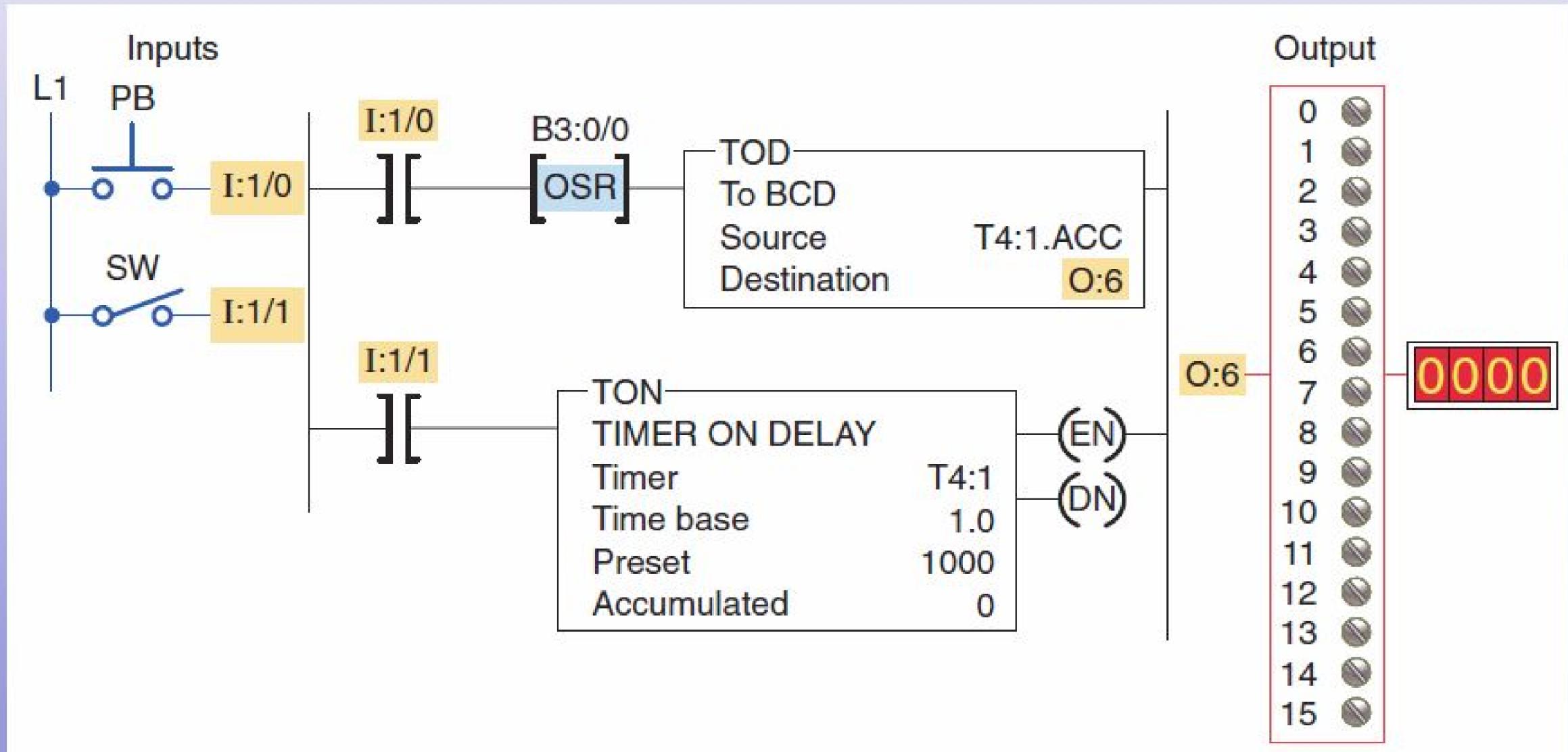
# Up-counter with a programmed *one-shot rising (OSR)* off-to-on transitional contact instruction.



## *Simulated* up-counter with a programmed one-shot rising (OSR) contact instruction.

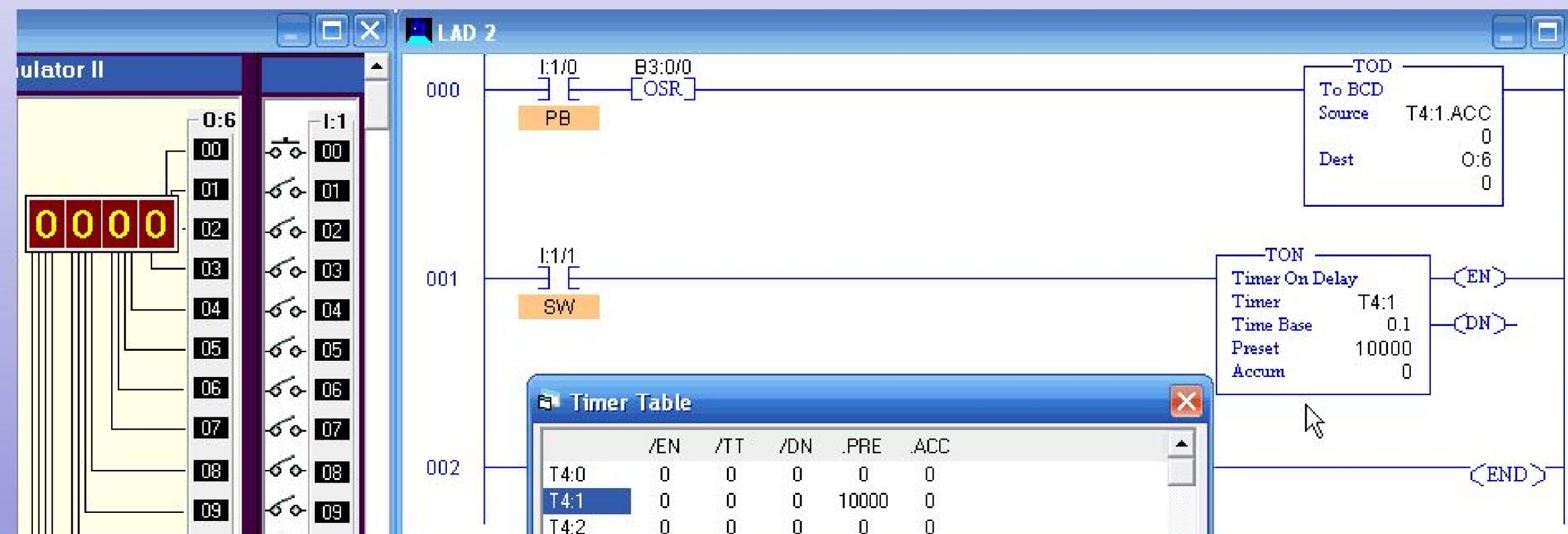


# OSR instruction used to freeze rapidly displayed LED values.

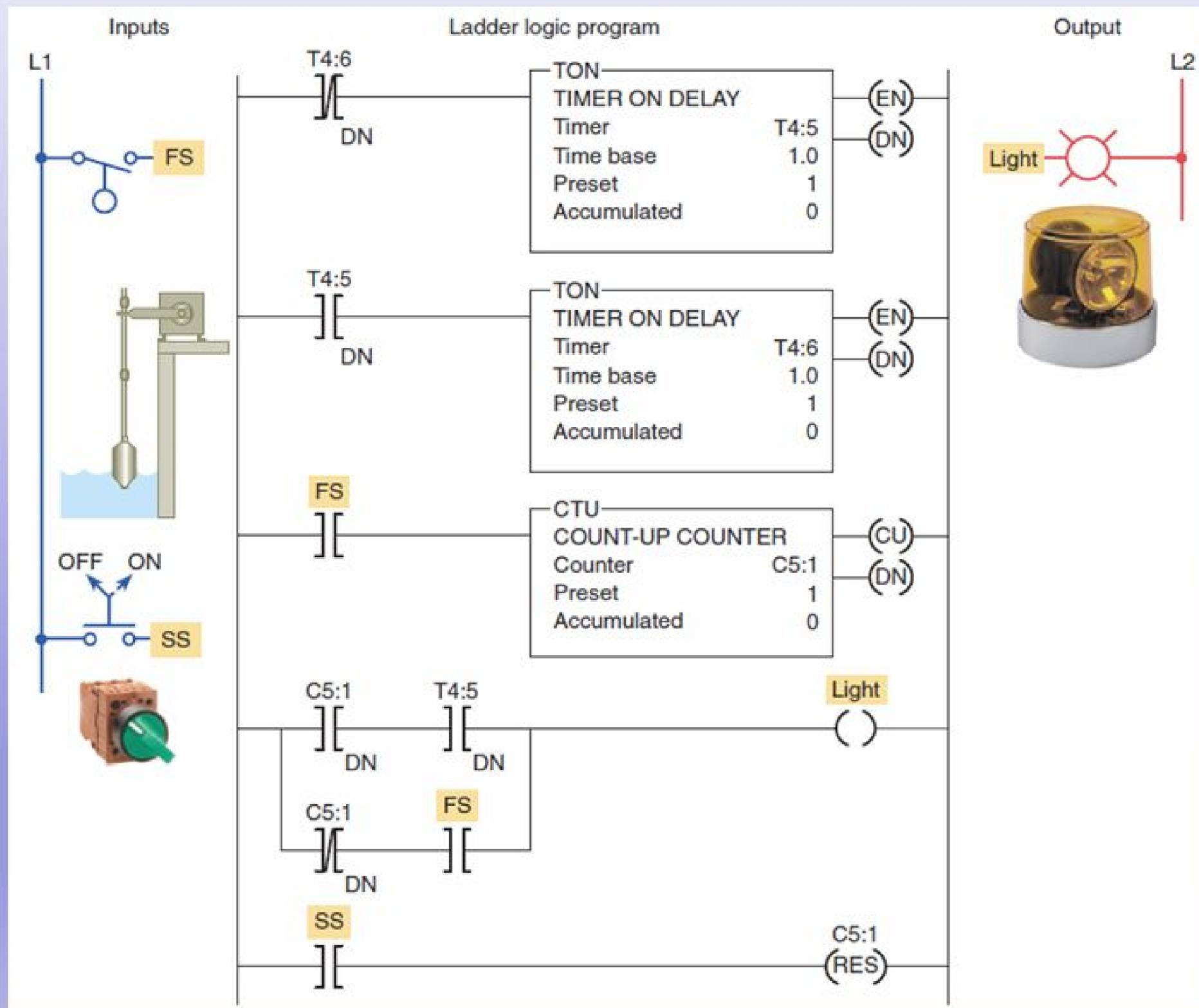


Closing the momentary pushbutton PB (I:1/0) will **freeze** and display the value at **that point in time**.

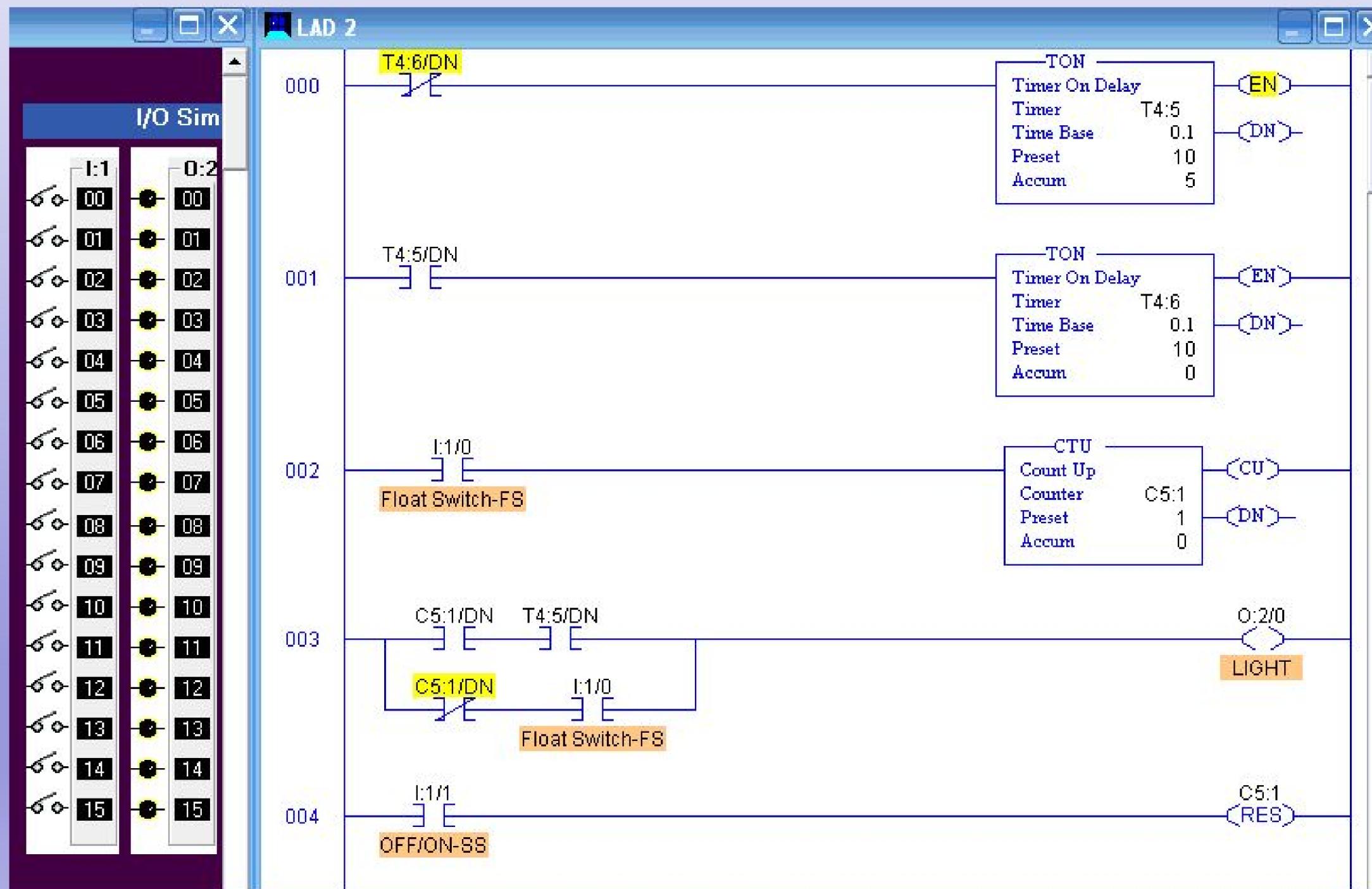
# Simulation of OSR instruction used to freeze rapidly displayed LED values.



