

Introduction to Control System (Control Panel)



Start & Stop
Operation

What is inside the control panel?



Contactors, relays, timers & counters
in the control panel

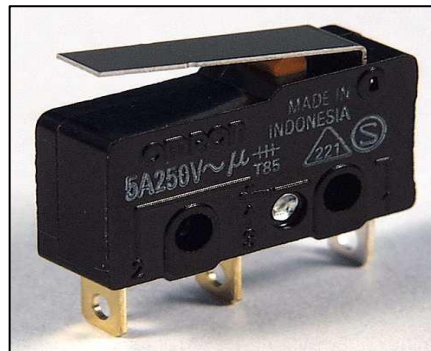
Input Devices



Photoelectric Switch



Rotary Encoder



Limit Switch

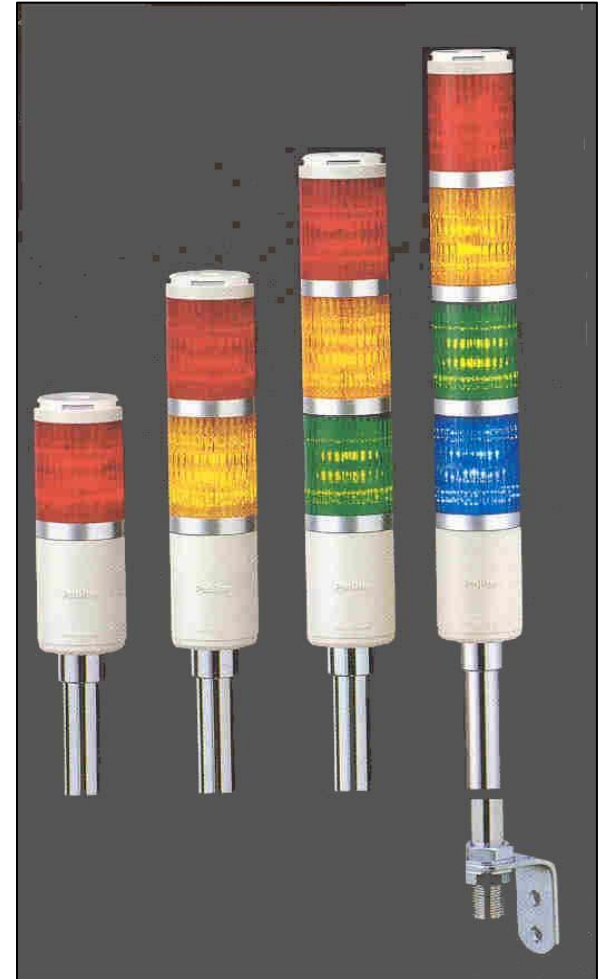


Proximity Switch

Output Devices

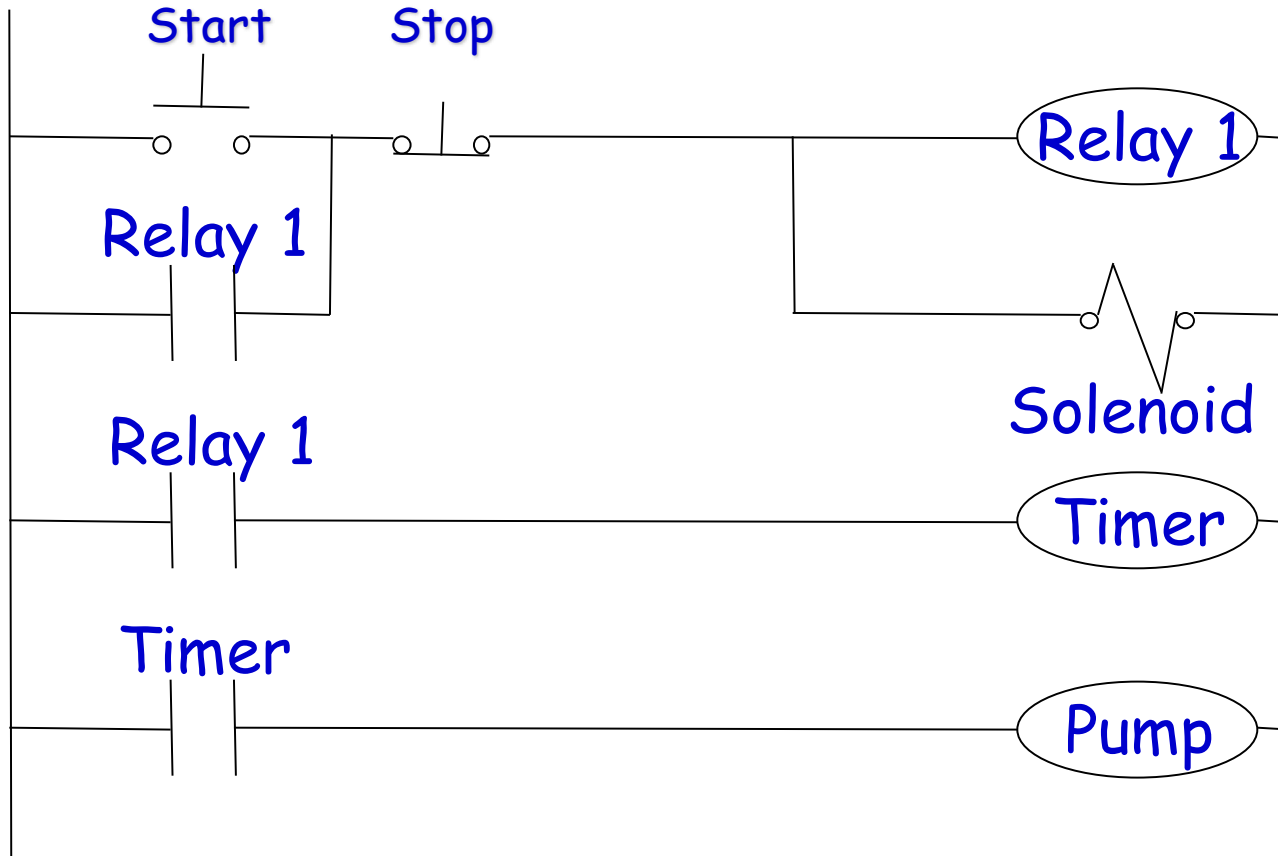


**7-segment Display
Unit**

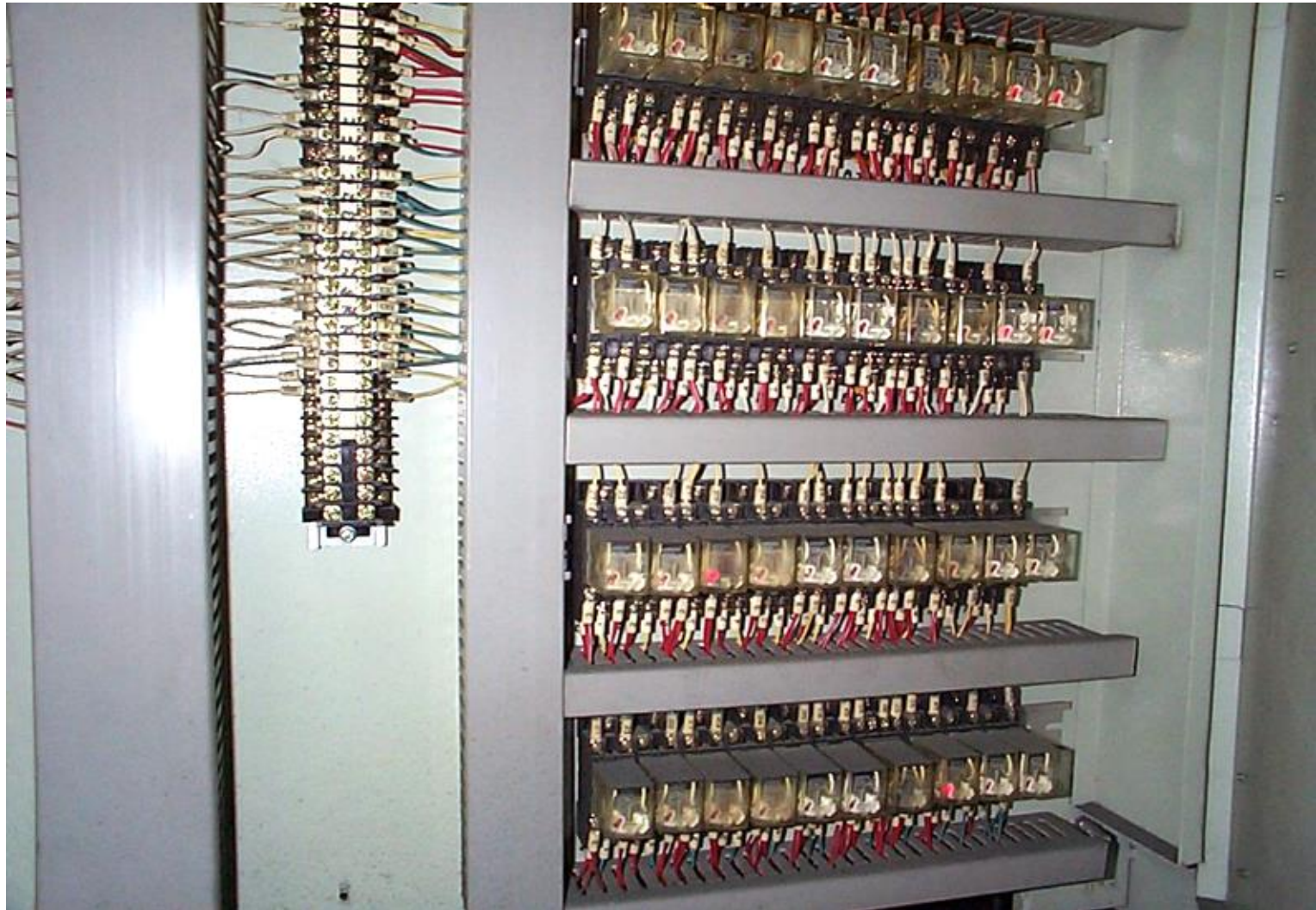


Tower Light

Conventional Hardwire Logic Circuit



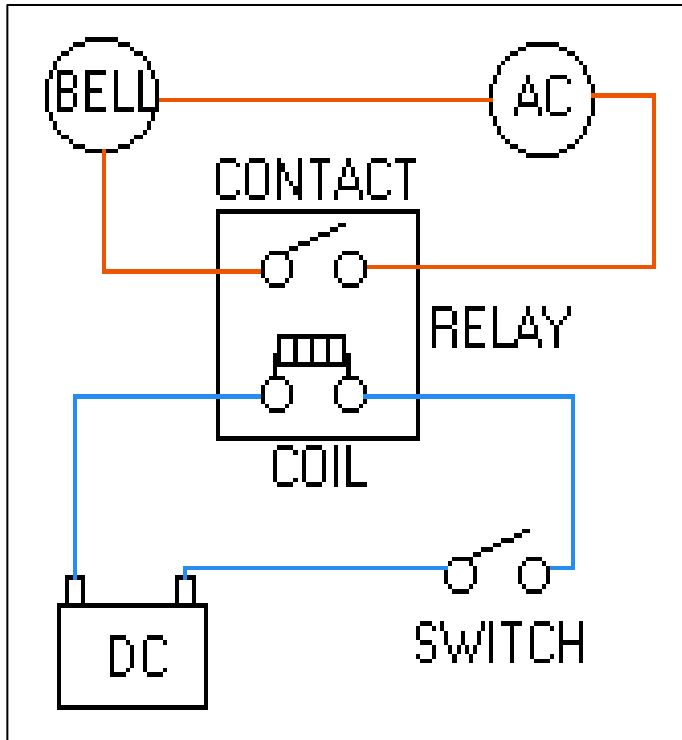
Conventional Relay Control Panel



Introduction: What is a PLC?

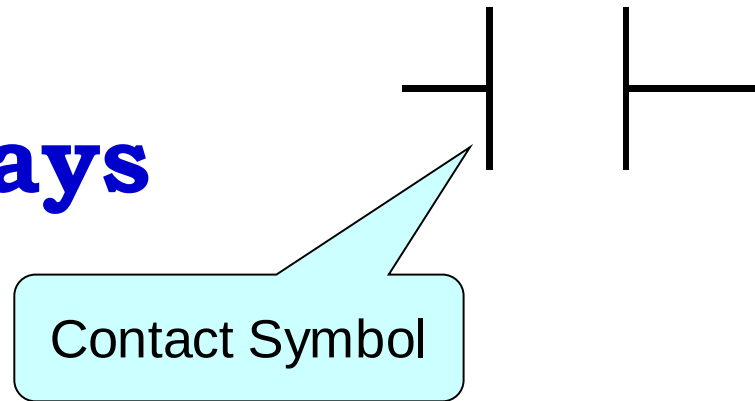
- A PLC is a device that was invented to replace the necessary sequential relay circuits for machine control.
- The PLC works by monitor its inputs and depending upon their state, turning on/off its outputs.
- The user enters a program, usually via software, that gives the desired results.

Relay



- Relay is an electromagnetic switch.
- Applying voltage to the coil will generate magnetic field.
- This magnetic field sucks the contacts of the relay in, causing them to make a connection.
- These contacts can be considered as a switch.