## Alarm monitor program.



# Simulated alarm monitor program.

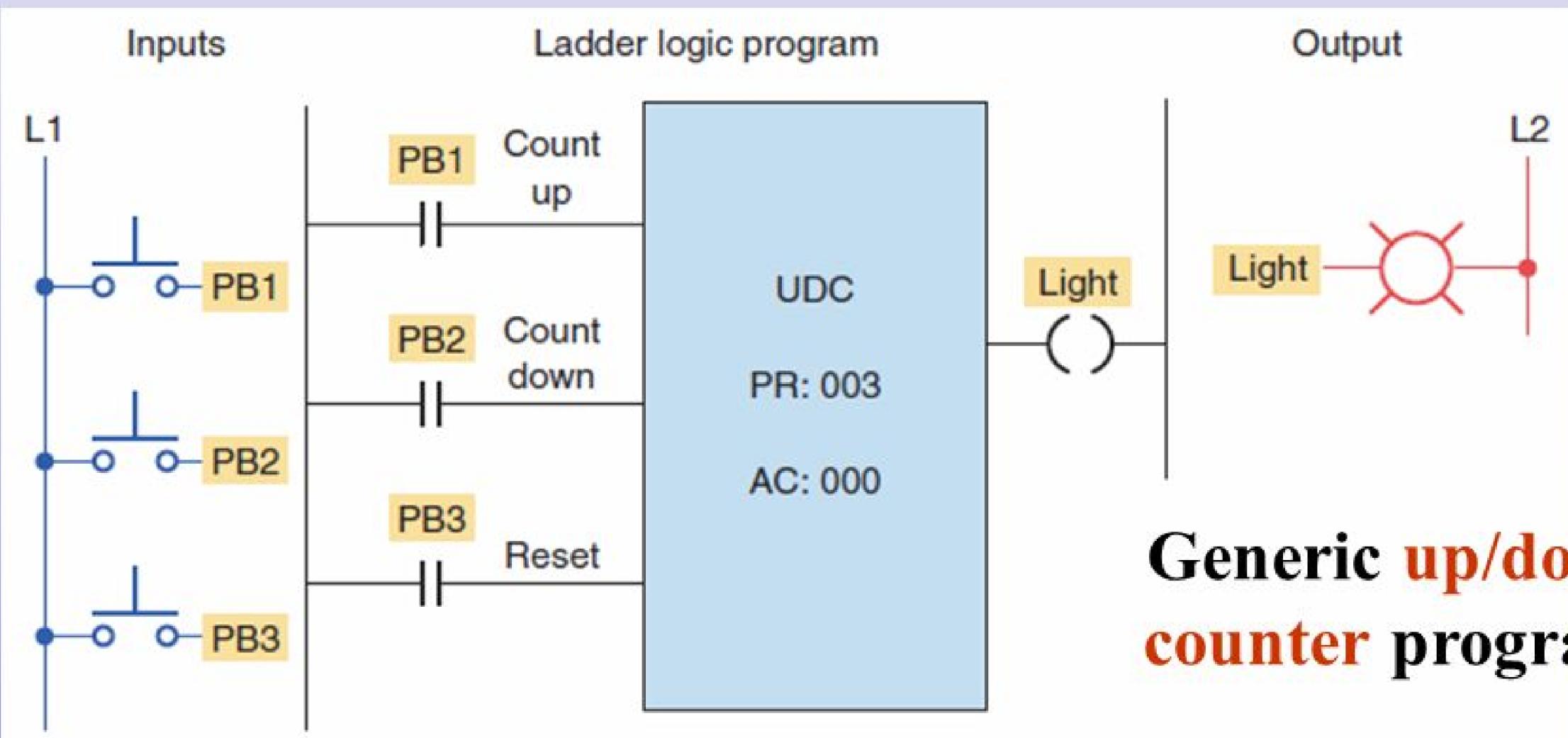


# 8.3



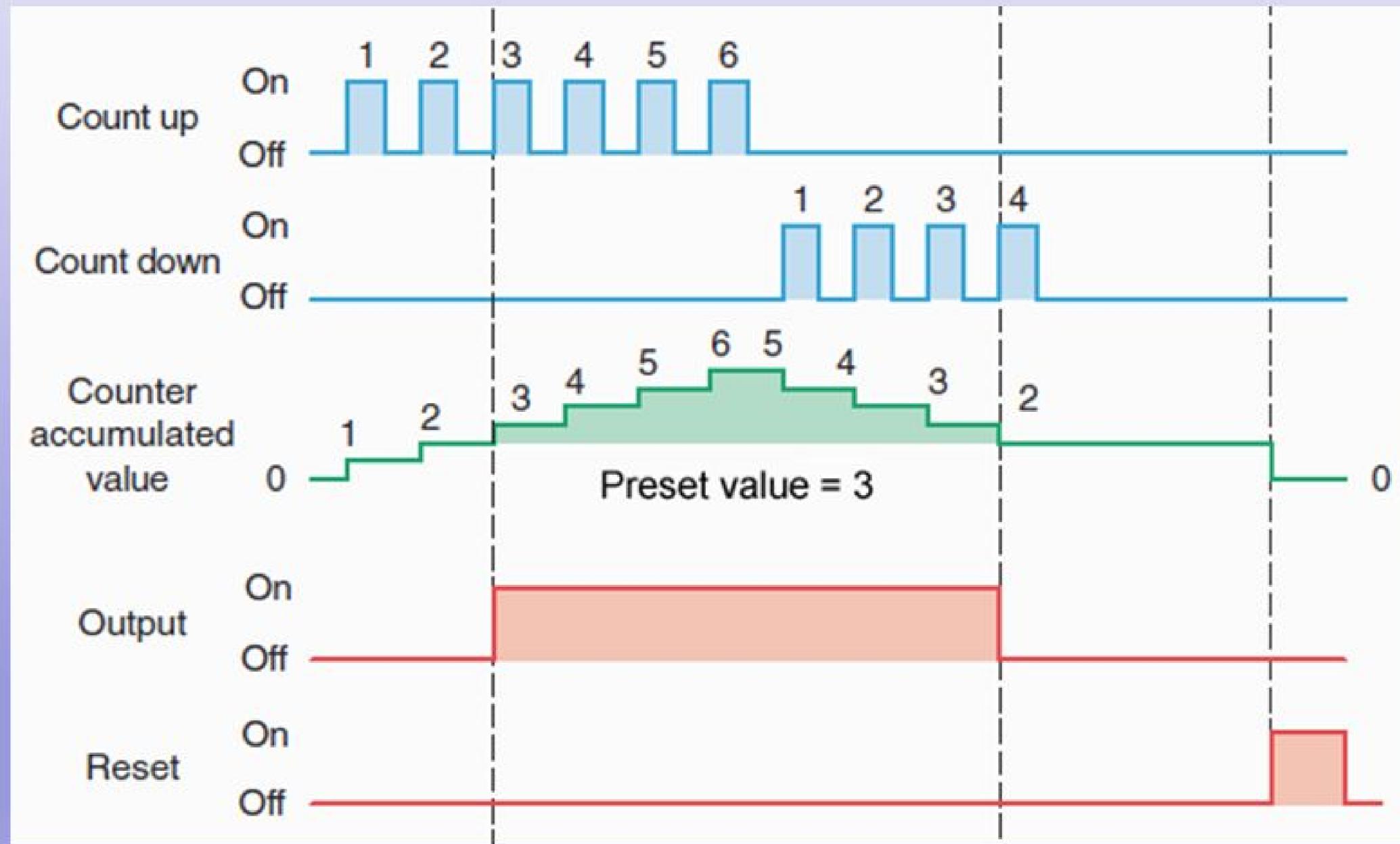
# Down-Counter

**A down-counter will count down or decrement by 1 each time the counted event occurs.**

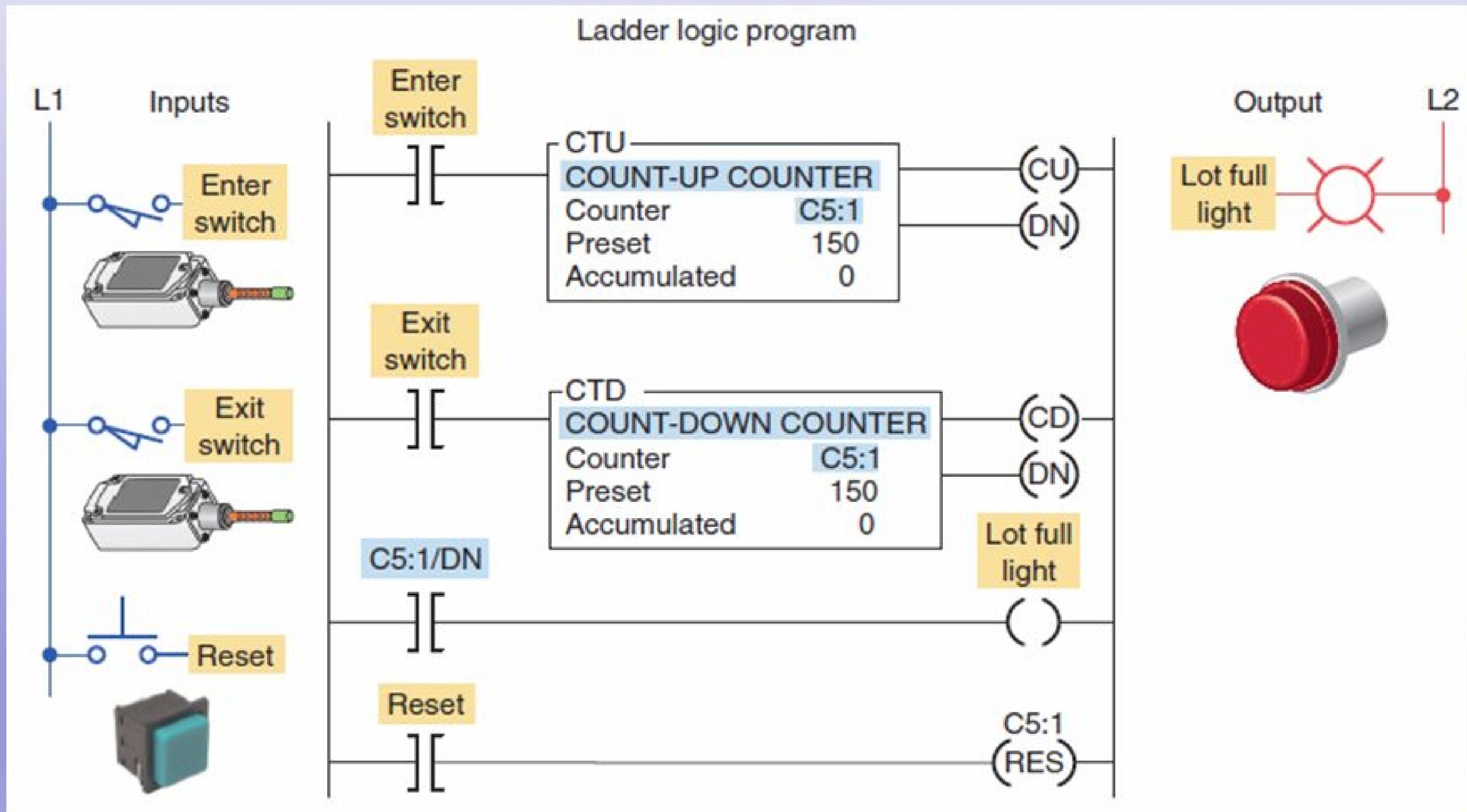


Normally the **down**-counter is used in **conjunction** with the **up**-counter to form an up/down-counter.

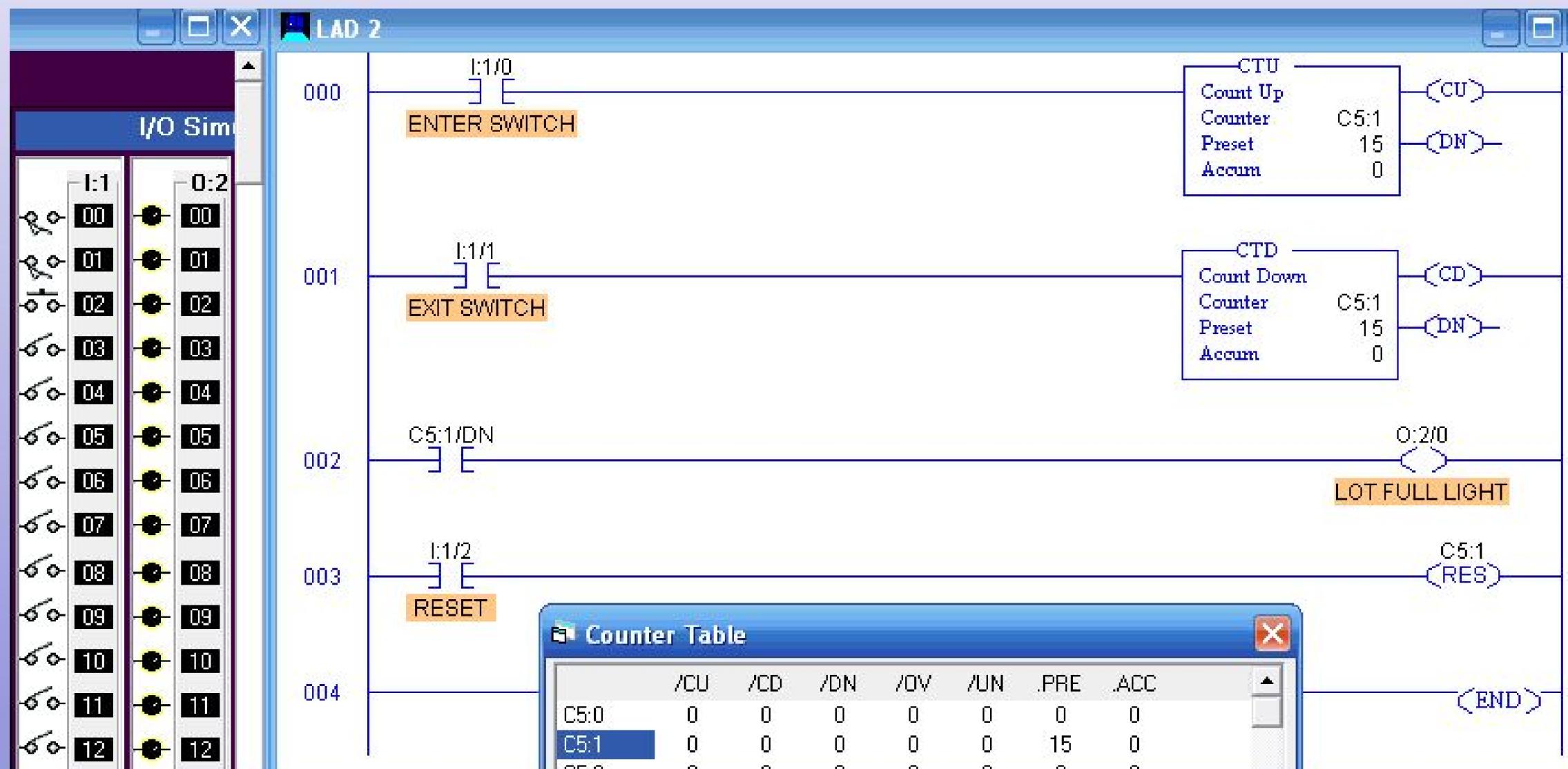
# Up/down counter program counting diagram.



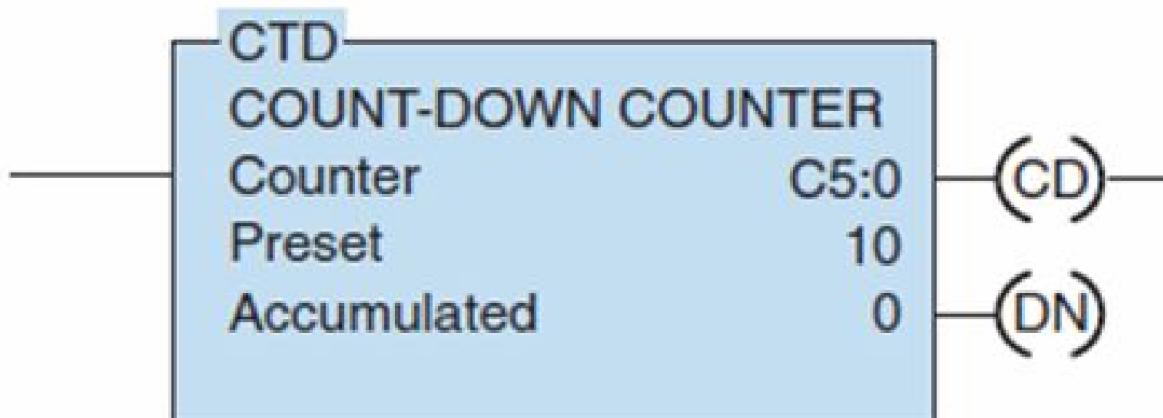
# Parking garage counter program.



# Simulated parking garage counter program.



# Count-down counter instruction used as part of the SLC 500 controller instruction set.



C5:0/CD

][ Counter enable bit

C5:0/DN

][ Counter done bit

C5:0/UN

][ Underflow status bit

C5:0  
(RES)

The reset instruction resets the counter's accumulated value back to zero.

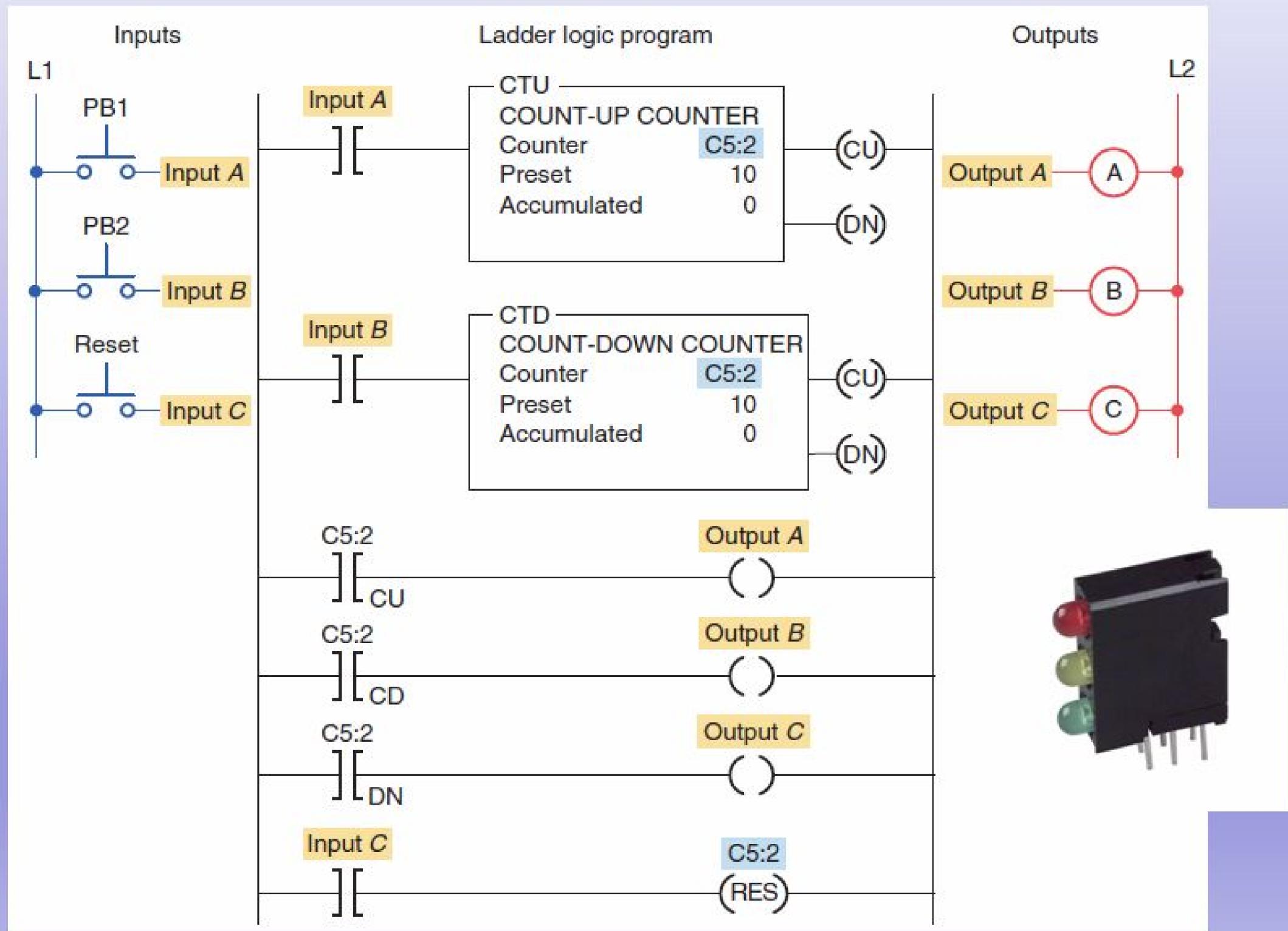
Counter Table

	/CU	/CD	/DN	/OV	/UN	/UA	.PRE	.ACC
C5:0	0	0	0	0	0	0	0	0
C5:1	0	0	0	0	0	0	0	0
C5:2	0	0	0	0	0	0	0	0
C5:3	0	0	0	0	0	0	0	0
C5:4	0	0	0	0	0	0	0	0
C5:5	0	0	0	0	0	0	0	0

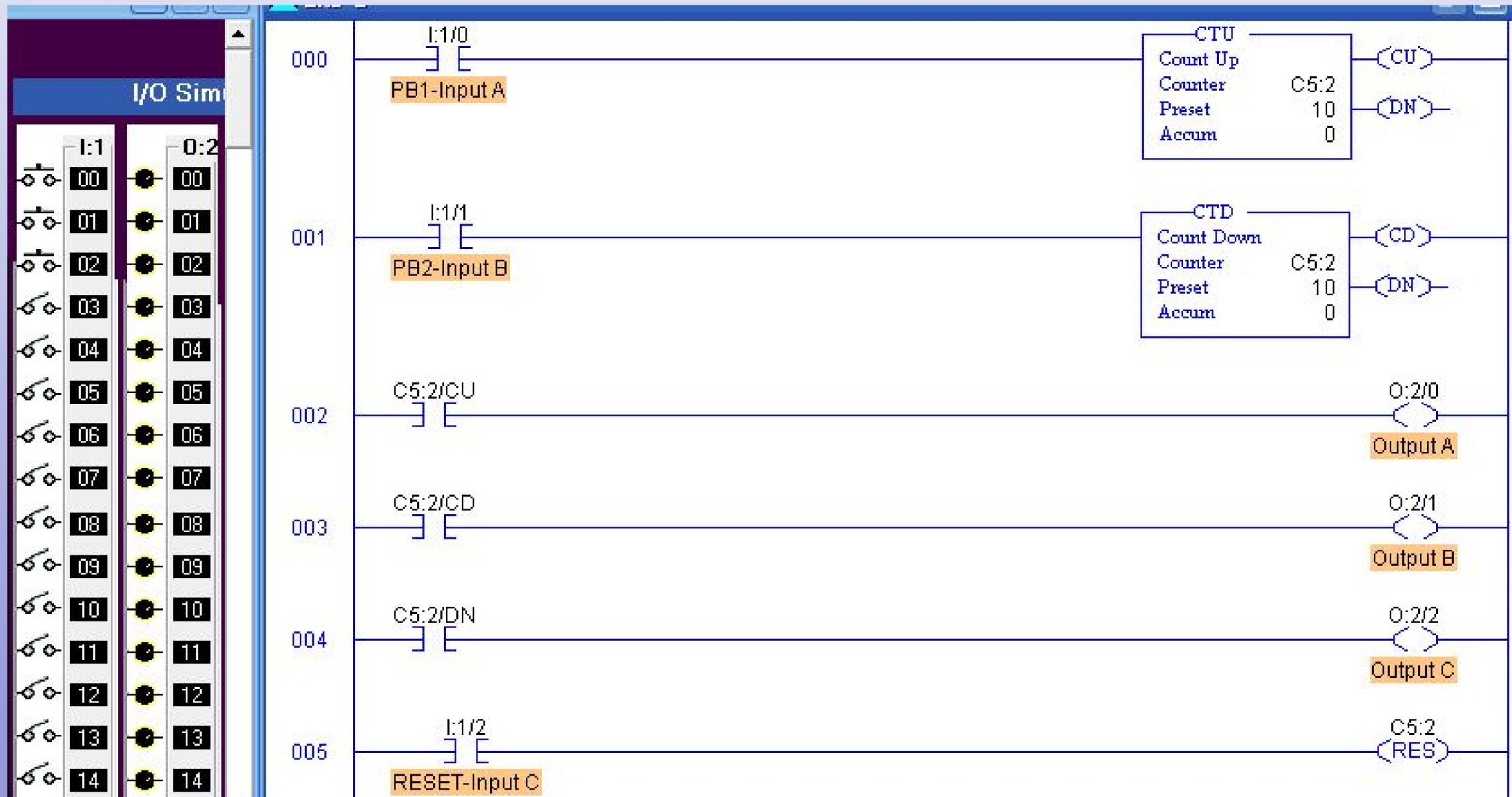
Address  Table: C5: Counter ▾

The information to be entered into the instruction is the **same as for the count-up instruction.**

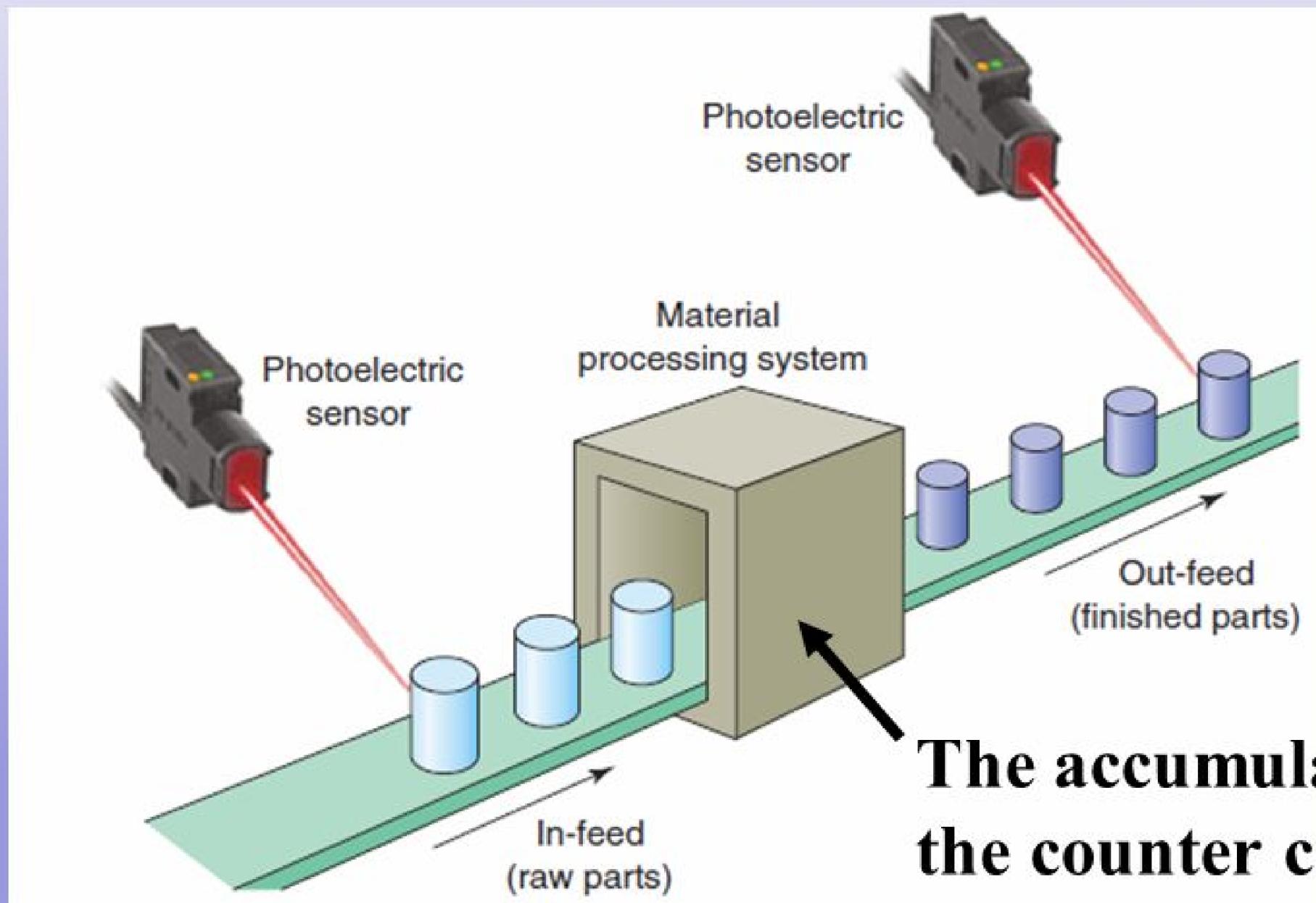
# Up/down-counter program.