Replacing Relays

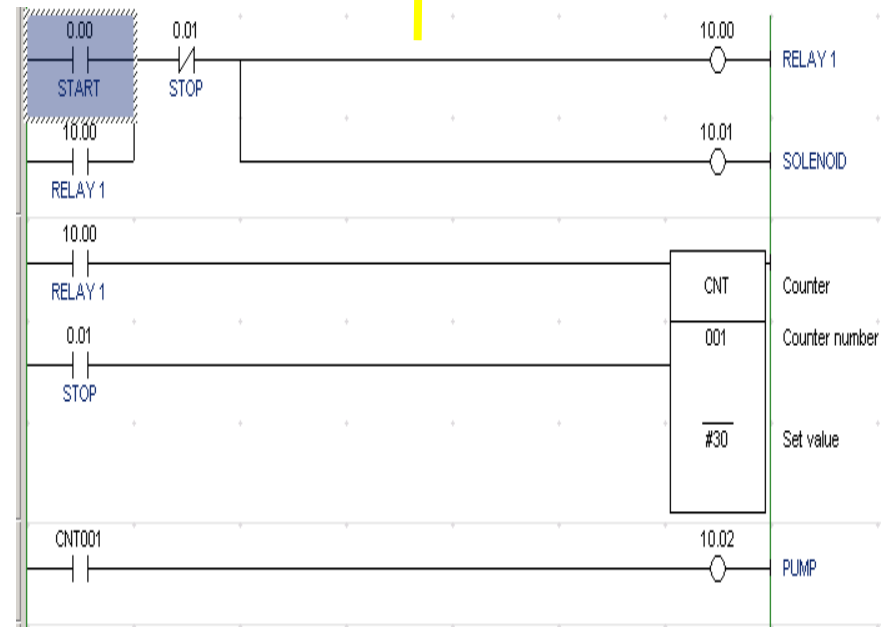
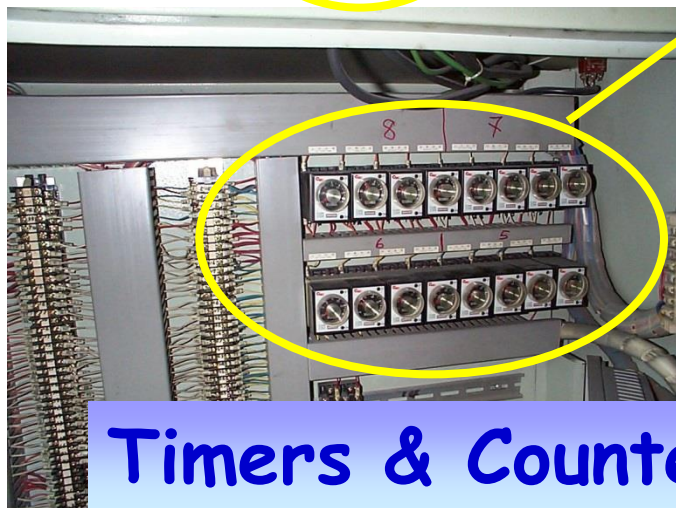
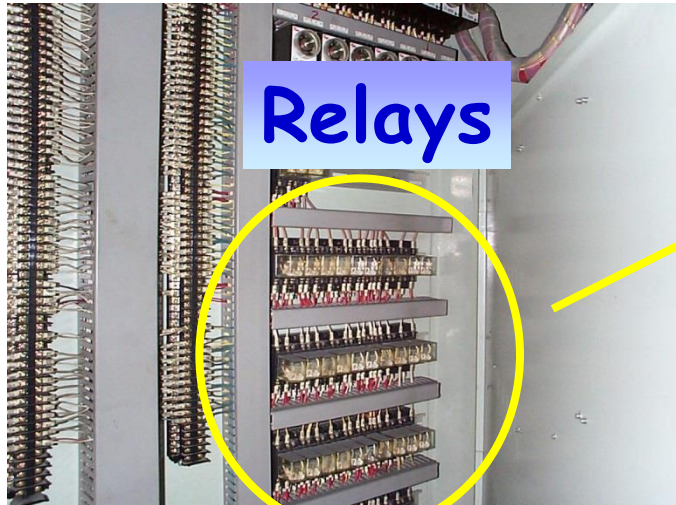


- The main purpose of PLC is to replace relays.
- Relay based control system is designed using **Ladder diagram**.
- CX-Programmer is the software used to convert ladder diagram into PLC mnemonic code.
- PLCs use input, output coil and contact instead of switch, relay, motor etc.
- Bus bar is two vertical bars common to all ladder diagram.

PLC History

- ❑ In the late 1960's PLCs were first introduced to replace complicated relay based control systems.
- ❑ In 1970's, the dominant PLC technologies were sequencer state-machines. Communications abilities began to be introduced for PLCs.
- ❑ In 1980's, an attempt to standardize communications with Manufacturing Automation Protocol(MAP).
- ❑ In 1990's, an attempt to standardize PLC programming languages under one international standard: IEC 1131-3.

1. Sequence Control

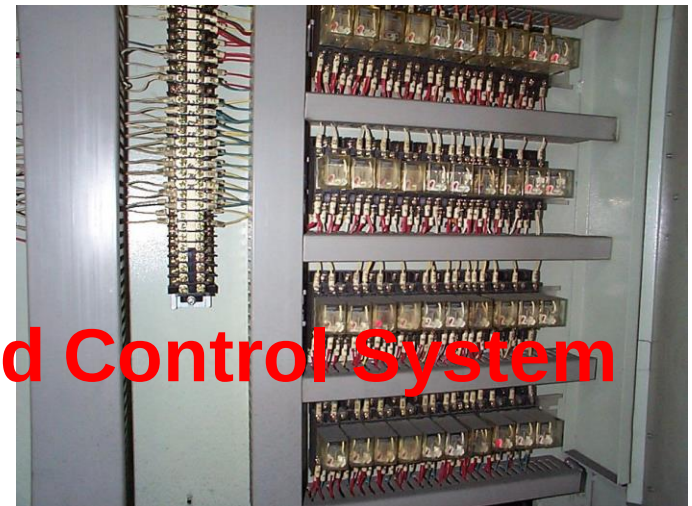


Positioning Control with PLC



The advantages of Using PLC

- ❑ Smaller physical size than hard-wire solutions.
- ❑ Easier and faster to make changes.
- ❑ Diagnostics are centrally available.
- ❑ Applications can be immediately documented.
- ❑ Applications can be duplicated faster and less expensively.
- ❑ Fast project implementation time
- ❑ Low operating cost
- ❑ Increase productivity



PLC Vs Relay Based Control System

Control Device

Wired Logic



Specific Purpose

Control sequence is fixed for one design

PLC

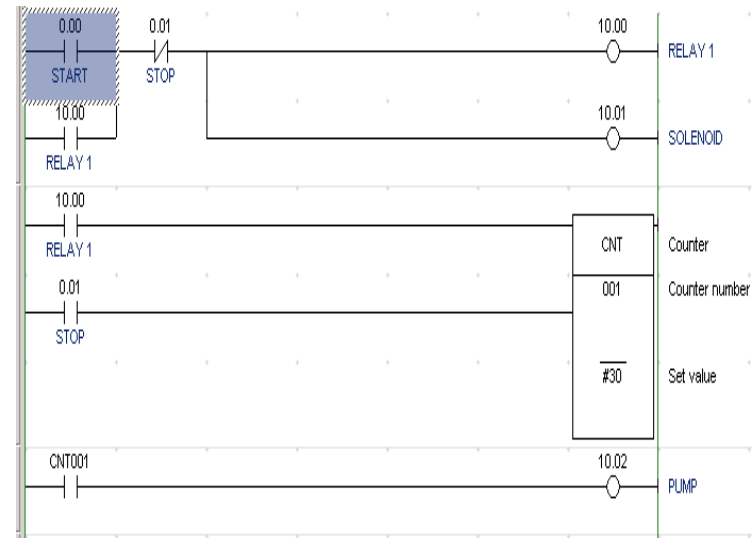
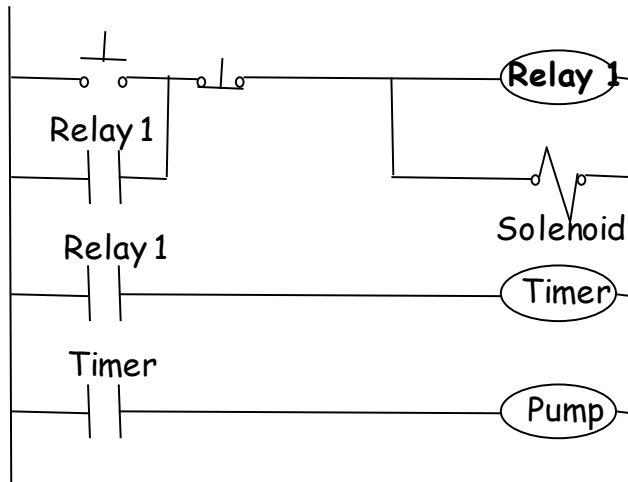


General Purpose

Control sequence can be changed from time to time without rewire

Modification

An example for hard wire logic



Mnemonic Code

For PLC:-

Modification by only to change the ladder program.

For hardwired logic:-

Modification by rewired all the things.

LD		START
OR		RELAY 1
AND	NOT	STOP
OUT		RELAY1
OUT		SOLENOID
LD		RELAY 1
TIM		000
	#0020	
LD	TIM	000
OUT		PUMP

Delivery Period

Several days



Wired Logic

Almost Immediate

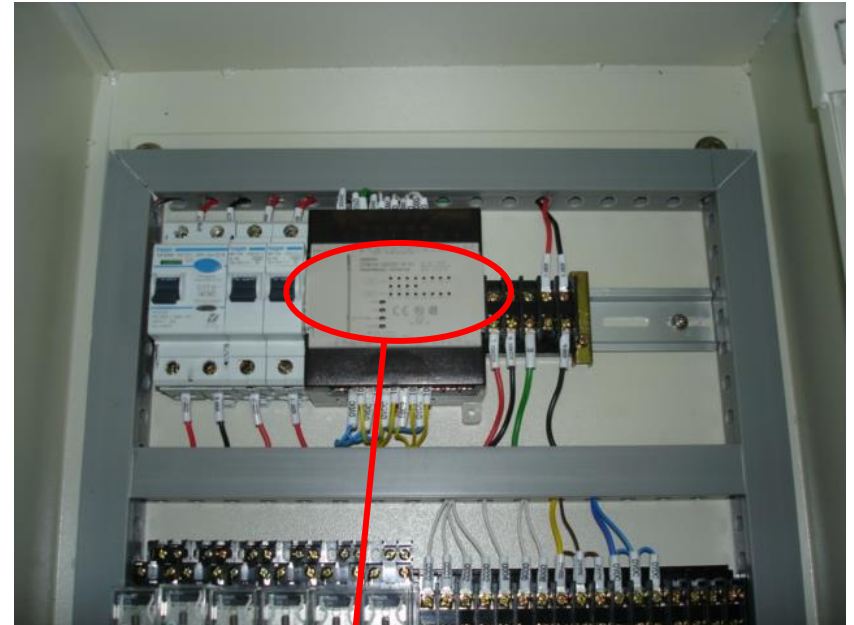
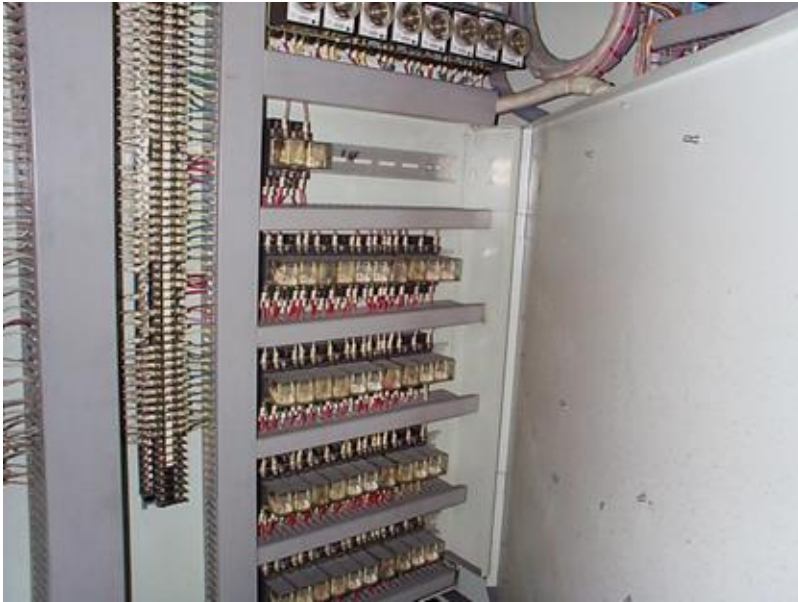


PLC

Maintenance

Easy

Difficult



LED indicator

How ?