# Simulated up/down-counter program.

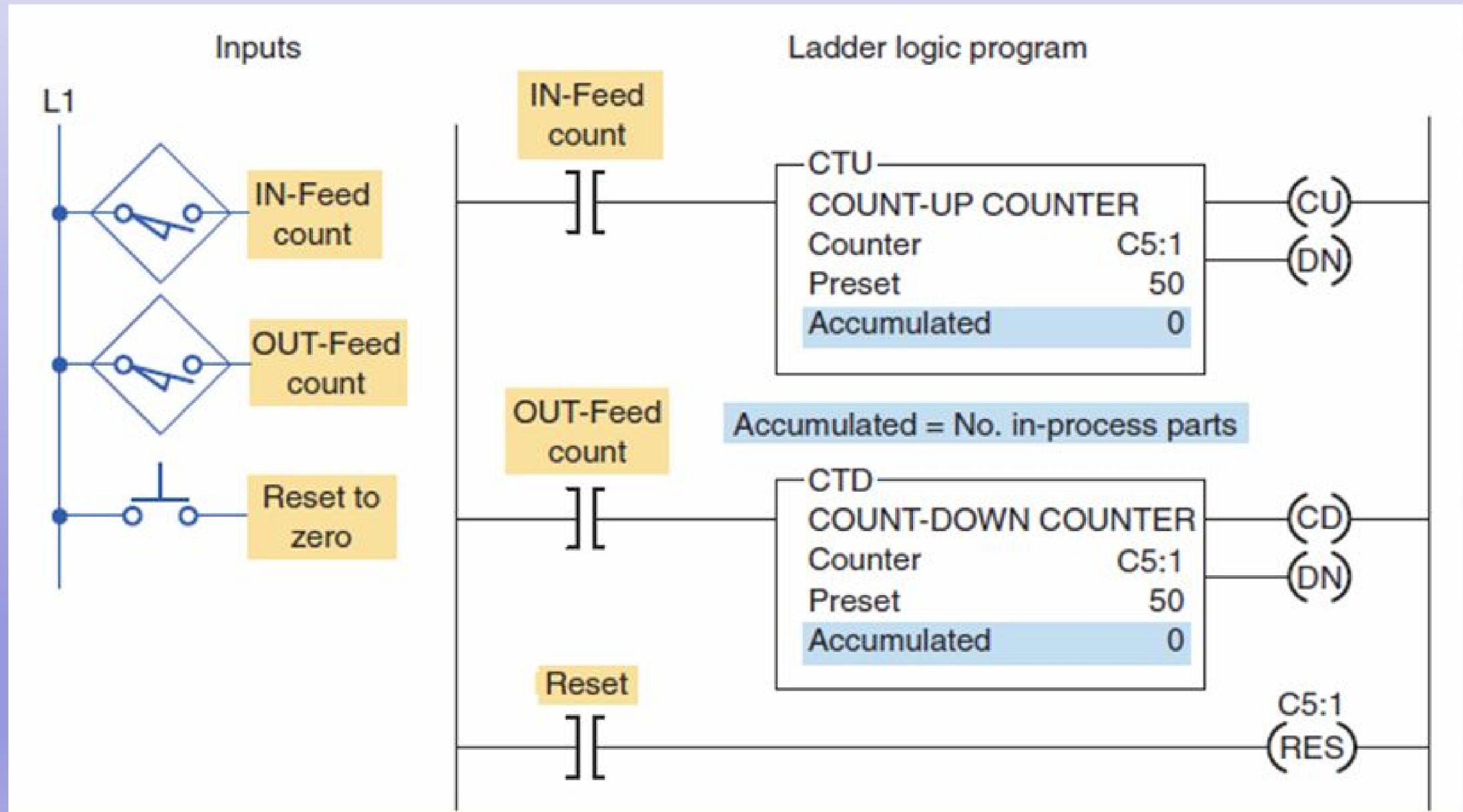


# Program that provides continuous monitoring of items in process.

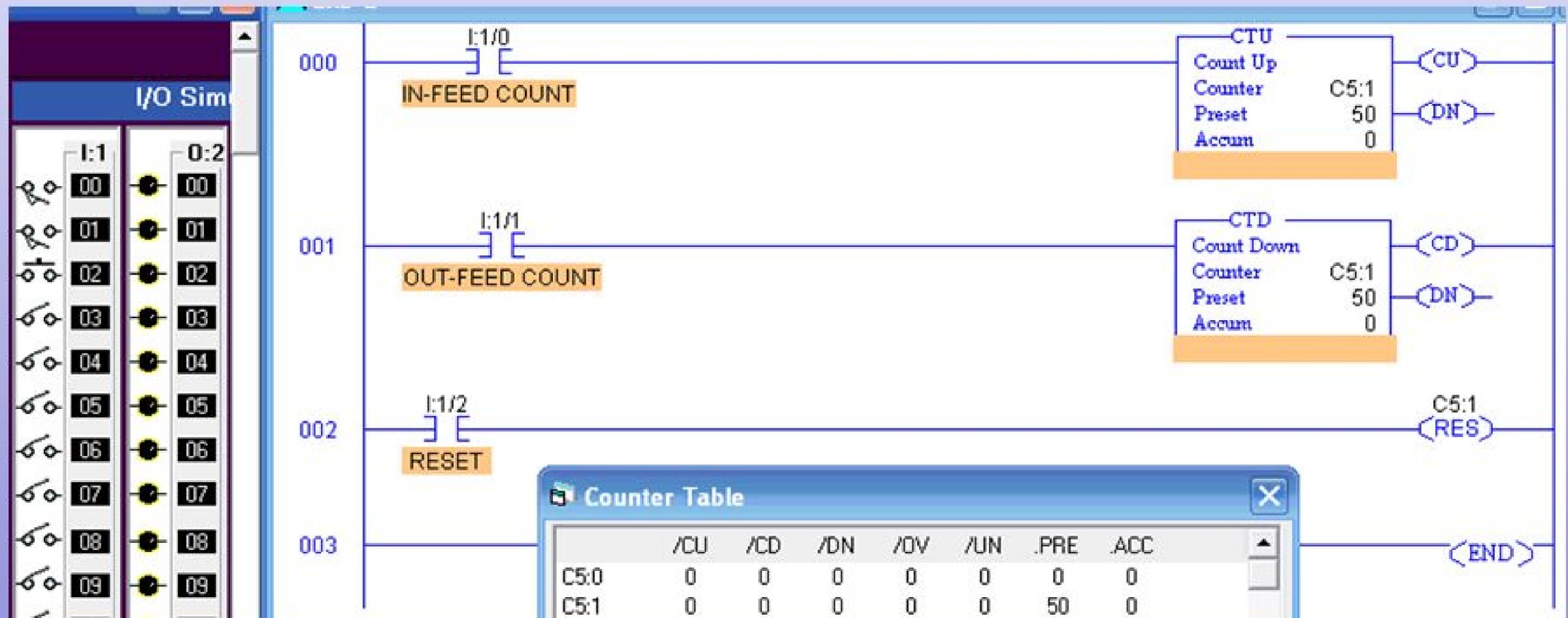


**The accumulated count of the counter continuously indicates the number of in-process parts.**

# Program that provides continuous monitoring of items in process.



# Simulated program that provides continuous monitoring of items in process.

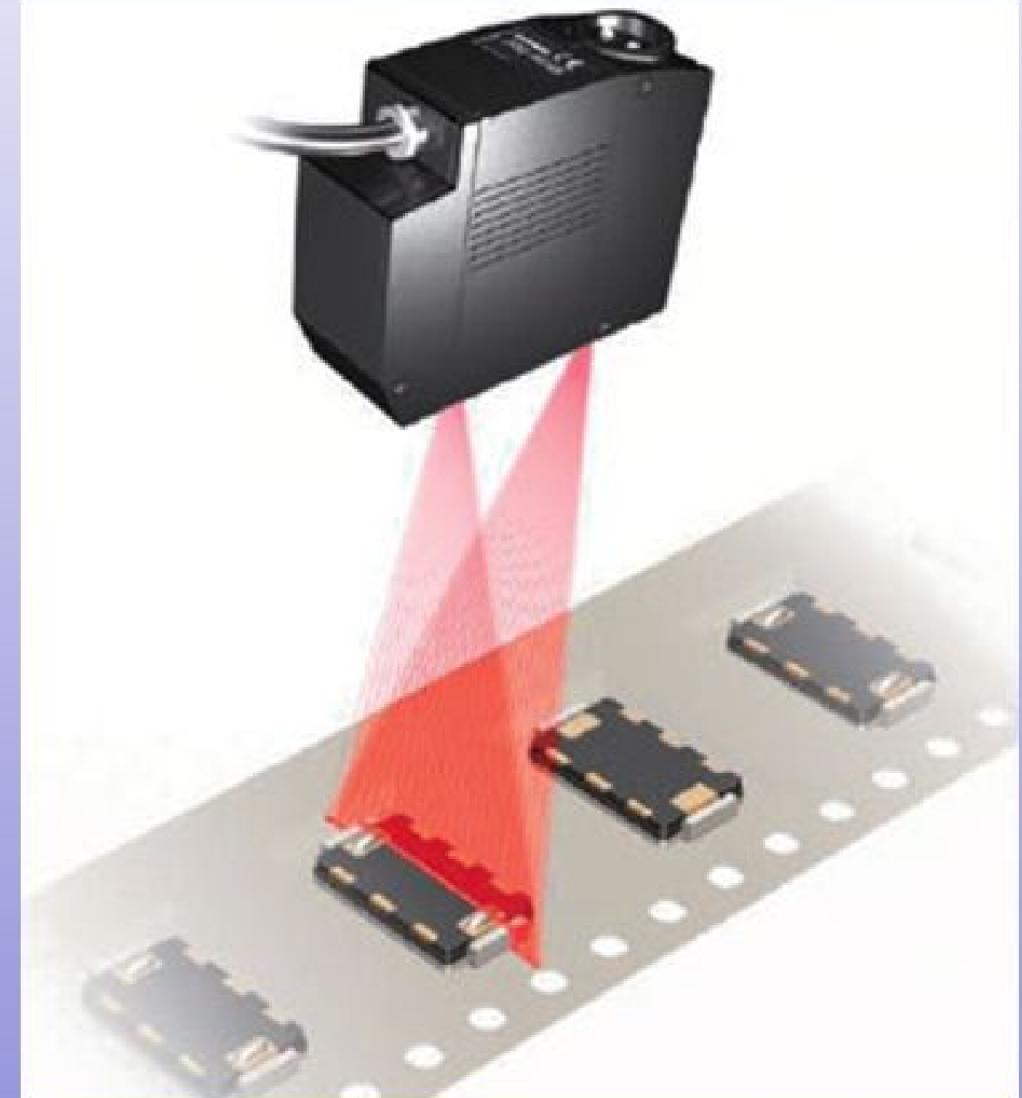


# 8.4

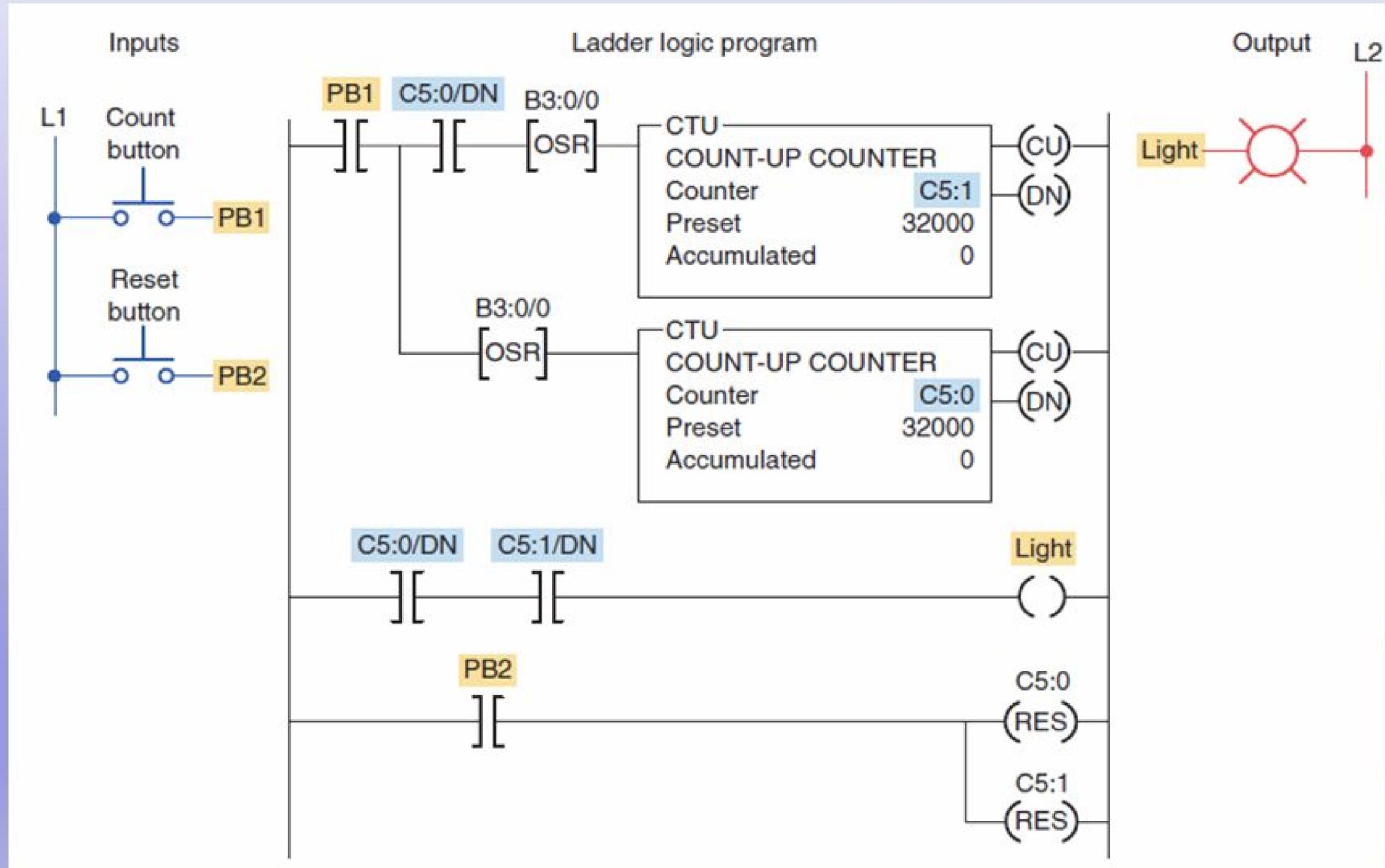


# Cascading Counters

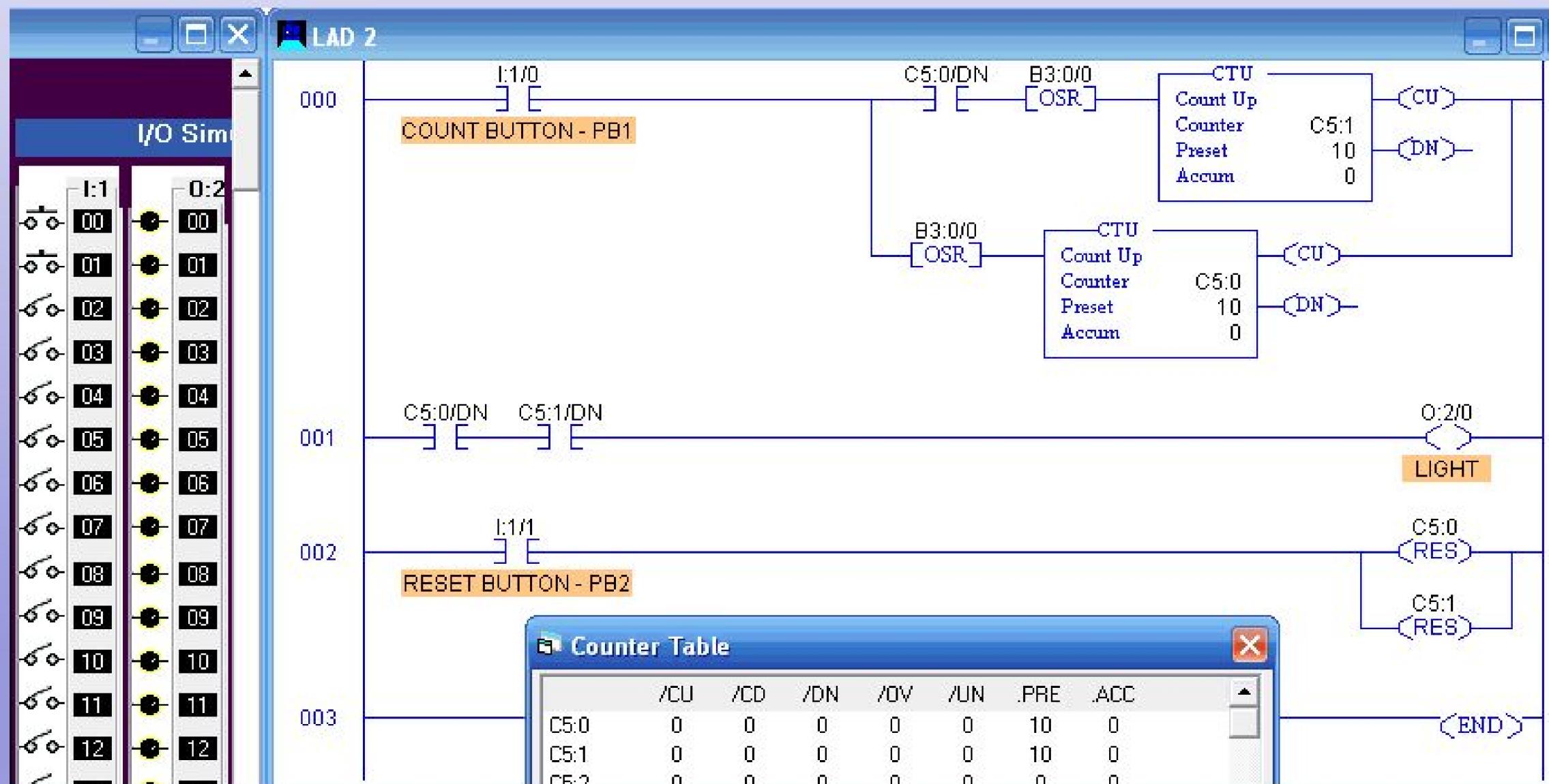
Depending on the application, it may be necessary to count events that exceed the maximum number allowable per counter instruction. One way of accomplishing this count is by *interconnecting, or cascading, two counters.*



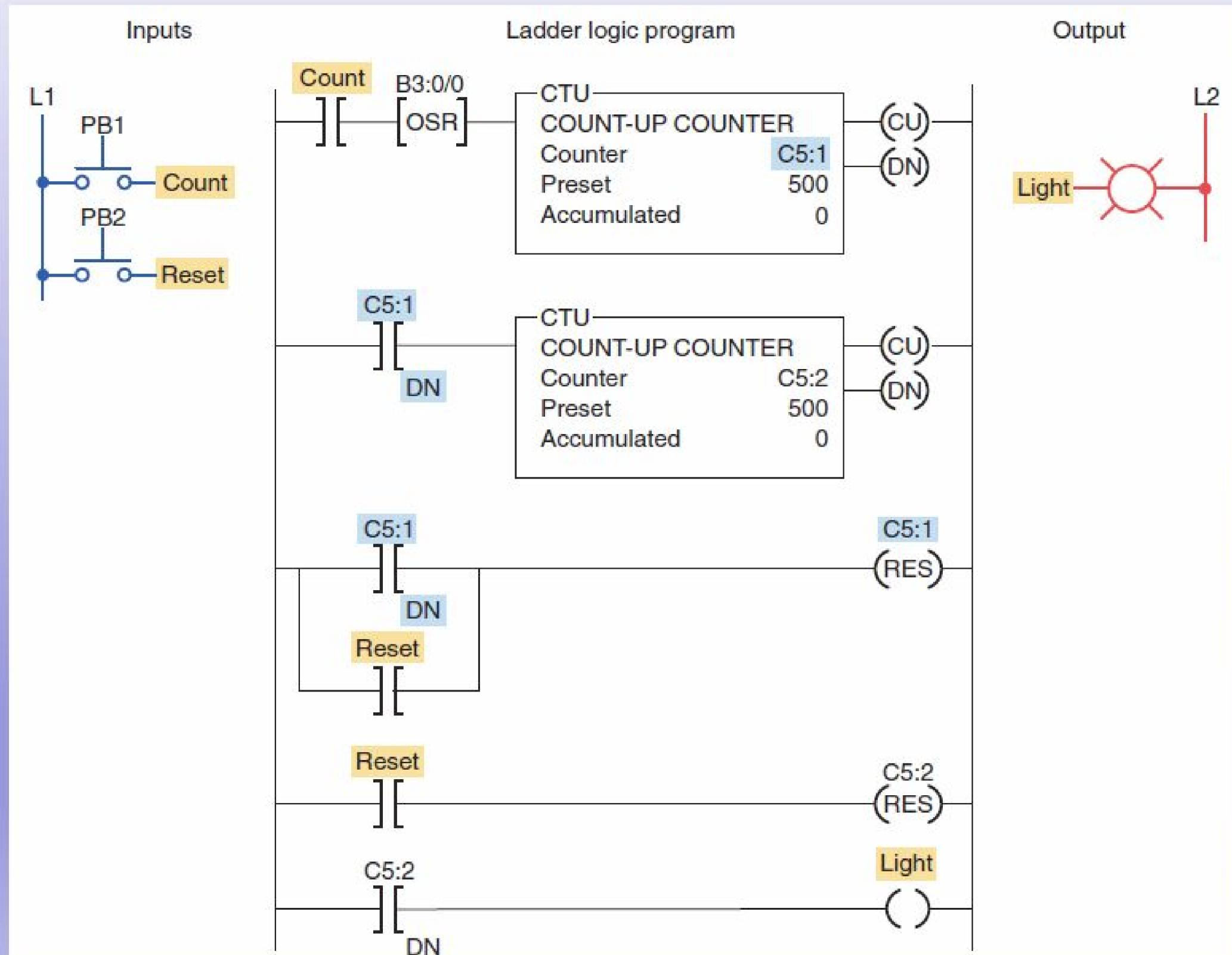
# Counting beyond the maximum count program.



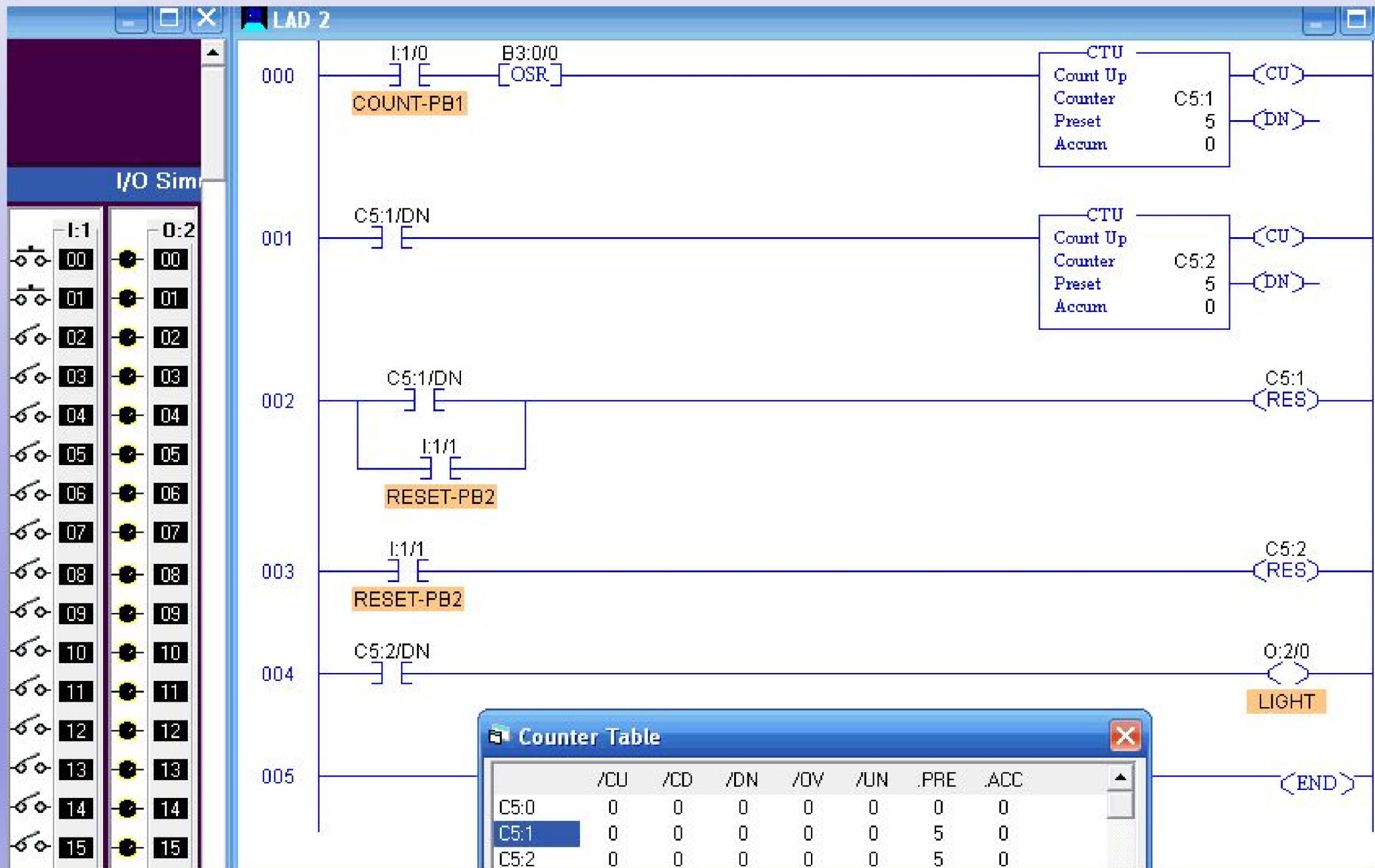
# Simulated counting beyond the maximum count program.