Wired Logic

Input/output connector
can be remove easily

PLC

Economic Efficiency

Advantage on
small scale



Wired Logic

Advantage on
small, medium
and large

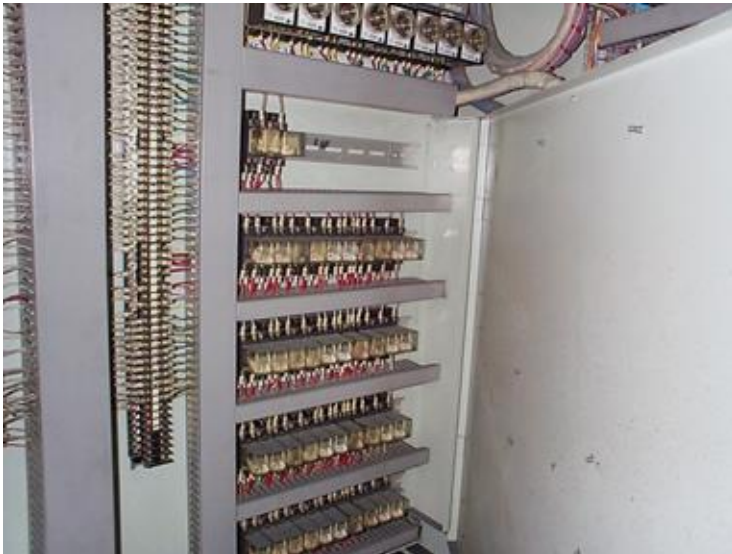


PLC



Power Consumption

High



> 2 Amp

Wired Logic

Low

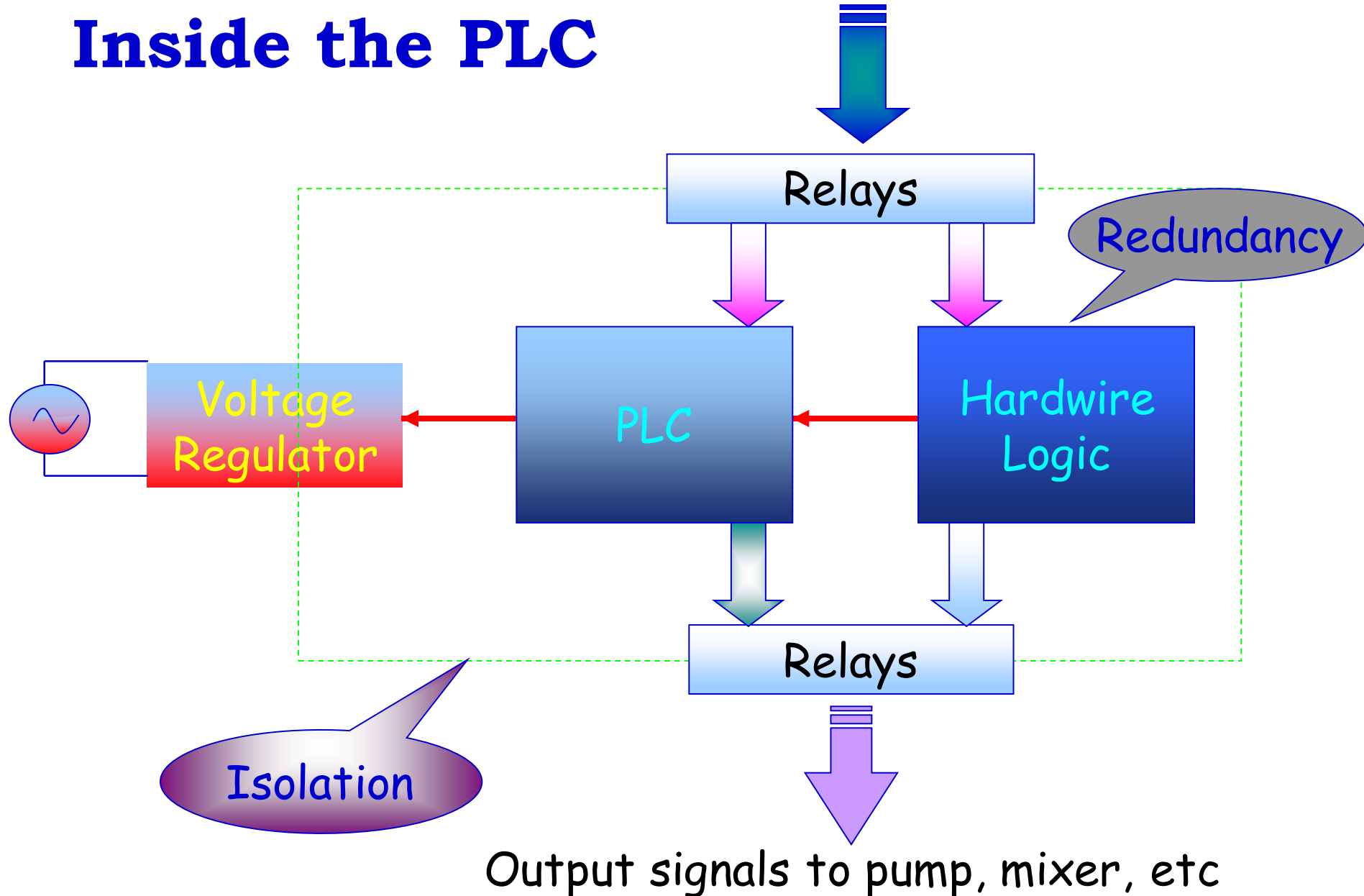


0.2 Amp

PLC

Input signals from sensors, switches, etc

Inside the PLC



Inside the PLC

- **Input Relays** - (contacts)
 - connected to the outside world
 - physically exist and receive signals from switches, sensors, etc..
- **Internal Relays** - (contacts)
 - do not receive signals from the outside world nor do they physically exist
 - simulated relays and are what enables a PLC to eliminate external relays
 - also some special relays that are dedicated to performing only one task

Inside the PLC

□ **Counters**

- do not physically exist
- simulated counters and they can be programmed to count pulses
- limited in their counting speed
- high-speed counters that are hardware based

□ **Timers**

- do not physically exist
- on-delay and off reset
- increments vary from 10ms through 100ms

Inside the PLC

□ **Output Relays** (coils)

- connected to the outside world
- physically exist and send on/off signals to solenoids, lights, etc
- can be transistors, relays, or triacs depending upon the model chosen

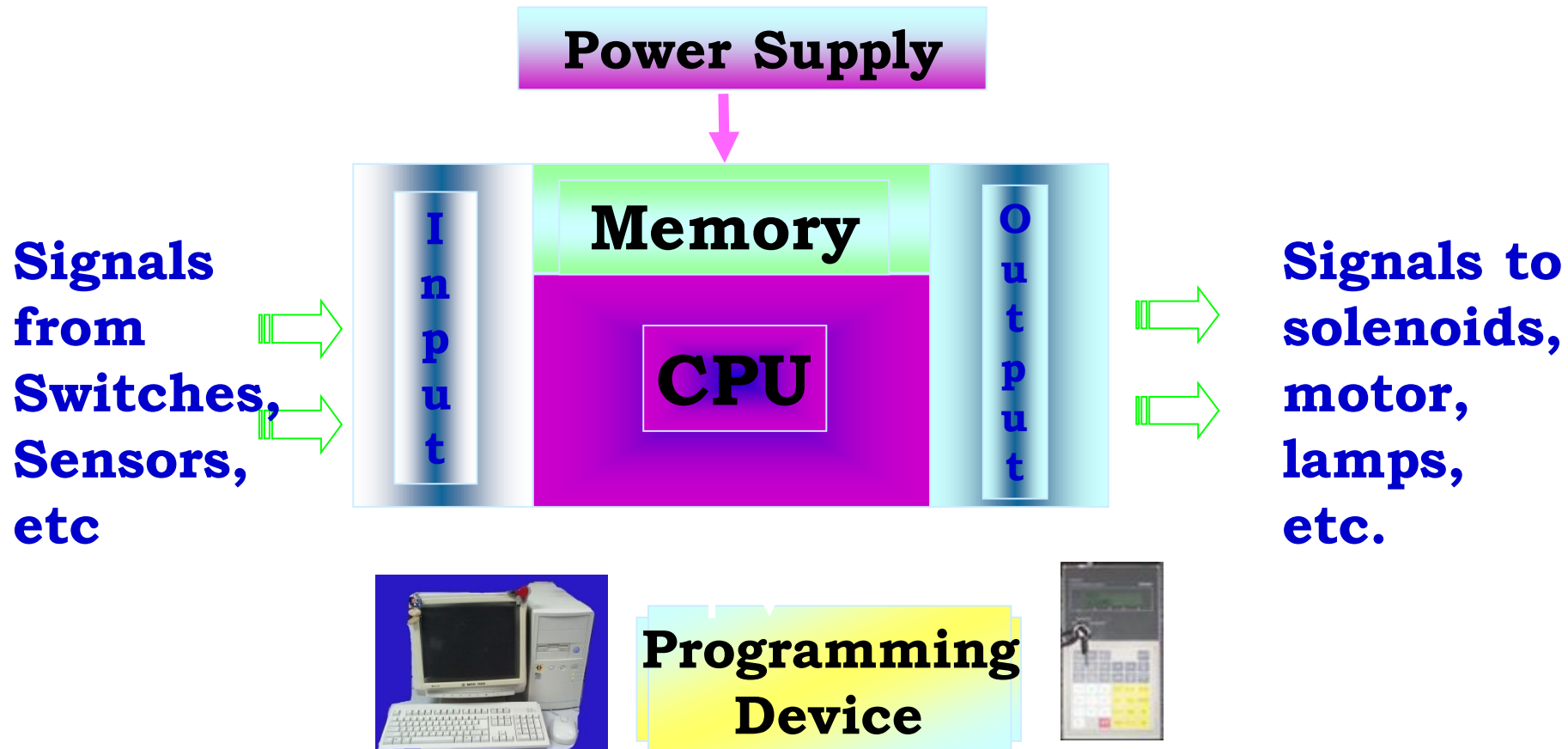
□ **Data Memory**

- registers assigned to store data for math or data manipulation
- can also typically be used to store data when power is removed from the PLC

Types of Memory

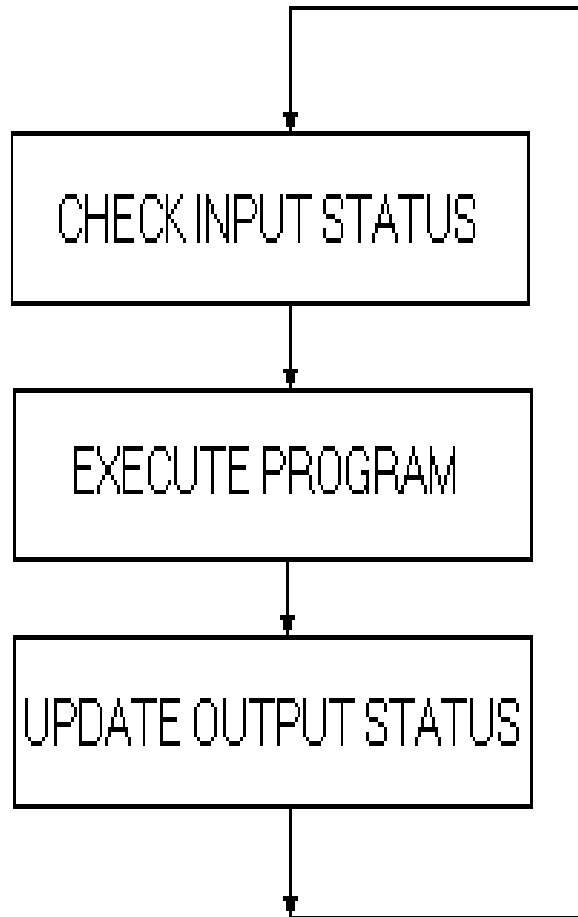
- ROM: Read Only Memory
 - RAM: Temporary storage area, need battery backup
 - EPROM: Erasable Programmable Read Only Memory
 - EEPROM: Electrical Erasable Programmable Read Only Memory
- ◆ Note :Battery is used for backup the data in the RAM in PLC when Power Off

How PLC Work?



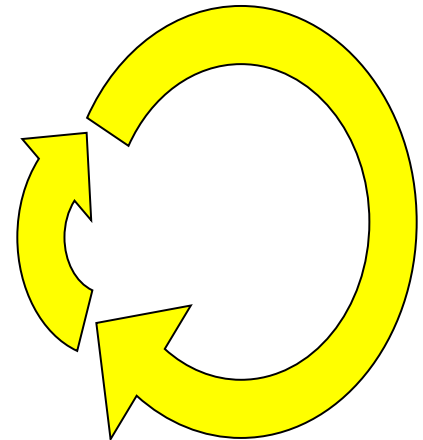
A PLC monitors inputs, makes decisions based on its program, and controls outputs to automate a process or machine.

How PLC Work?

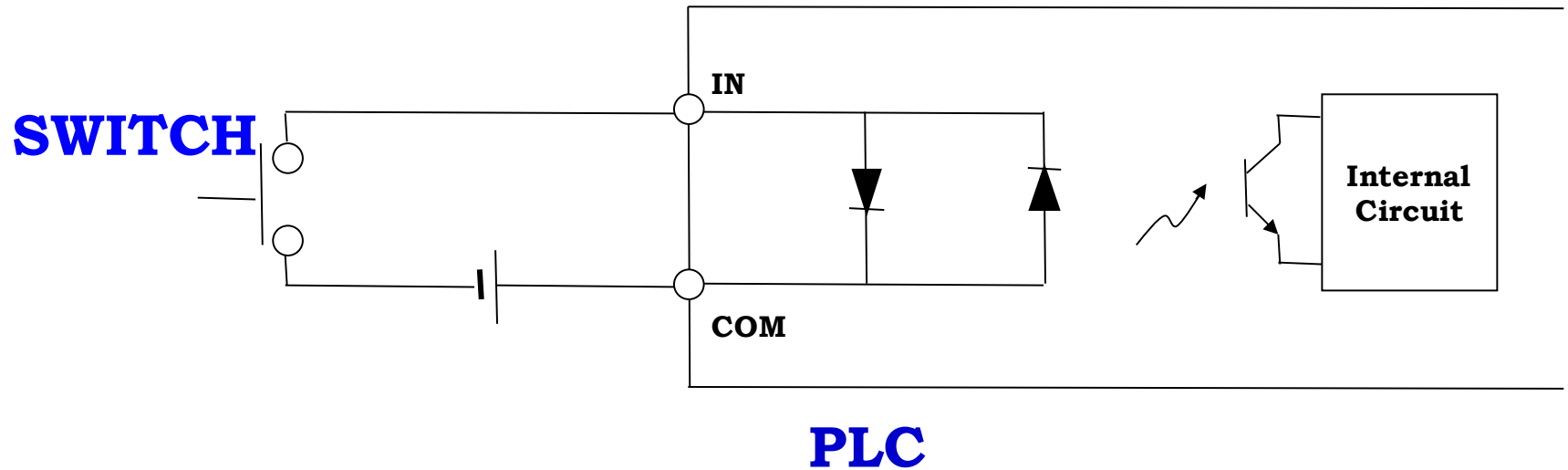


Response Time (Scan Time)

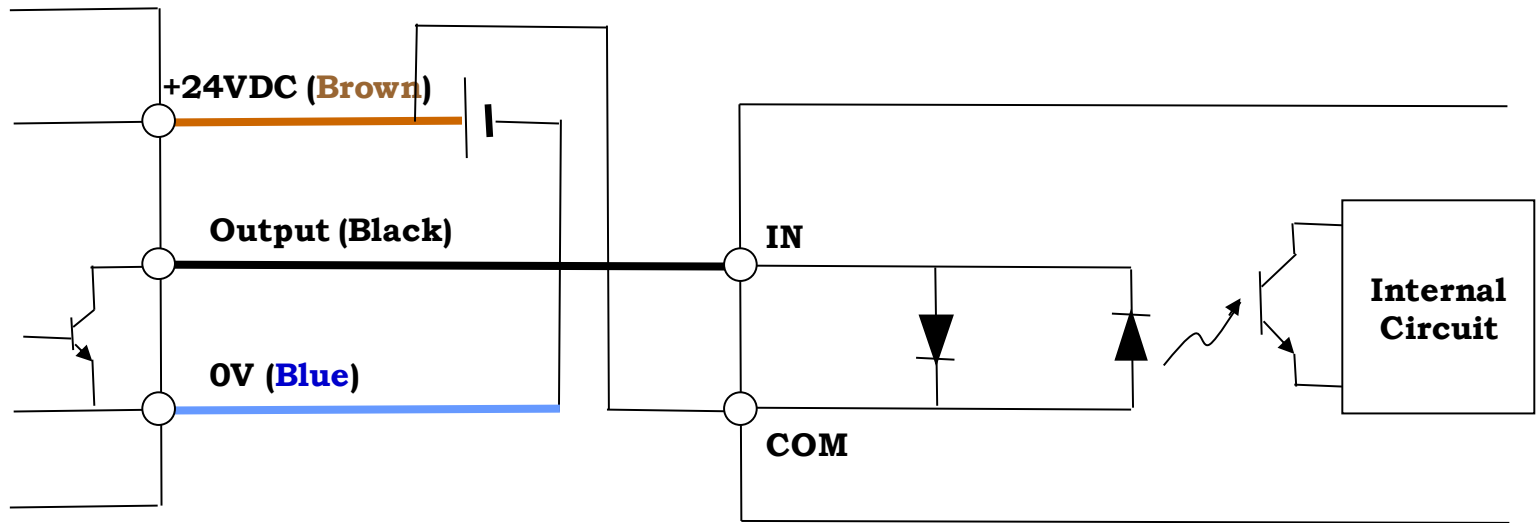
- Just like our brains, the PLC takes a certain amount of time to react to changes
- Total PLC Response Time is a summation of
 - Input Response Time
 - Program Execution Time
 - Output Response Time
- Factor Influence Scan Time
 - 1) CPU speed
 - 2) Length/Size of program
 - 3) Number of I/O
 - 4) Remote I/O sub-system



Input Wiring (Switch & PLC)



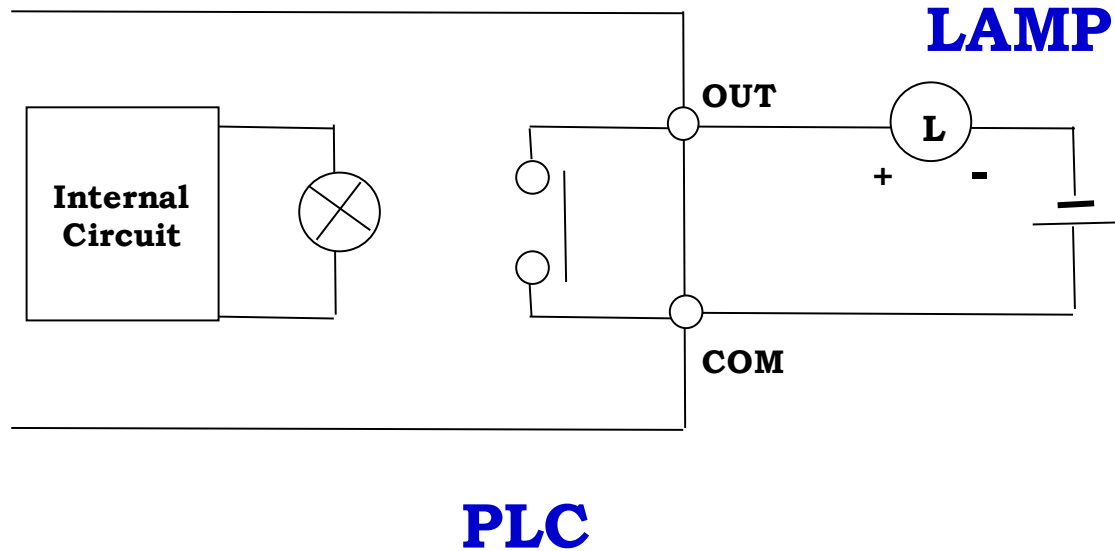
Input Wiring (Sensor & PLC)



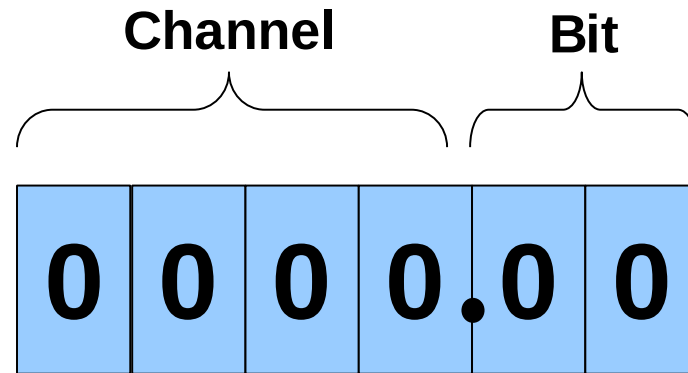
24VDC
NPN
SENSOR

PLC

Output Wiring (Lamp & PLC)



PLC I/O Addressing



1 Channel / 1 Word = 16 Bits

i.e.: Input: 000.00, 000.01, 000.02,000.14, 000.15,
Output: 100.00, 100.01,100.15

CPU Status Indicators

Indicator	Status	Meaning
PWR (Green)	ON OFF	Power supply to PLC Power not supply to PLC
RUN (Green)	ON OFF	RUN or MONITOR mode PROGRAM mode or Fatal Error occurred
ERR/ALM (Red)	ON Flash OFF	Fatal Error (PLC operation stops) Non-fatal Error (PLC operation continue) CPU unit operate normally
COMM (Green)	ON OFF	Data being transfer Data not being transfer
PRPHL (Green)	ON OFF	Data being transfer via Peripheral Port Data not being transfer via Peripheral Port
BKUP (Yellow)	ON OFF	Access Backup Memory Not access Backup Memory
INH (Yellow)	ON OFF	Output OFF Bit turn On Output OFF Bit turn Off

PLC Programming Tools

CX-Programmer Software



PLC Operating Mode

1) PROGRAM Mode...

- Programs are not executed.
- Used for inserting or modification existing program.

2) MONITOR Mode...

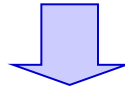
- Programs are executed.
- Online editing, and changes to present value in I/O memory, are enabled in this mode.

3) RUN Mode...

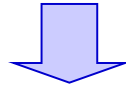
- Programs are executed. (No changes can be made)

History of Omron Software Tools for PLC Programming

LSS, Ladder Support Software (DOS)

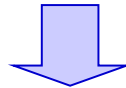


SSS, Sysmac Support Software (DOS)



SYSWIN Ver 3.4

(16 bit Windows Application)



CX-Programmer

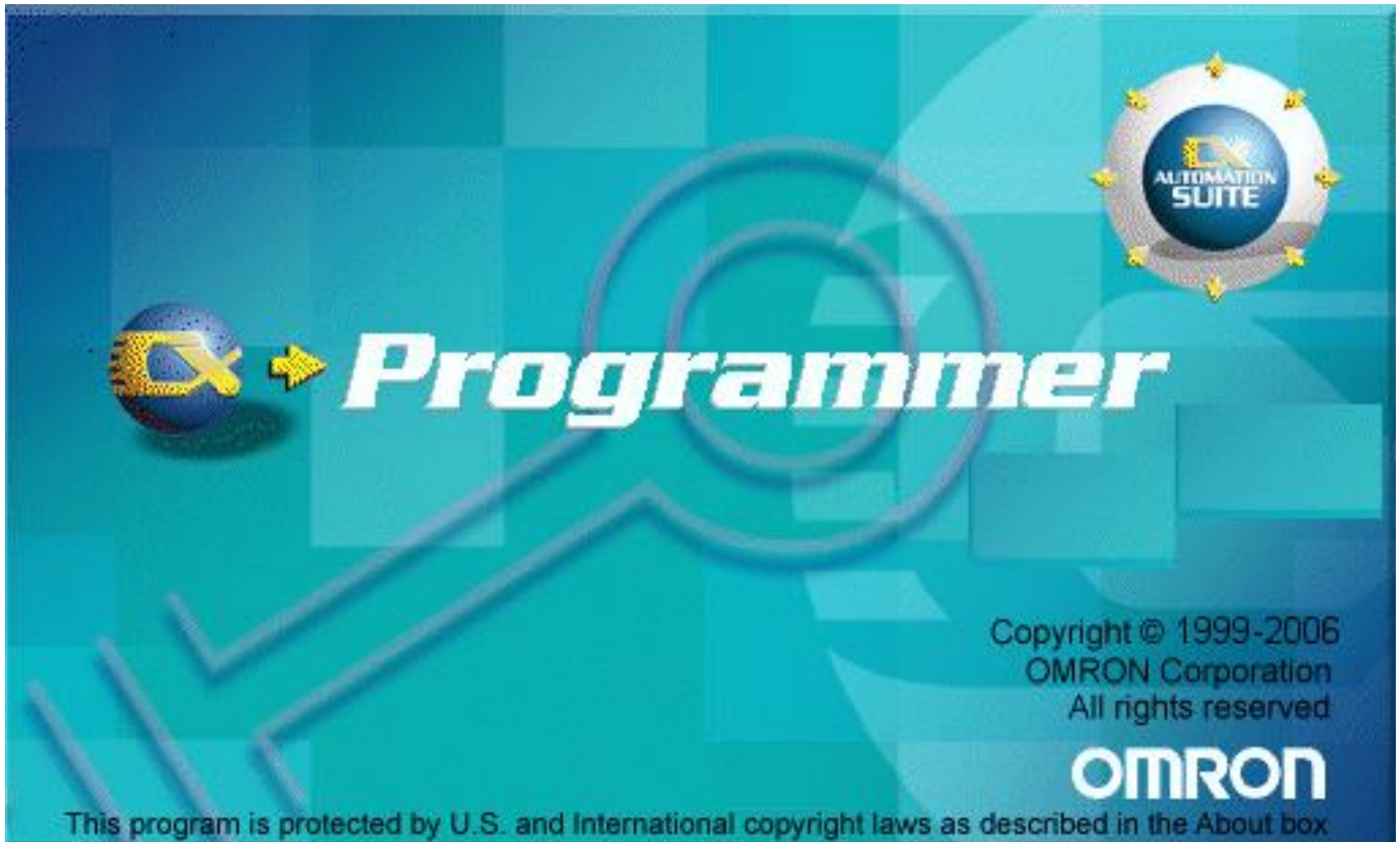
(32 bit Windows Application)

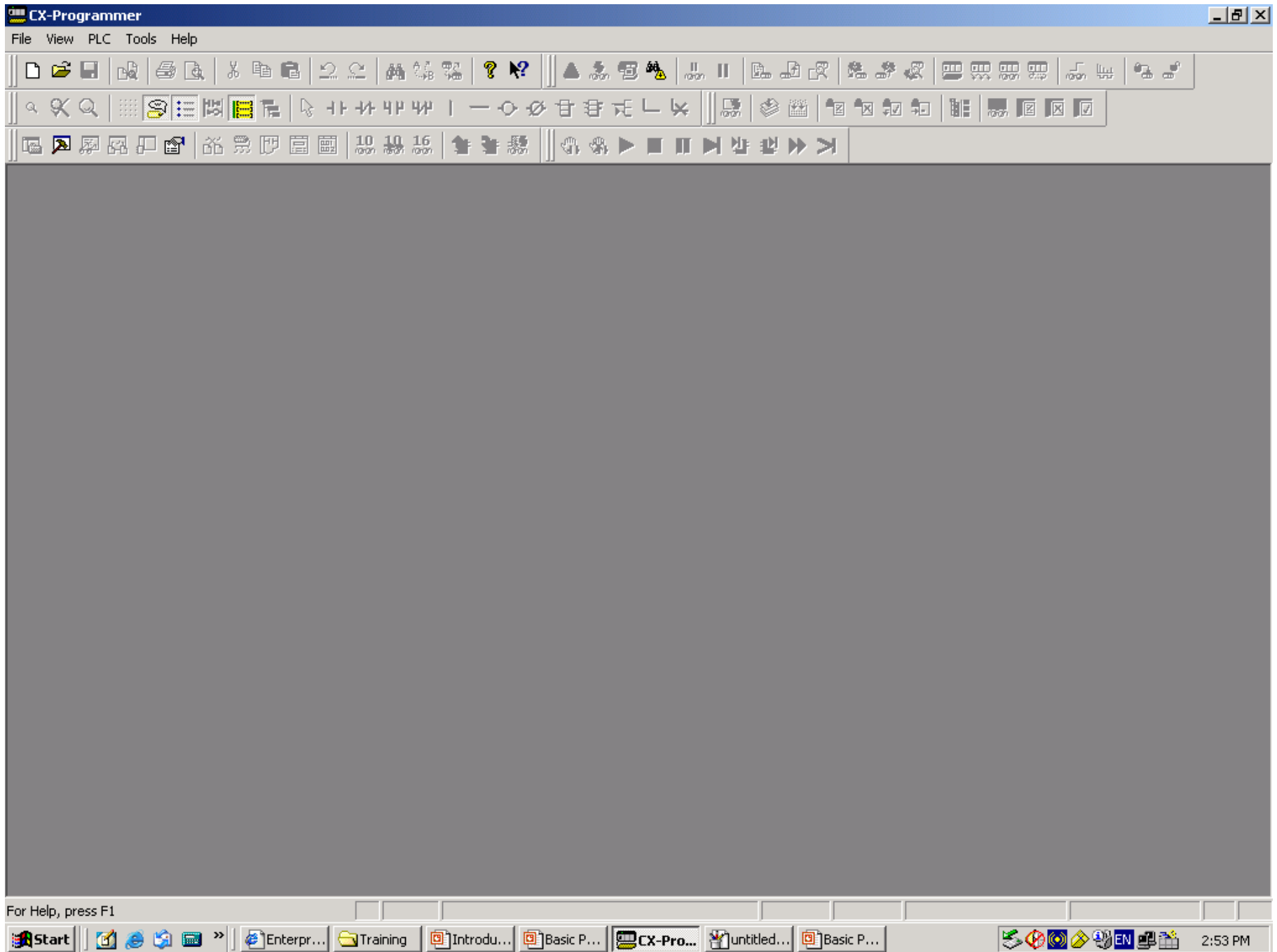
Now CX-Programmer is included in CX-One

CX-Programmer Features

- ★ Programming in Ladder, Mnemonic Code or Function Block
- ★ Multiple window display
- ★ On-line editing and monitoring
- ★ Extensive I/O and comment documentation
- ★ Communications support for ToolBus, SYSMACWAY, Ethernet, USB, etc.

Get Started





Set PLC Model & CPU Type

Change PLC

Device Name
NewPLC1

Device Type
CP1L Settings...

Network Type
USB Settings...