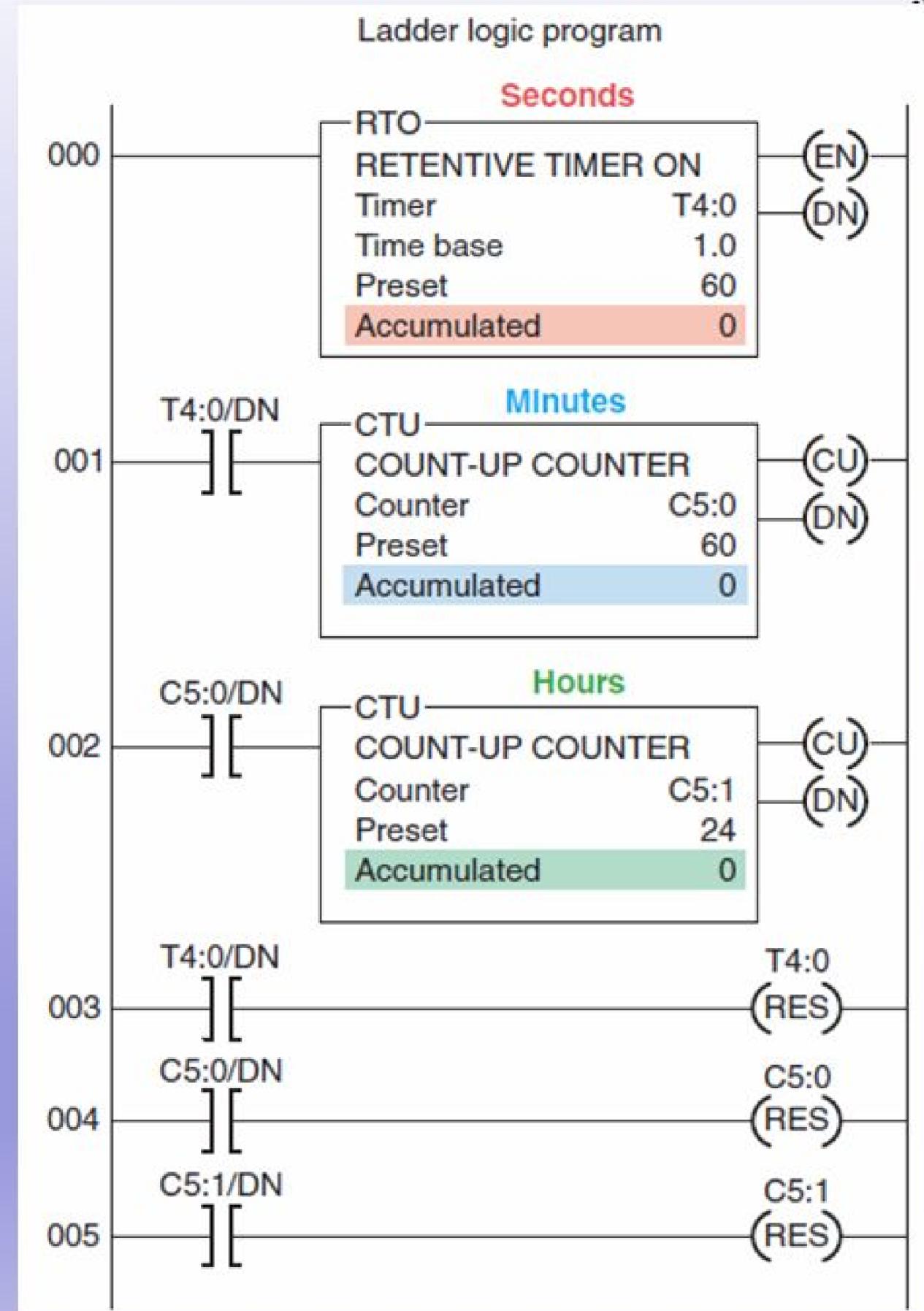
# Cascading counters for *extremely large counts.*



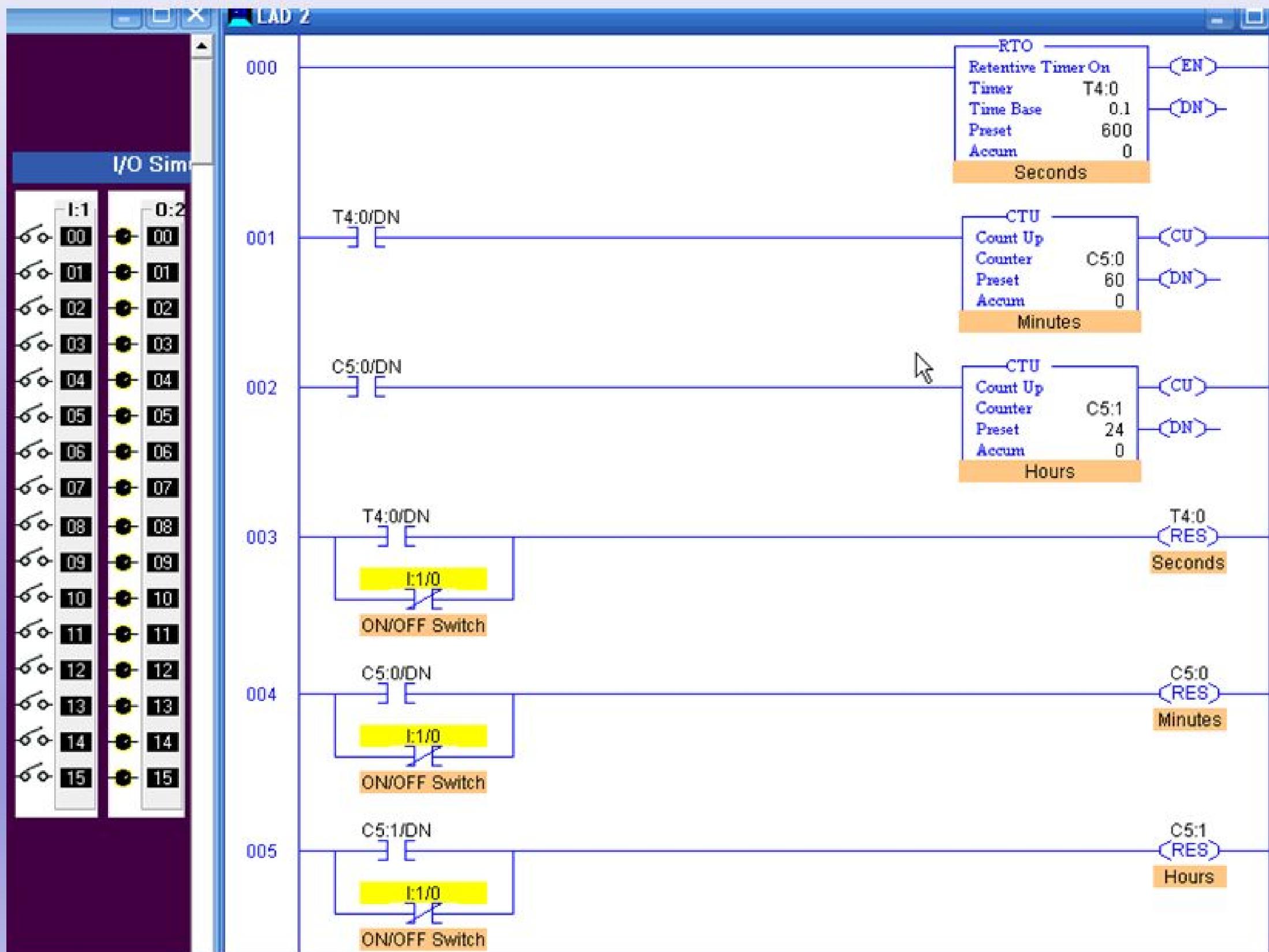
# Simulated program for extremely large counts.



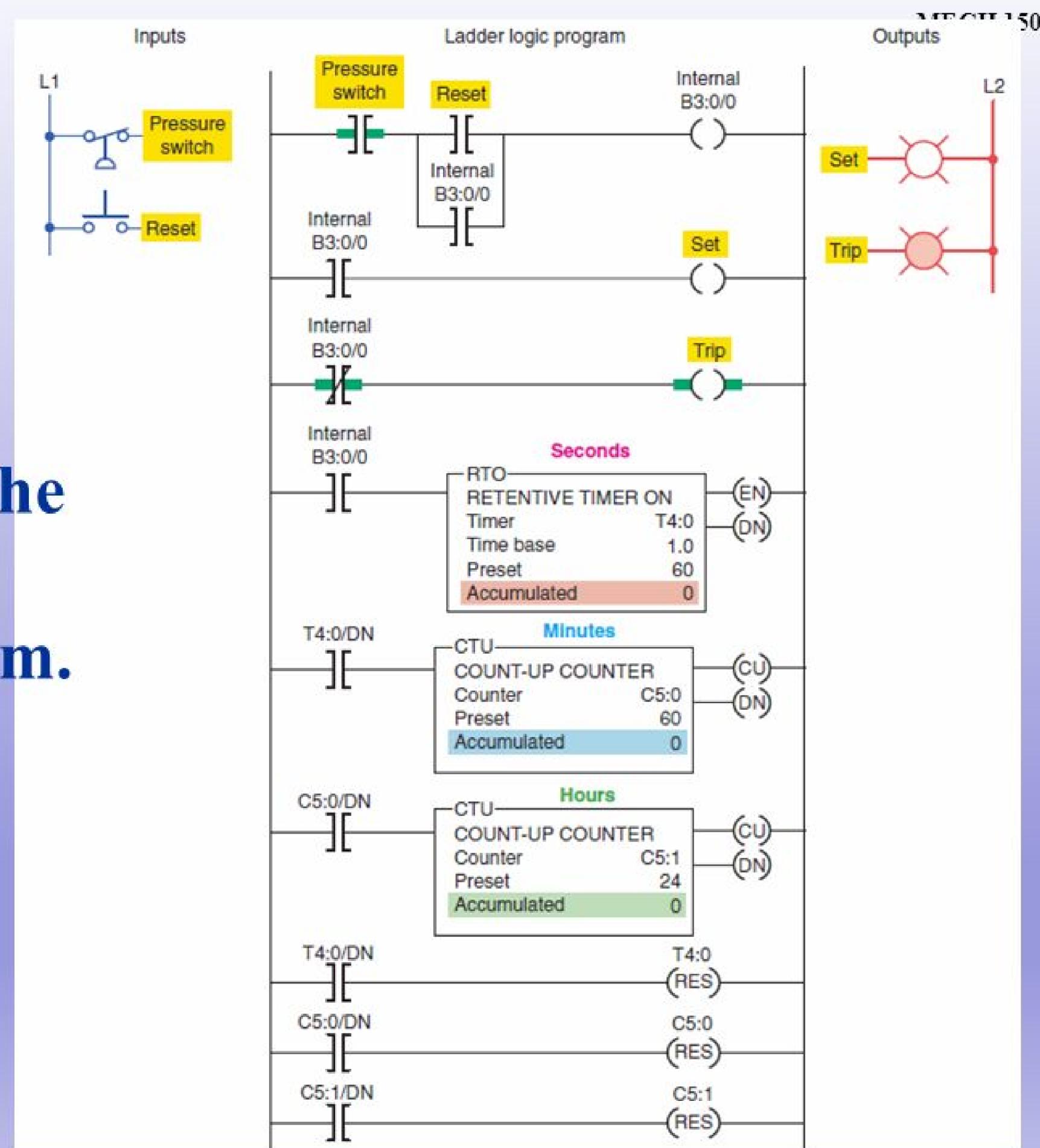
# 24-hour clock program.



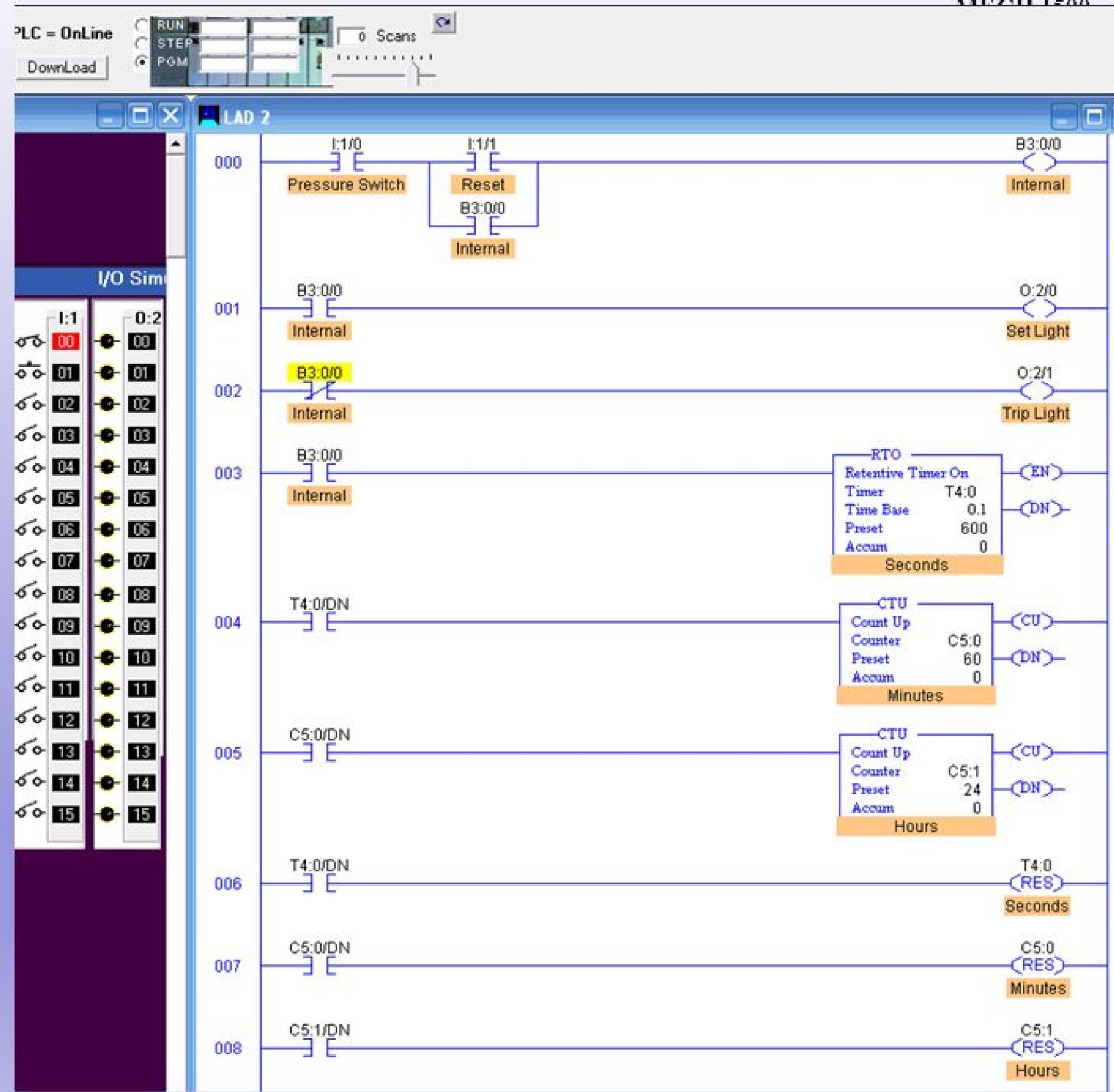
# Simulated 24-hour clock program.