Comment

OK Cancel Help

Device Type Settings [CP1L]

General

CPU Type
L

Total Program Area Size
5K [Step] ☐ Read Only

Expansion Memory
None ☐ Read Only

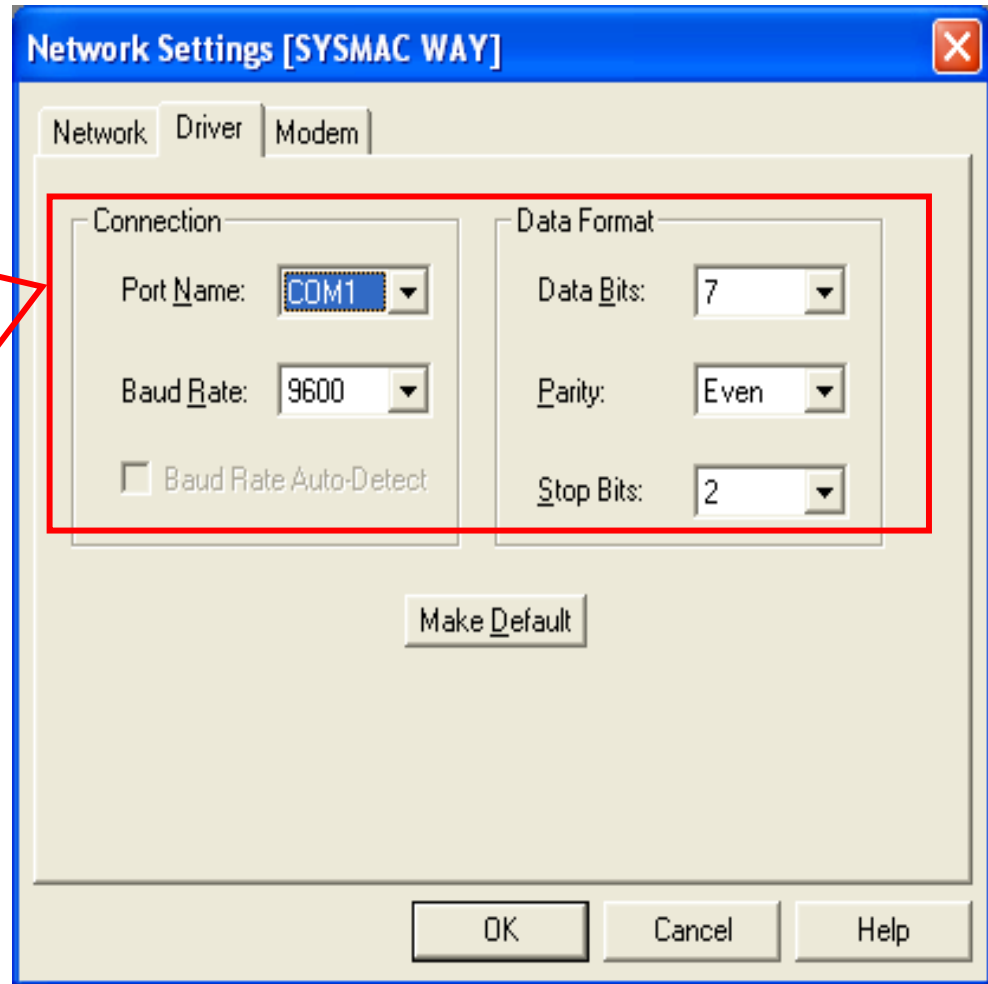
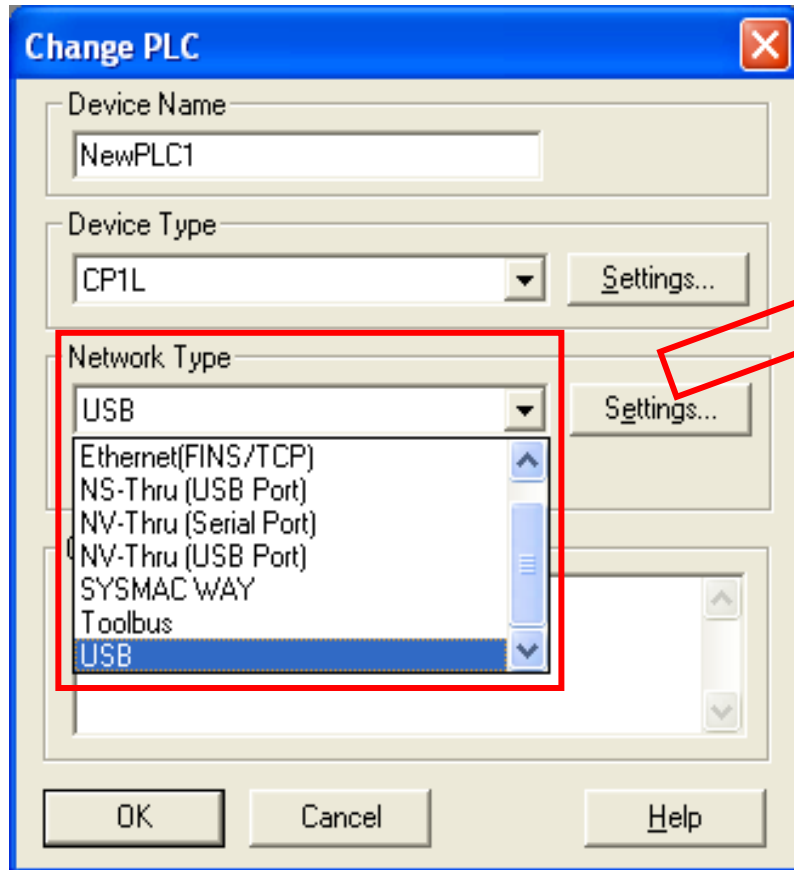
File Memory
None ☐ Read Only

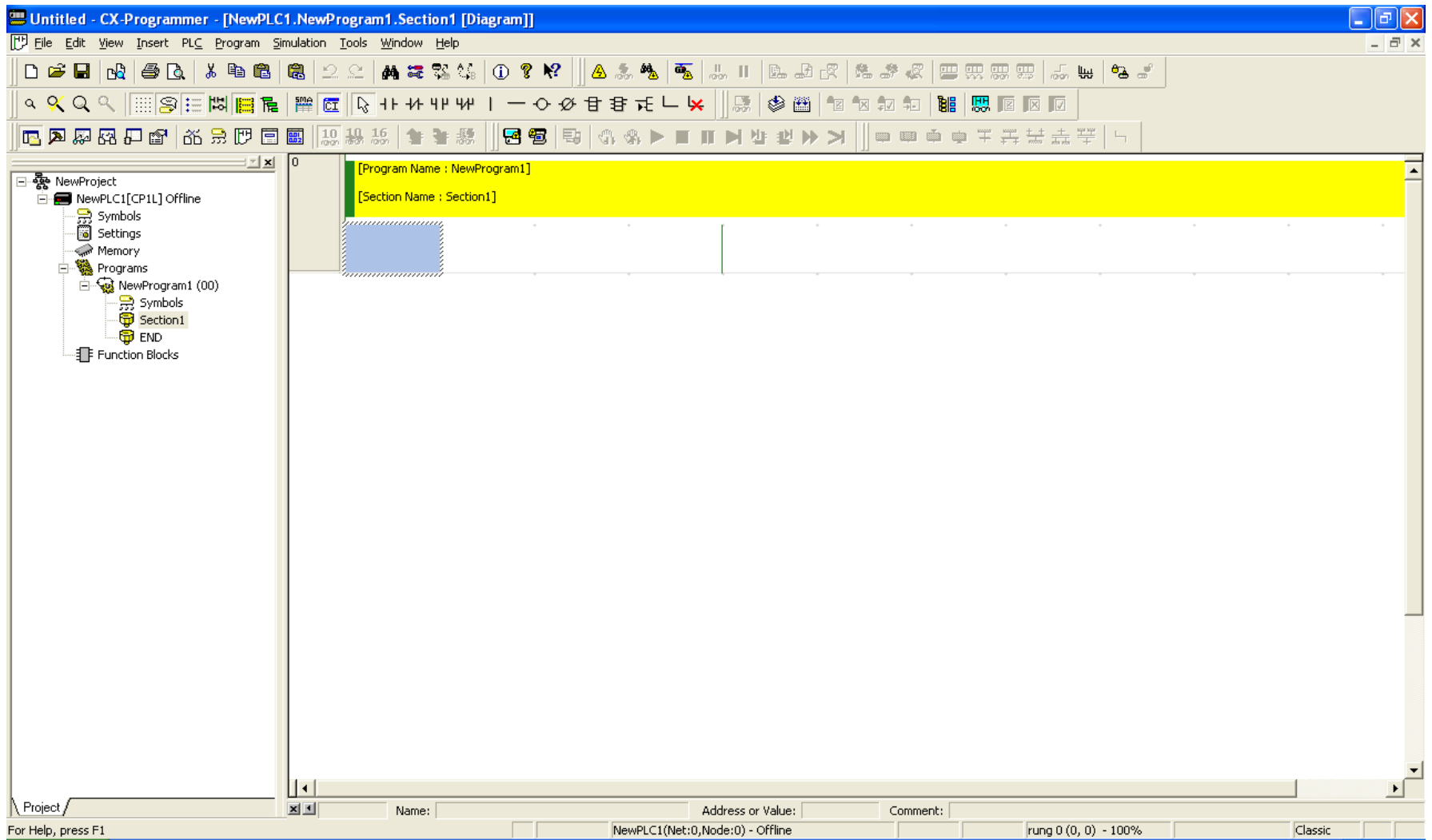
Timer / Clock
☒ Installed

Make Default

OK Cancel Help

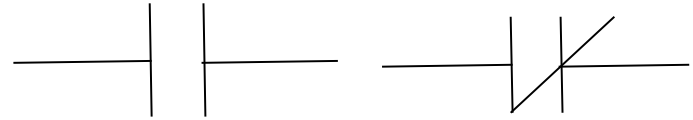
Set Communication Interface



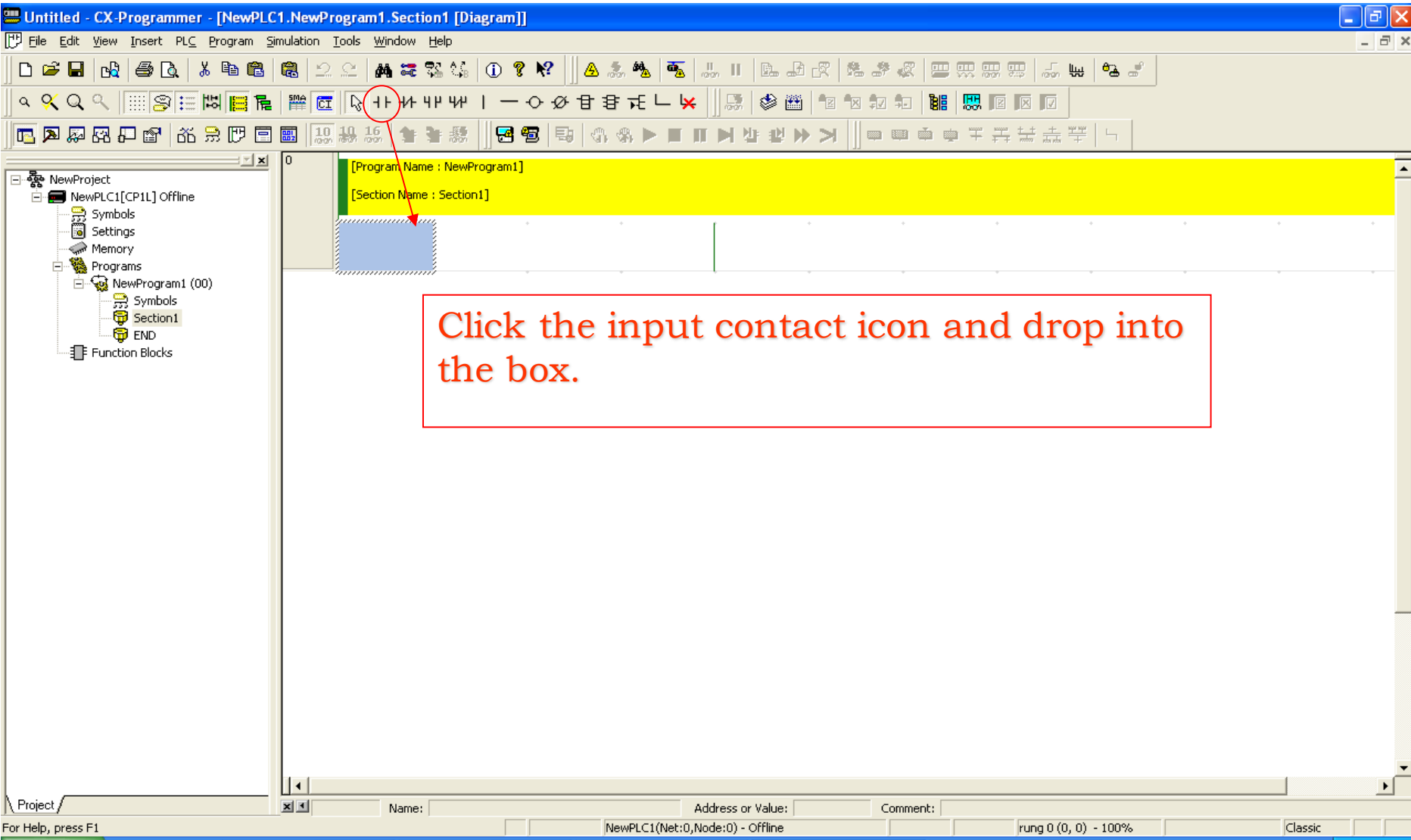


Simple Circuit for First Trial

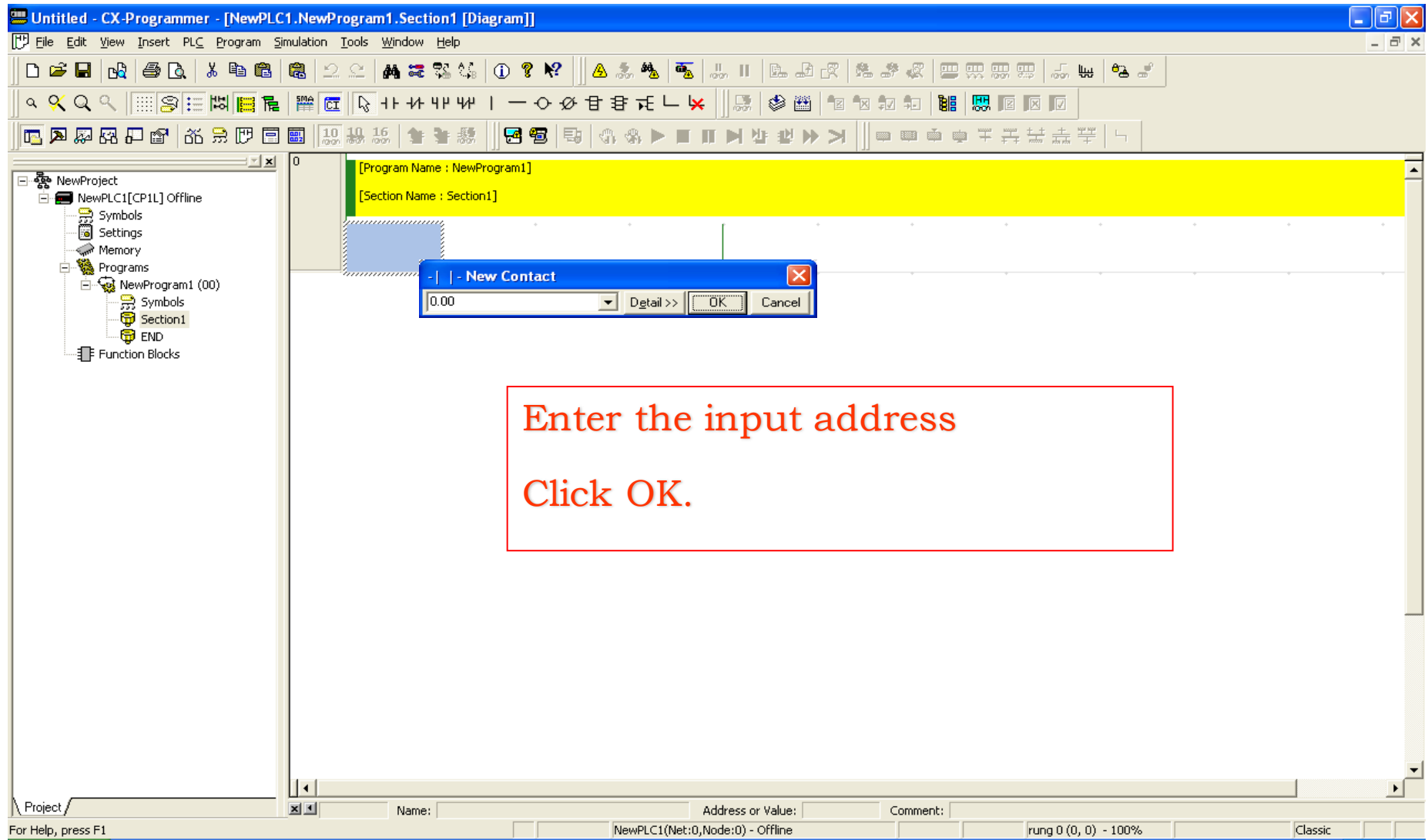
LD / LD NOT

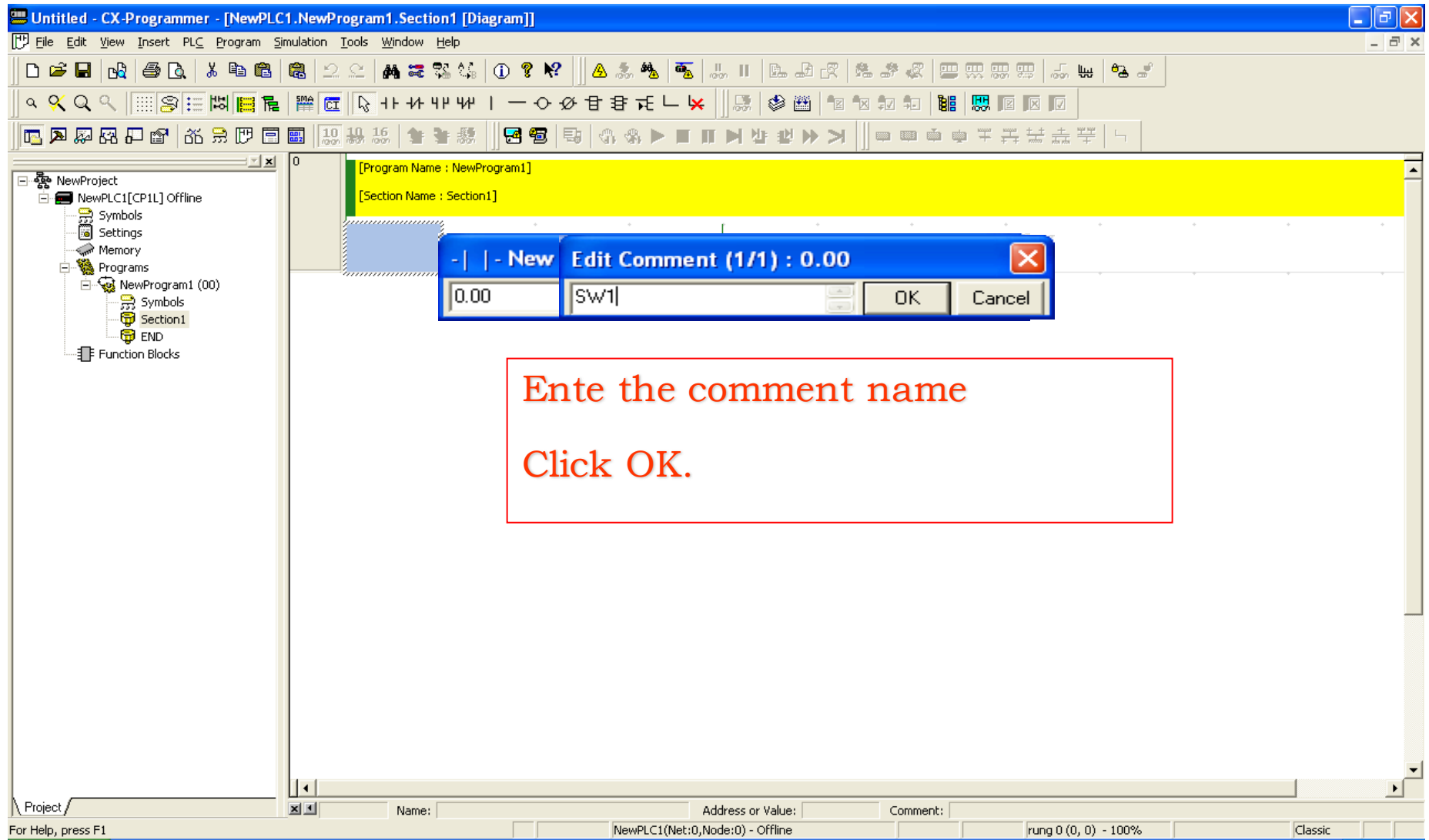


- The first condition that starts any logic block within a ladder diagram corresponds to a LD or LD NOT instruction.
- LD - Normally Open contact, examine if On
- LD NOT - Normally Close contact, examine if Off

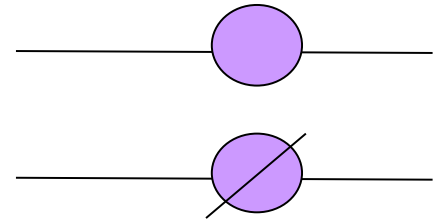


Click the input contact icon and drop into the box.





OUT / OUT NOT



- The OUT instruction is like a relay coil.
- When there is a path of True instruction preceding this on the ladder rung, it will also be True.
- When the instruction is True it is physically On.
- We can think of this instruction as a normally open output.
- This instruction can be used for internal coils and external outputs.
- The OUT NOT instruction is the reverse logic of OUT instruction.

Untitled - CX-Programmer - [NewPLC1.NewProgram1.Section1 [Diagram]]

File Edit View Insert PLC Program Simulation Tools Window Help

0 [Program Name : NewProgram1]
[Section Name : Section1]

I: 0.00
SW1

1

Click the output icon and drop into the box.

Project

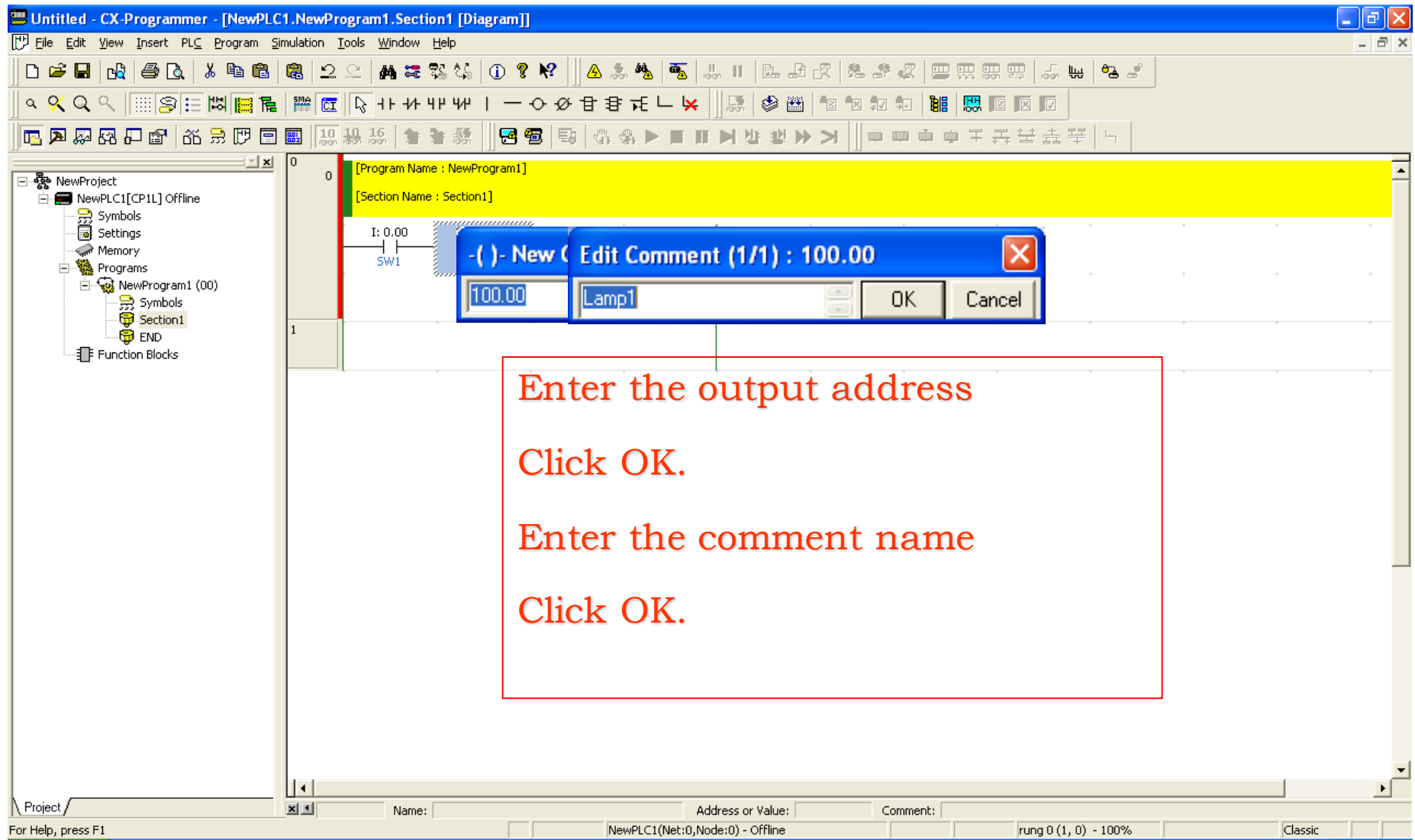
Name: Address or Value: Comment:

NewPLC1(Net:0,Node:0) - Offline

rung 0 (1, 0) - 100%

Classic

For Help, press F1



END (01)

- The last instruction required to complete a simple program is the END instruction.
- When the CPU scan the program, it executes all instructions up to the first END instruction before returning to the beginning of the program and begin the execution again.



Untitled - CX-Programmer - [NewPLC1.NewProgram1.Section1 [Diagram]]

File Edit View Insert PLC Program Simulation Tools Window Help

NewProject

NewPLC1[CP1L] Offline

Symbols

Settings

Memory

Programs

NewProgram1 (00)

Symbols

Section1

END

Function Blocks

0

0

1

[Program Name : NewProgram1]

[Section Name : Section1]

I: 0.00

Q: 100.00

SW1

Lamp1

Rung Number

Step Number

Project

Name:

Address or Value:

Comment:

NewPLC1 (Net:0,Node:0) - Offline

rung 0 (0, 1) - 100%

Classic

Rung Number

Step Number

**A simple PLC program
completed!**

Untitled - CX-Programmer - [[Running]] - NewPLC1.NewProgram1.Section1 [Diagram]

File Edit View Insert PLC Program Simulation Tools Window Help

0 [Program Name : NewProgram1]
[Section Name : Section1]