# Monitoring the time of an event program.



# Simulated time of an event program.

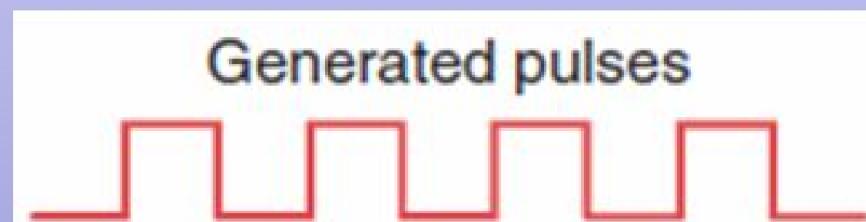
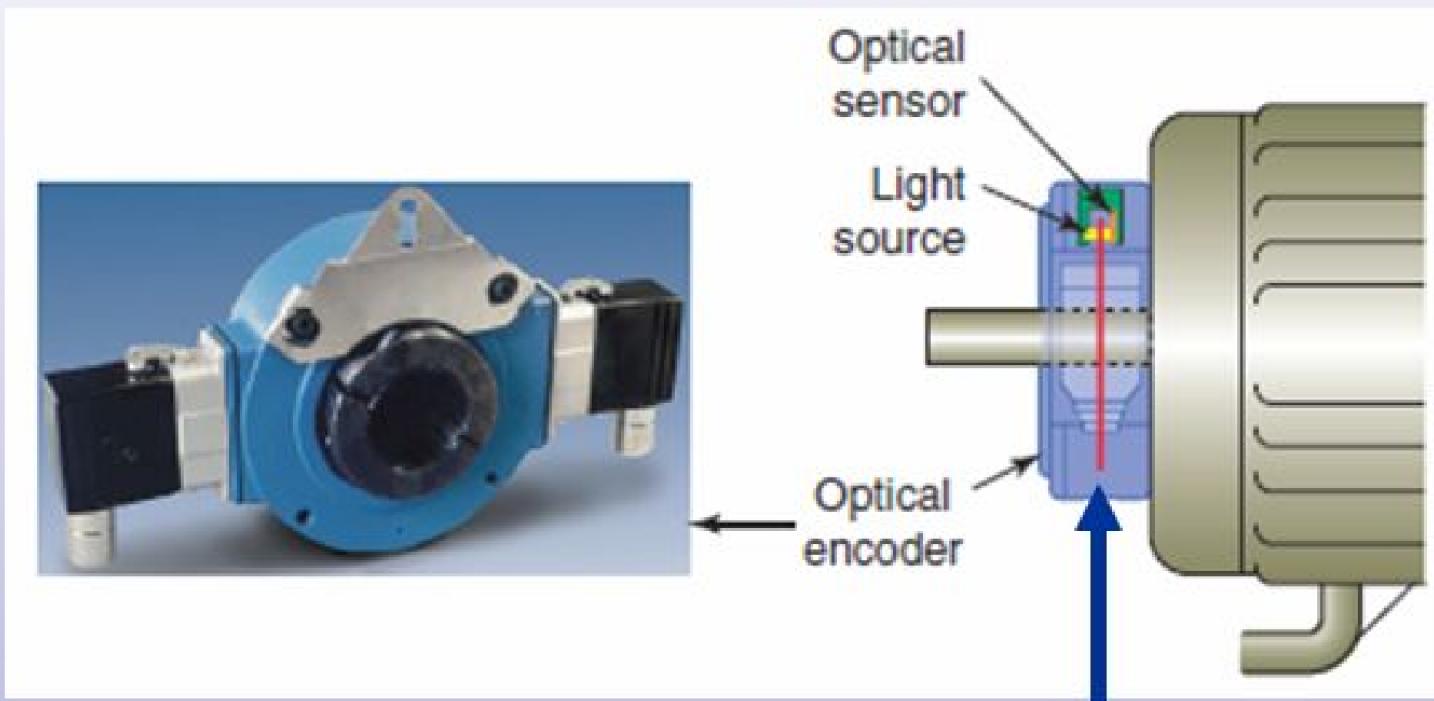


# 8.5

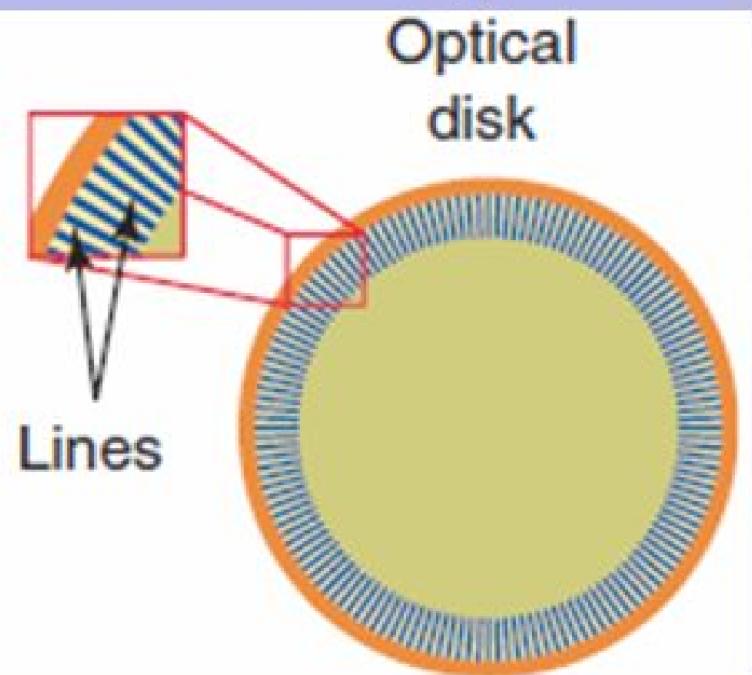


# Incremental Encoder-Counter Applications

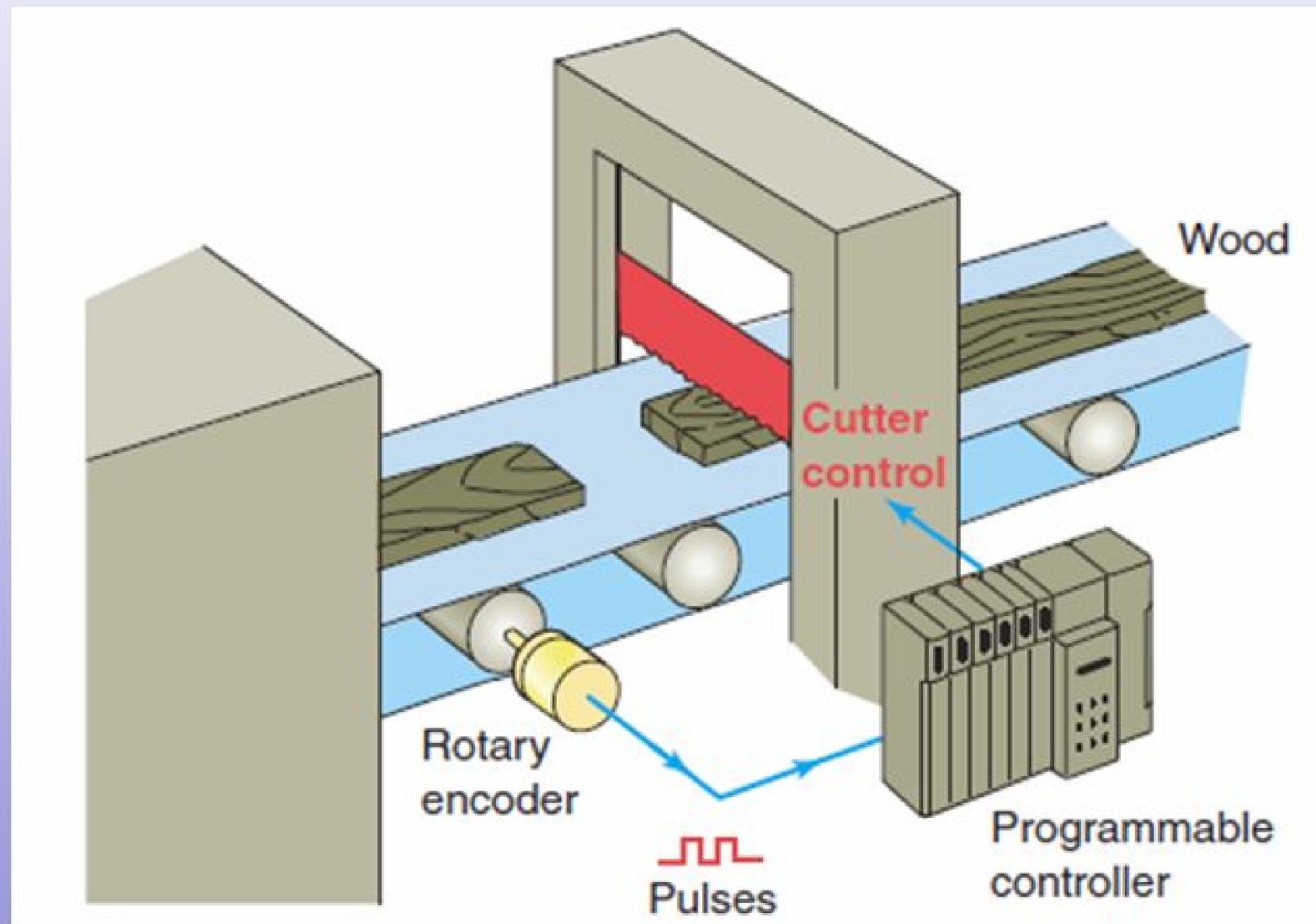
The incremental *optical encoder* creates a series of square waves as its shaft is rotated.



The encoder disk interrupts the light as the encoder shaft is rotated to produce the **square wave** output waveform.

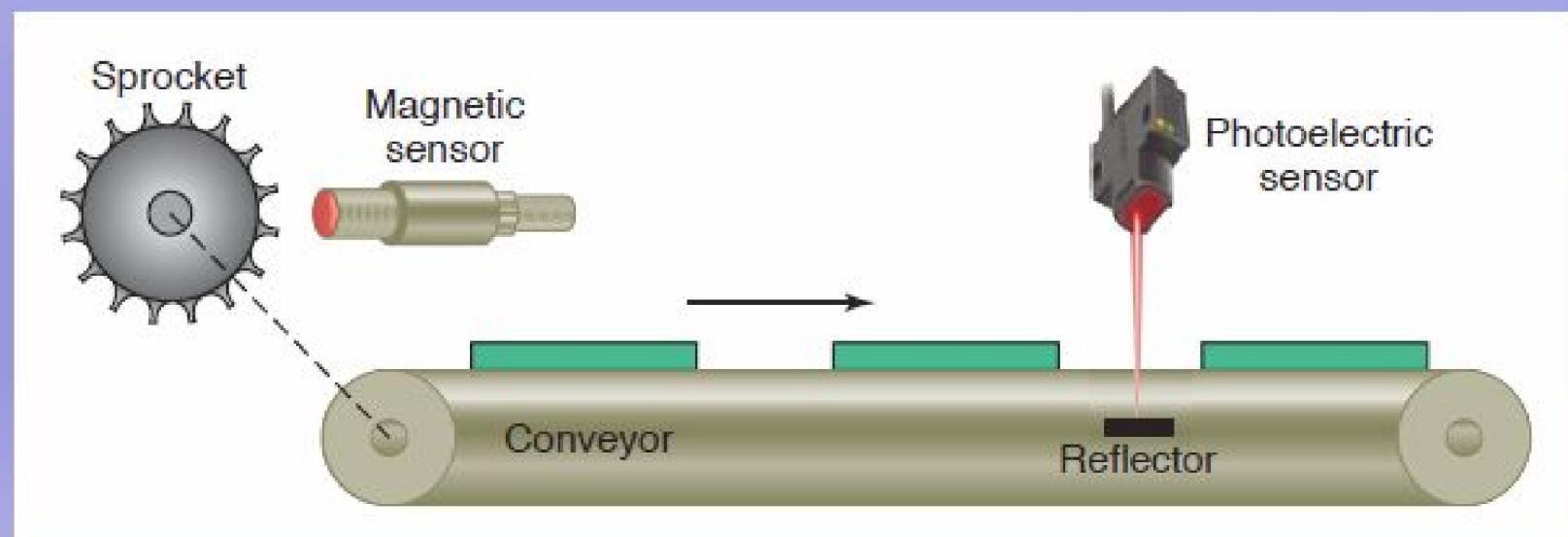
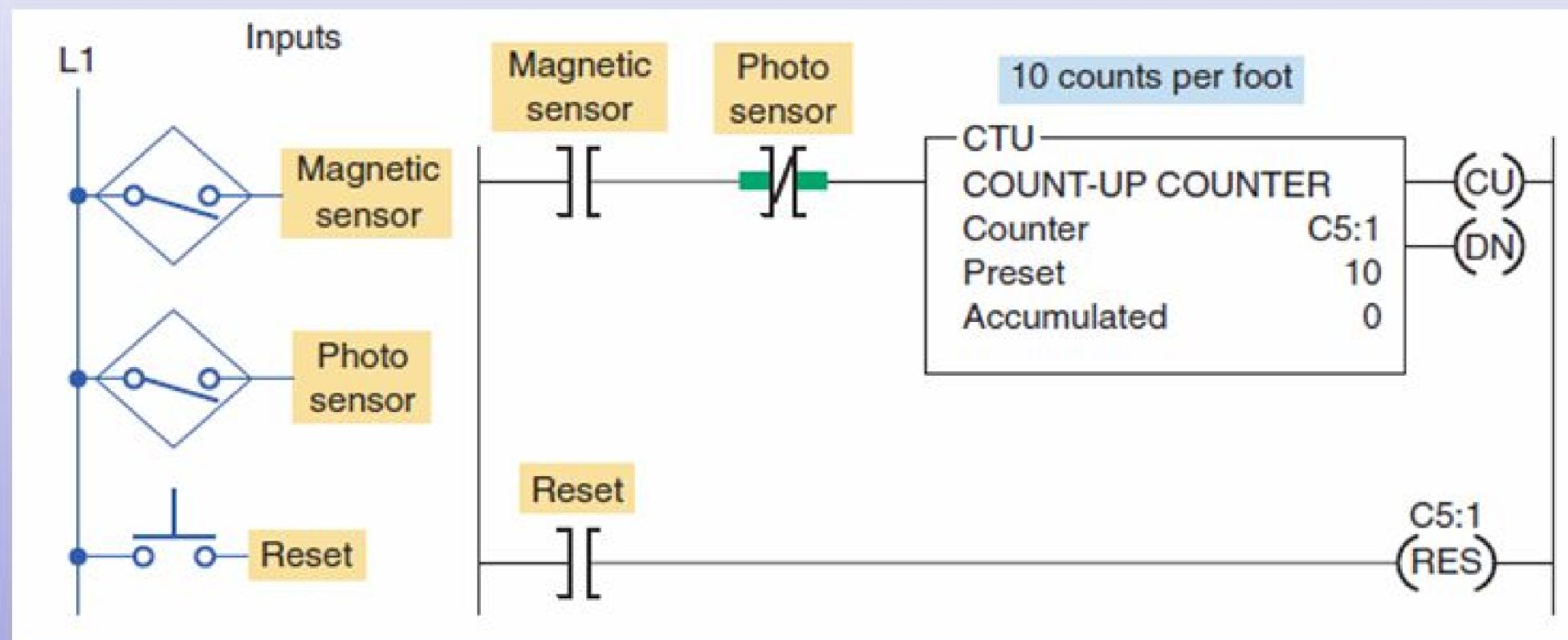


# Cutting objects to a specified length.



The object is advanced for a specified distance and measured by encoder pulses to determine the correct length for cutting.