I: 0.00 Q: 100.00
SW1 Lamp1

PLC at On-line

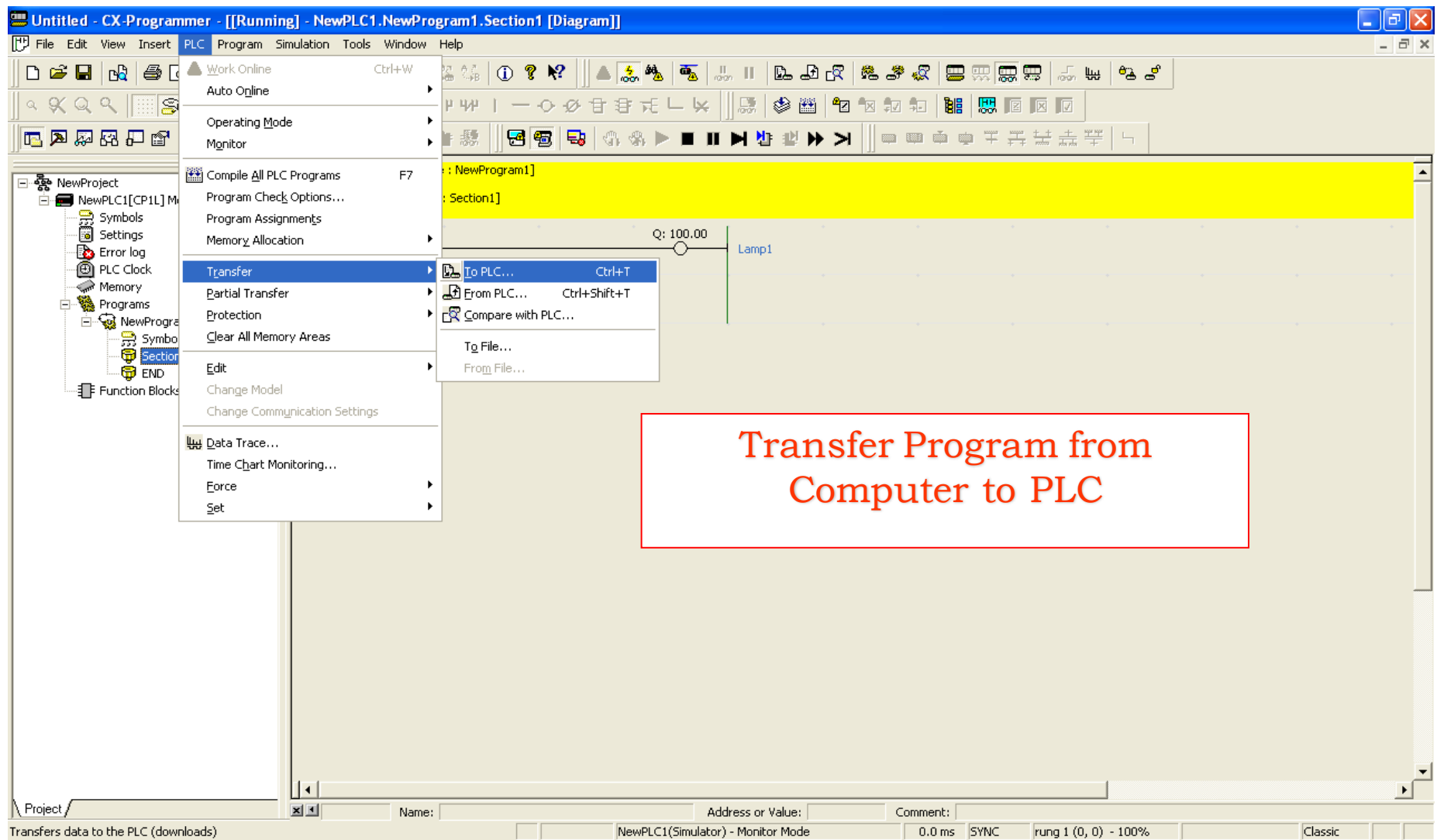
Project

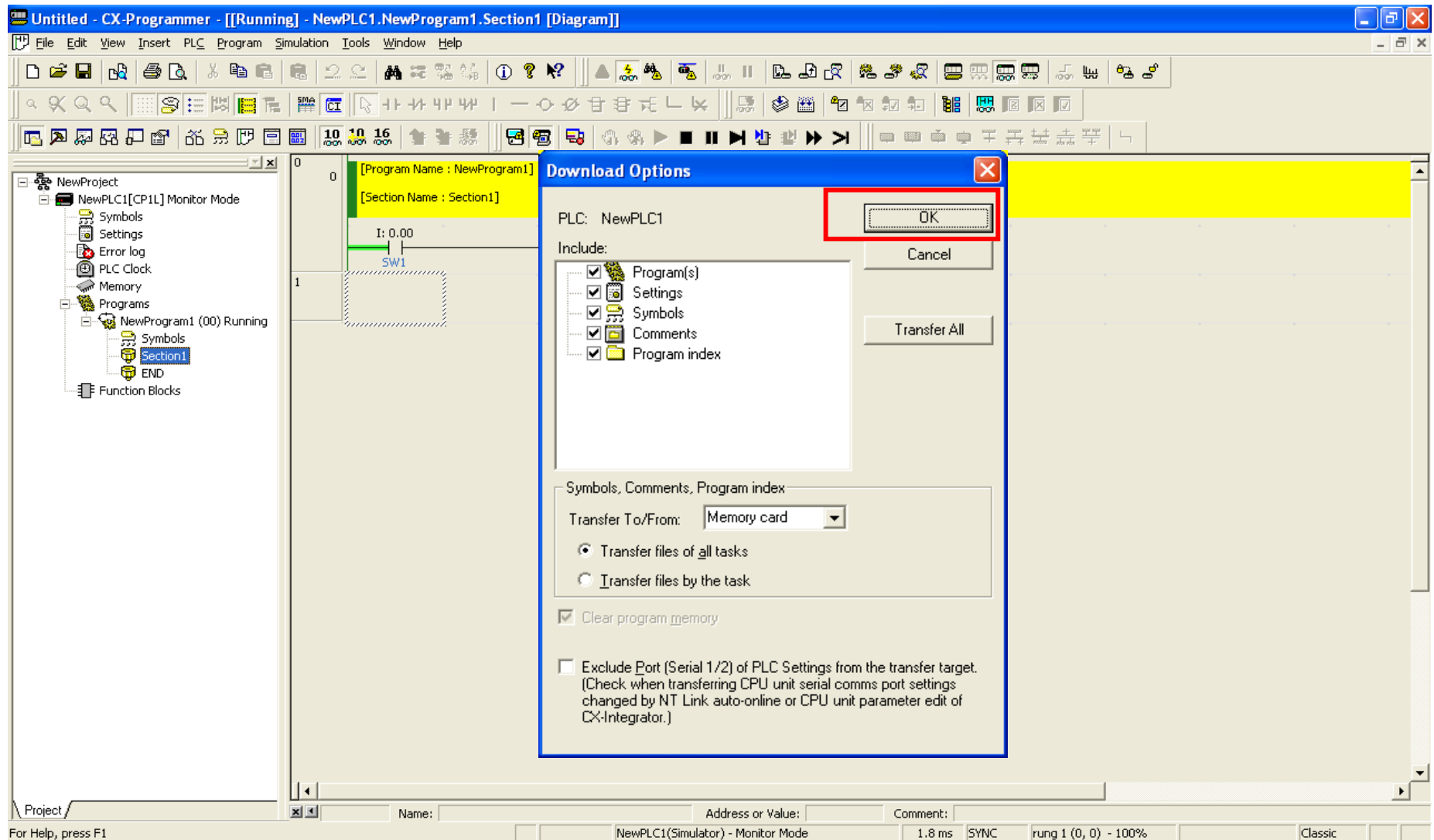
PLC: 'NewPLC1' (PLC Model 'CP1L L')
Compiling...
[PLC/Program Name : NewPLC1/NewProgram1]
[Ladder Section Name : Section1]
[Ladder Section Name : END]
NewPLC1 - 0 errors, 0 warnings.

Compile Find Report Transfer

For Help, press F1

NewPLC1(Simulator) - Monitor Mode 0.0 ms SYNC rung 1 (0, 0) - 100% Classic





Untitled - CX-Programmer - [[Running] - NewPLC1.NewProgram1.Section1 [Diagram]]

File Edit View Insert PLC Program Simulation Tools Window Help

NewProject

- NewPLC1[CP1L] Monitor Mode
 - Symbols
 - Settings
 - Error log
 - PLC Clock
 - Memory
 - Programs
 - NewProgram1 (00) Runn
 - Symbols
 - Section1
 - END
 - Function Blocks

0

[Program Name : NewProgram1]
[Section Name : Section1]
I: 0.00 Q: 100.00

CX-Programmer v9.2

 Make sure that there aren't any problems if
Do you wish to switch the PLC into program mode?

Yes

No

Download

Program Download to PLC NewPLC1

Program Transfer Complete

Download successful

OK

Project

Name: Address or Value: Comment:

For Help, press F1

NewPLC1(Simulator) - Monitor Mode 1.8 ms SYNC rung 1 (0, 0) - 100% Classic

Untitled - CX-Programmer - [[Running] - NewPLC1.NewProgram1.Section1 [Diagram]]

File Edit View Insert PLC Program Simulation Tools Window Help

NewProject

- NewPLC1[CP1L] Monitor Mode
 - Symbols
 - Settings
 - Error log
 - PLC Clock
 - Memory
 - Programs
 - NewProgram1 (00) Running
 - Symbols
 - Section1
 - END
 - Function Blocks

0

0

[Program Name : NewProgram1]

[Section Name : Section1]

I: 0.00

Q: 100.00

Lamp1

SW1

1

CX-Programmer v9.2

 Make sure that there aren't any problems if the PLC is started.
Do you wish to return the PLC to Monitor mode?

Yes

No

Screen at Monitoring Mode

Project

Name: Address or Value: Comment:

For Help, press F1

NewPLC1(Simulator) - Monitor Mode

0.0 ms SYNC

rung 1 (0, 0) - 100%

Classic

AND / AND NOT

- When 2 or more conditions lie in **series** on the same instruction line, the first one correspond to a LD or LD NOT instruction, and the rest of the conditions, to AND or AND NOT instructions.
- AND - taking the logical AND of the execution condition
- AND NOT - taking the logical AND between its execution condition and the inverse of its operand bit.

OR / OR NOT

- When 2 or more conditions lie on separate instruction line running in **parallel** and joining together, the first one correspond to a LD or LD NOT instruction, and the rest of the conditions correspond to OR or OR NOT instructions.
- OR - taking the logical OR of the execution condition.
- OR NOT - taking the logical OR between its execution condition and the inverse of its operand bit.

AND LD & OR LD Instructions

AND LD

- The AND LD instruction logically AND the execution conditions produced by two logic blocks.

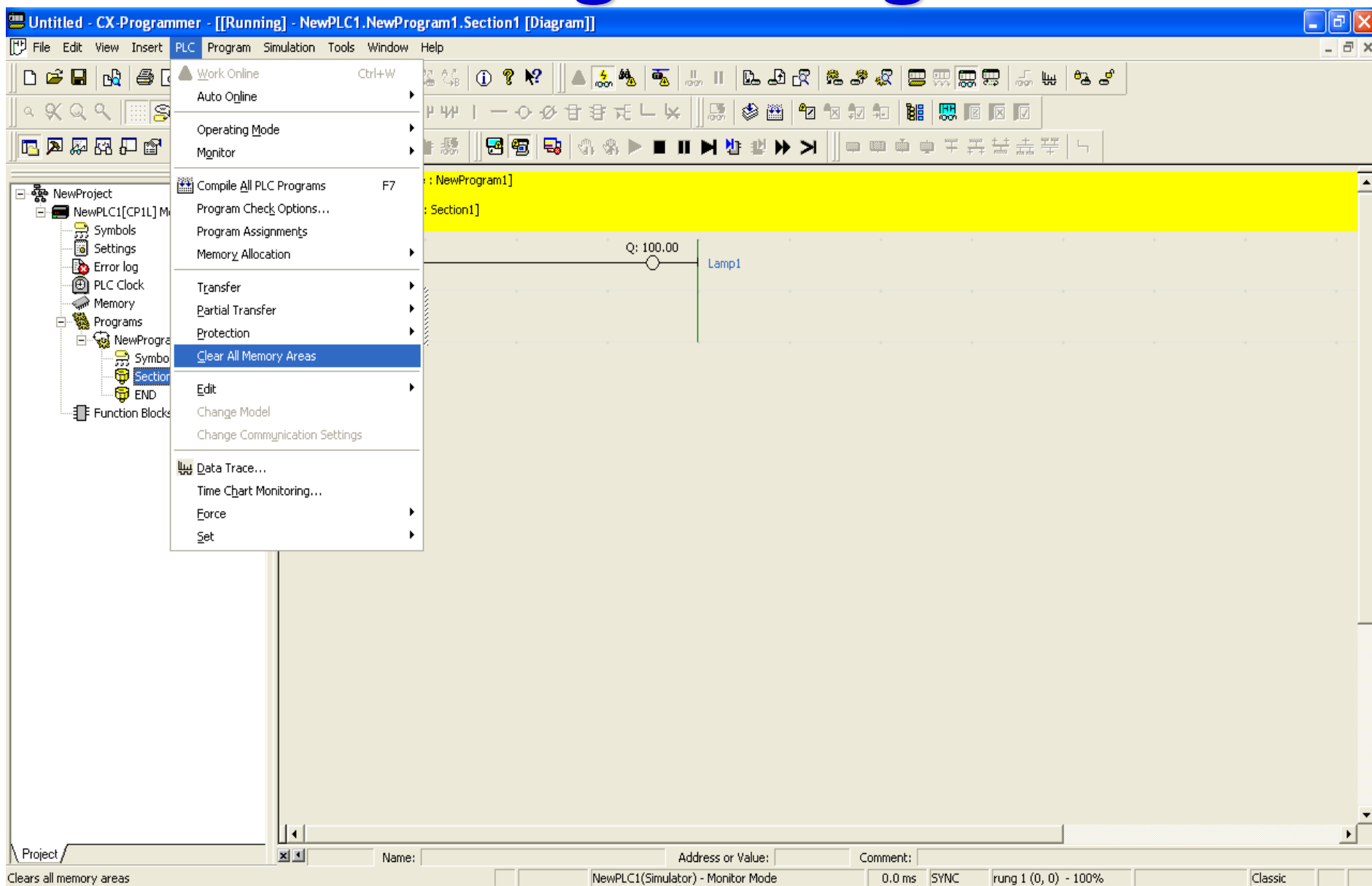
OR LD

- The OR LD instruction logically OR the execution conditions produced by two logic blocks.