# Counter program used for length measurement.

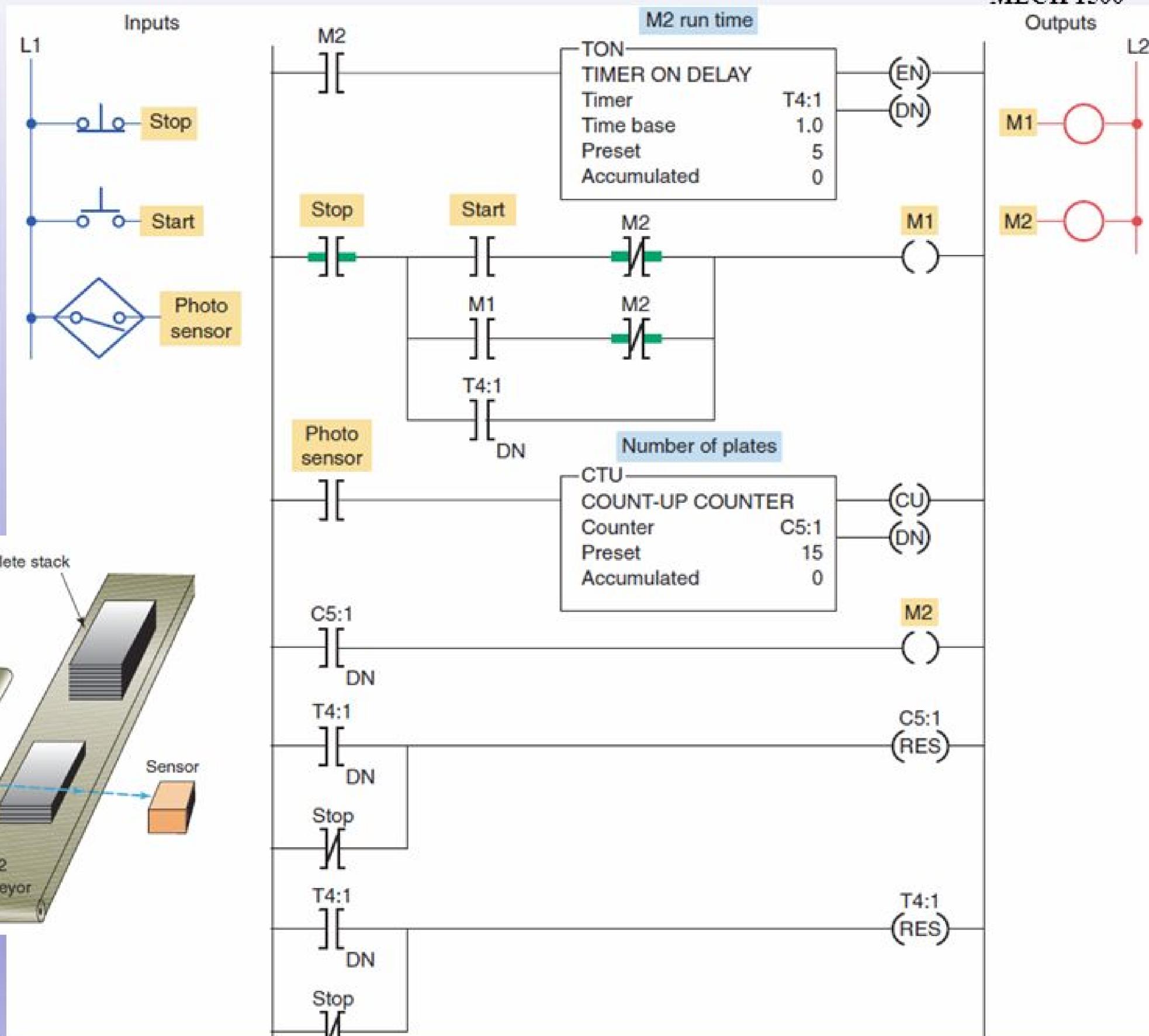
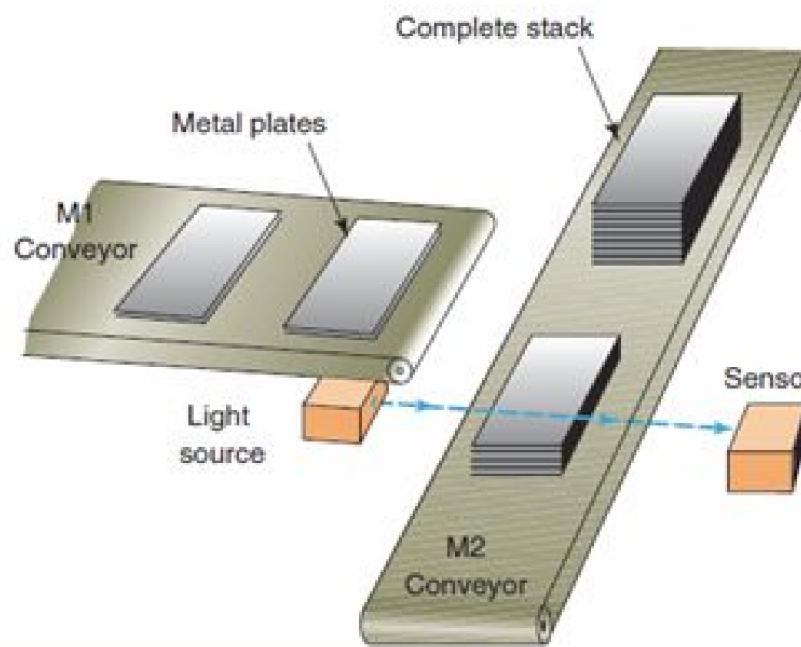


# 8.6

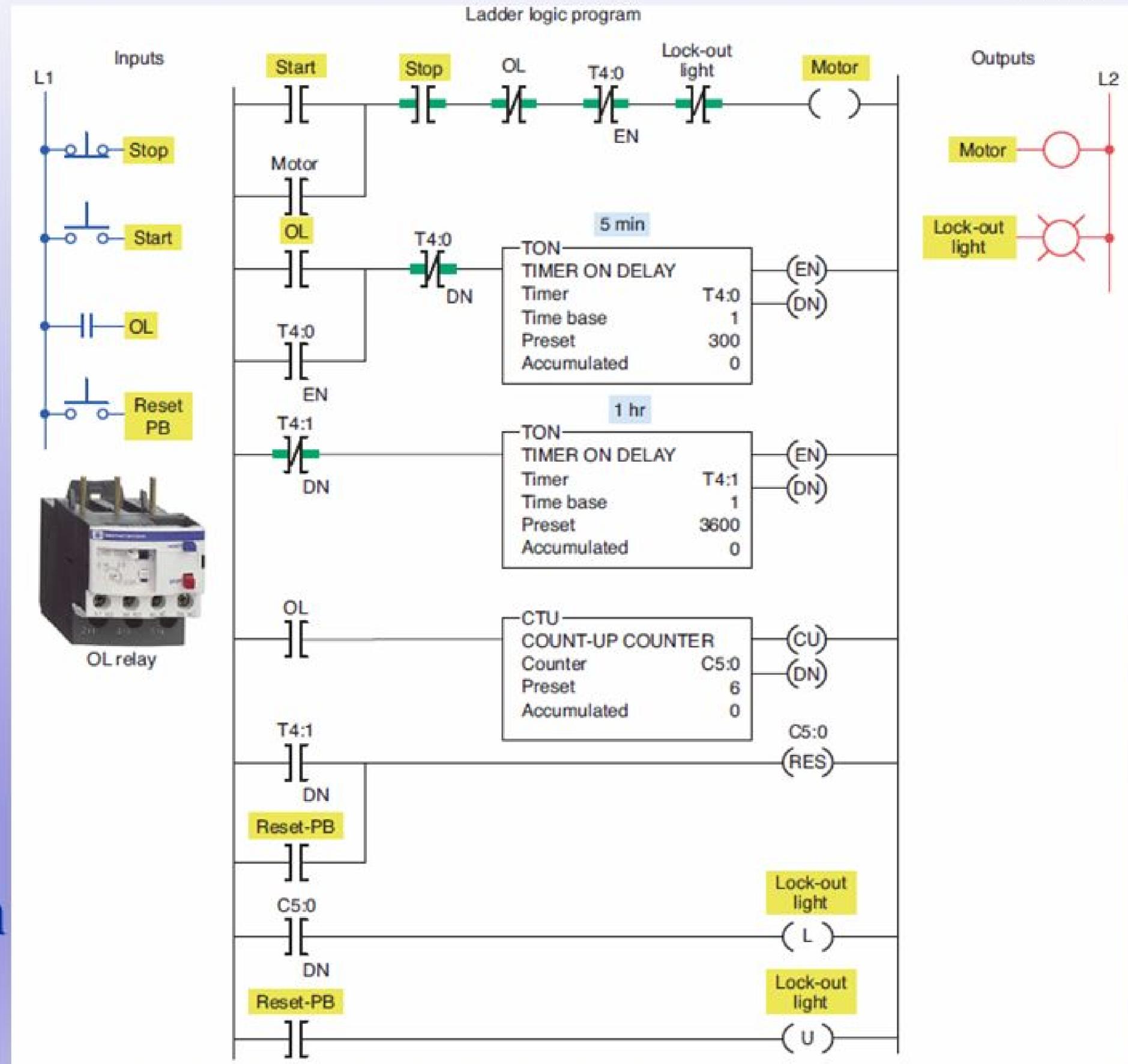


# Combining Counter and Timer Functions

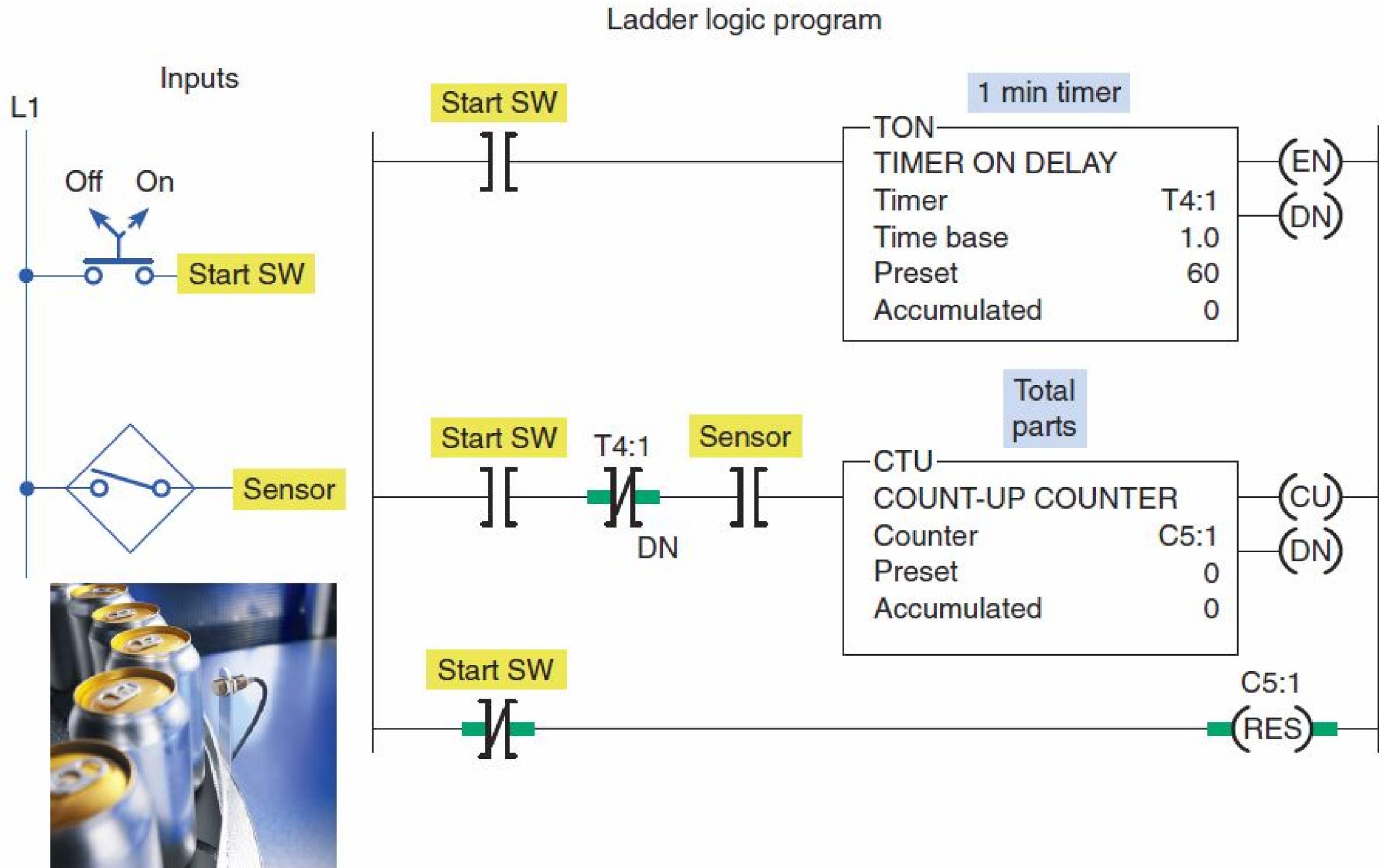
# Automatic stacking program



# Motor lock-out program



# Product flow rate program.



# Timer driving a counter to produce an extremely long time-delay period.