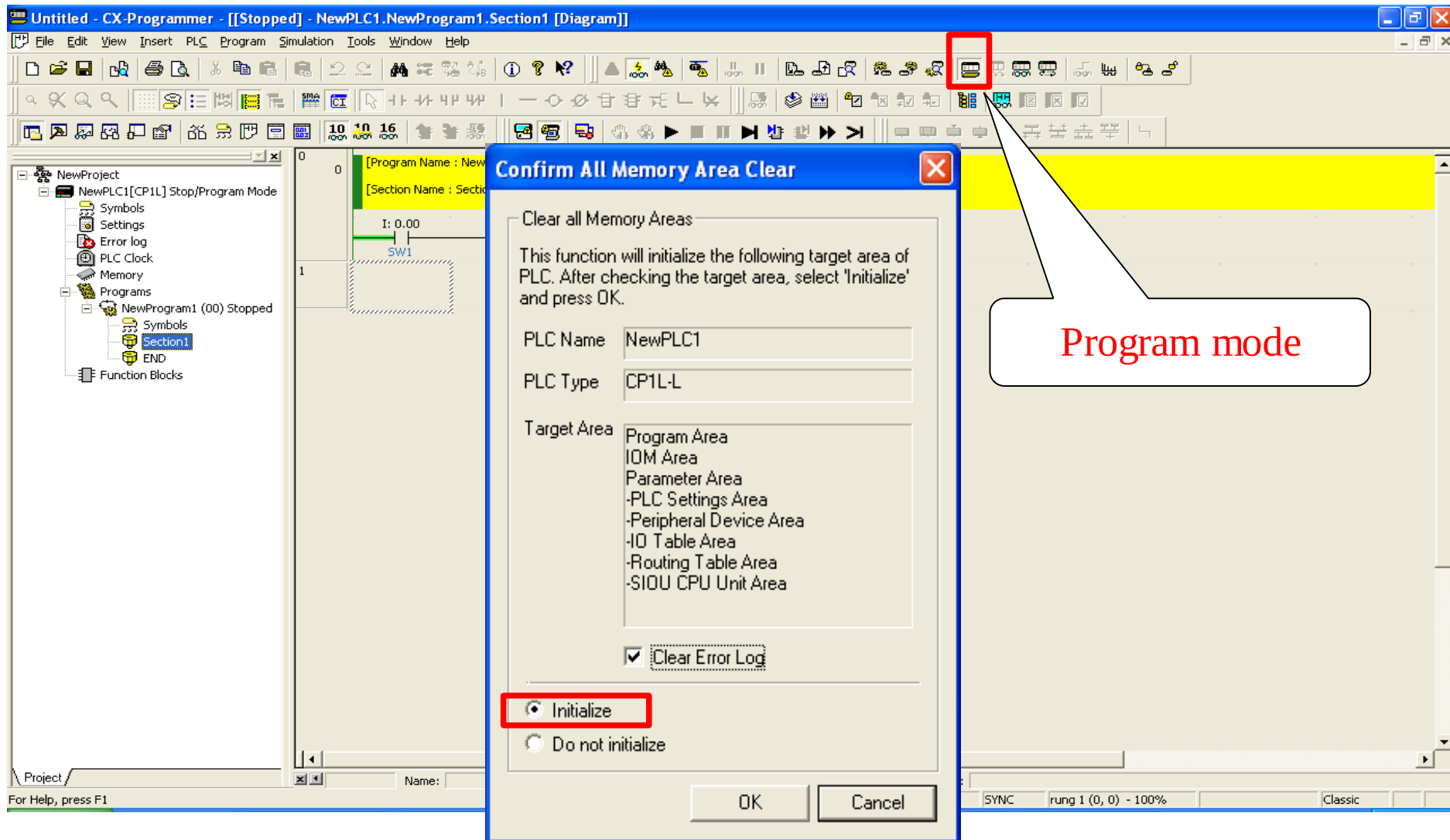
Memory Area Functions

Data		Function
IR	Internal Relay Area	Bits are allocated to external I/O terminals. Some can be used free within program
IO	I/O Relay Area	
WR	Work Relay Area	Not allocated to external I/O terminal. Freely use within program
SR	Special Relay Area	Serve for specific function such as flags & control bits
TR	Temporary Relay Area	Contain bits that record the ON/OFF status of program branches
AR	Auxiliary Relay Area	Serve for specific functions such as flags & control bits
LR	Link Relay Area	Used for data links (Serial PLC Link) with another PLC
	PLC Link Area	
TC	Timer/Counter Area	Same numbers are used for timers & counters in CPM1A)
DM	Data Memory Area	Word values are retained when power Off or operating mode switching
HR	Holding Relay Area	Bit status are retained when power Off or operating mode switching

Clearing All Program



Clearing All Program



Various Relays

I/O Relay (IR)

I/O Relay

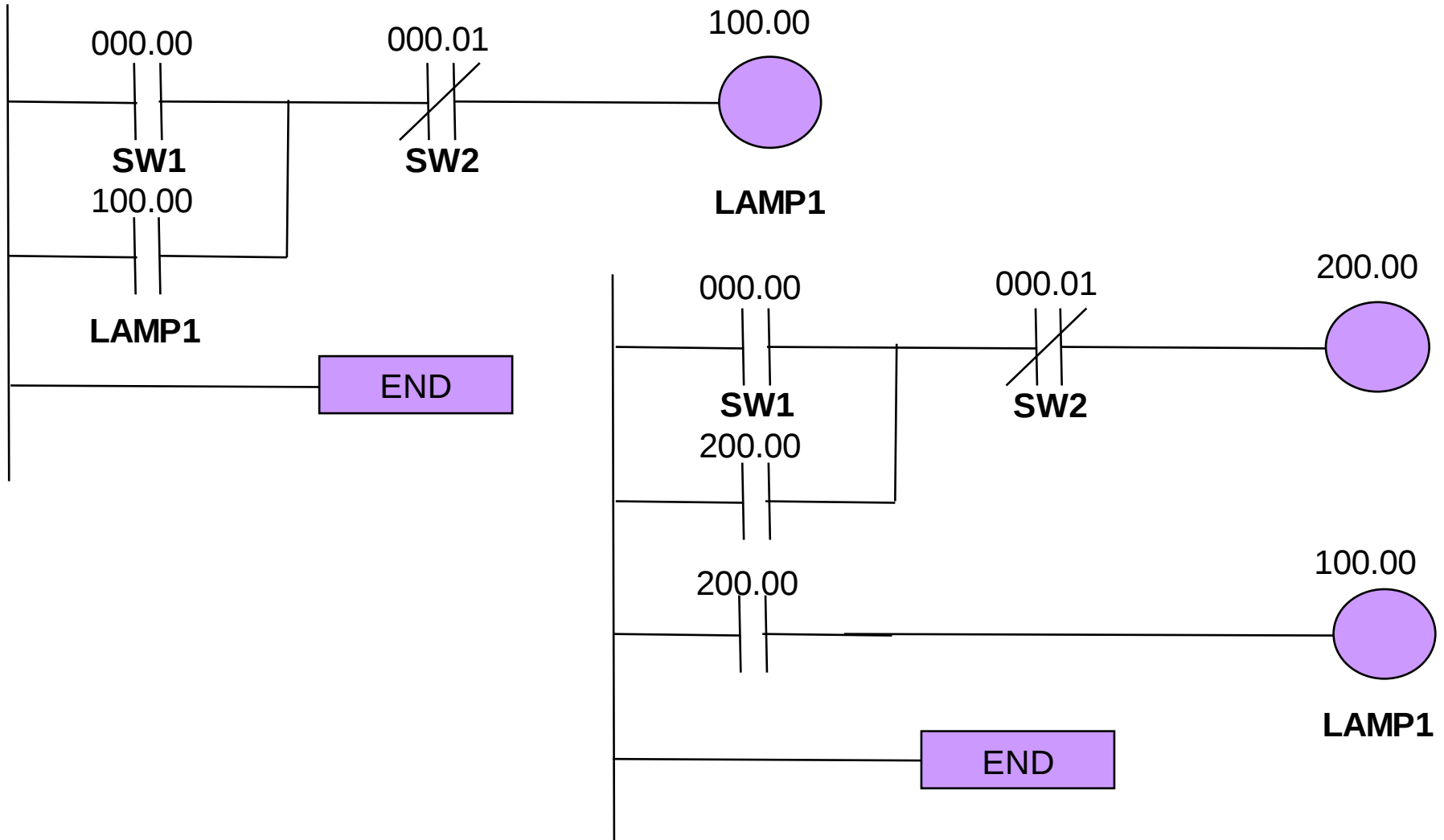
- Corresponds to external input terminals and output terminals
- e.g.: 000.00 to 000.15 (Input relay)
- e.g.: 100.00 to 100.15 (Output relay)

Internal Relay

- Can be used freely within the program, they cannot be used for I/O exchange with external I/O terminals.

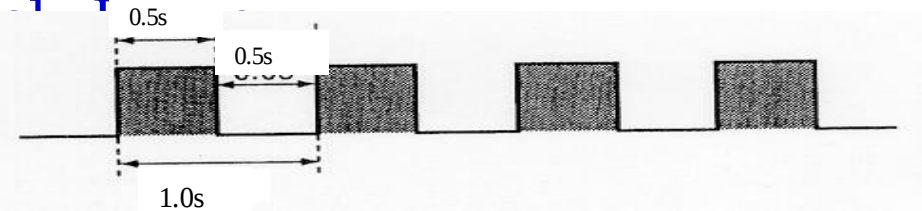
IR Application Example

Self-Holding / Latching Circuit

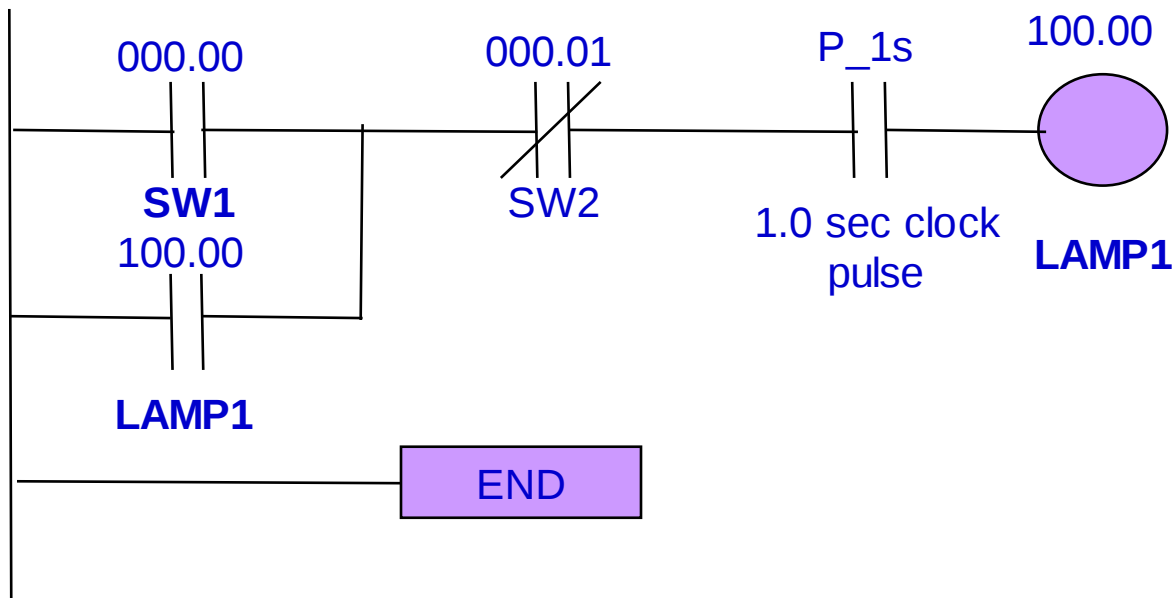


Condition & Clock Pulse Flags

- These flags include the Arithmetic Flags, such as the Error Flag and Equals Flag, which indicate the results of instruction execution.
- The Condition Flags are specified with symbols, such as P_CY and P_ER, rather than addresses.
- e.g.: P_On – Always On Flag
P_Off – Always Off Flag
P_1s – 1 second Clock Pulse
P_1s (1s clock pulse)



Special Flags Application Example

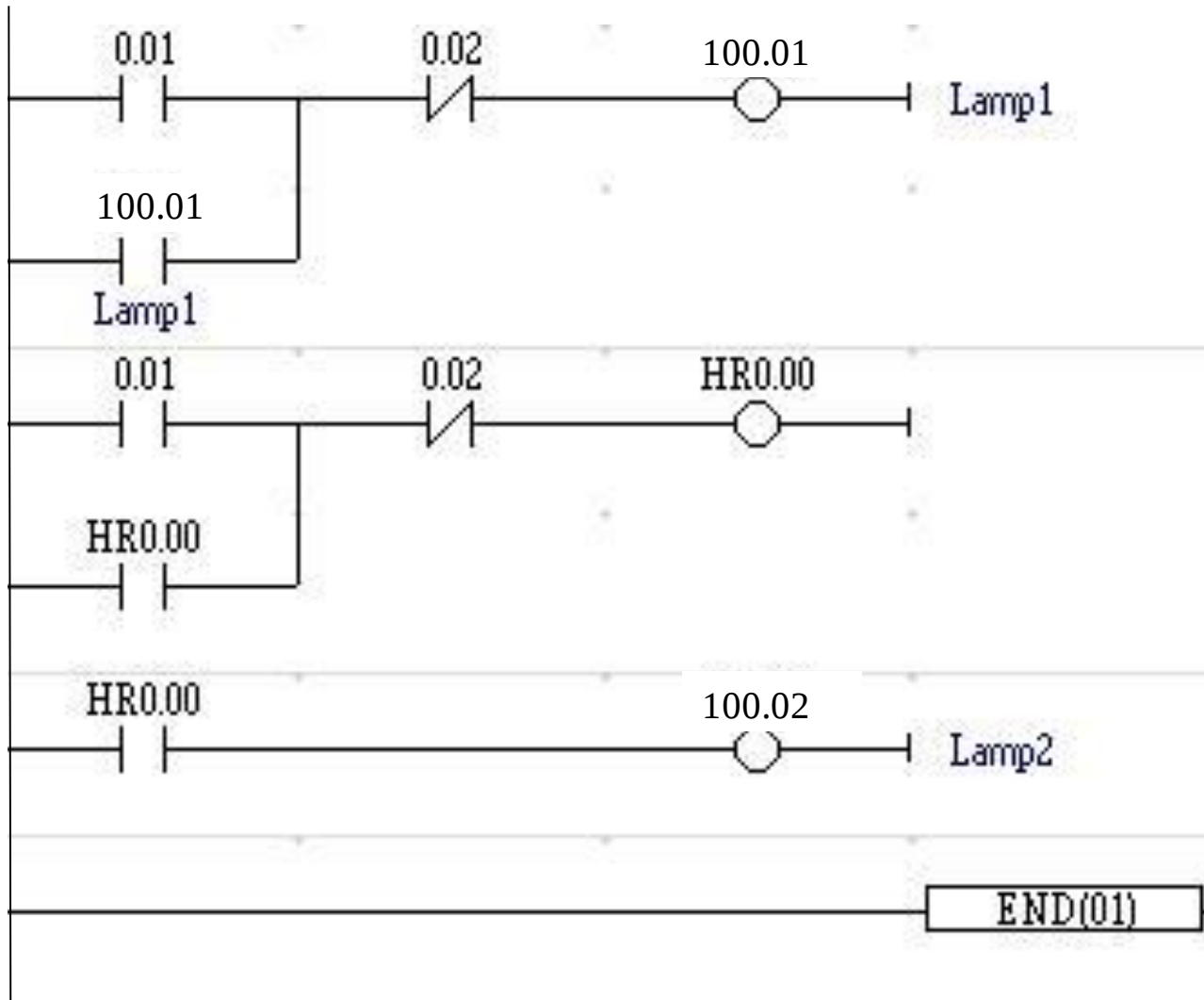


*** Lamp 1 will starts flashing/blinking after SW1 was being trigger.**

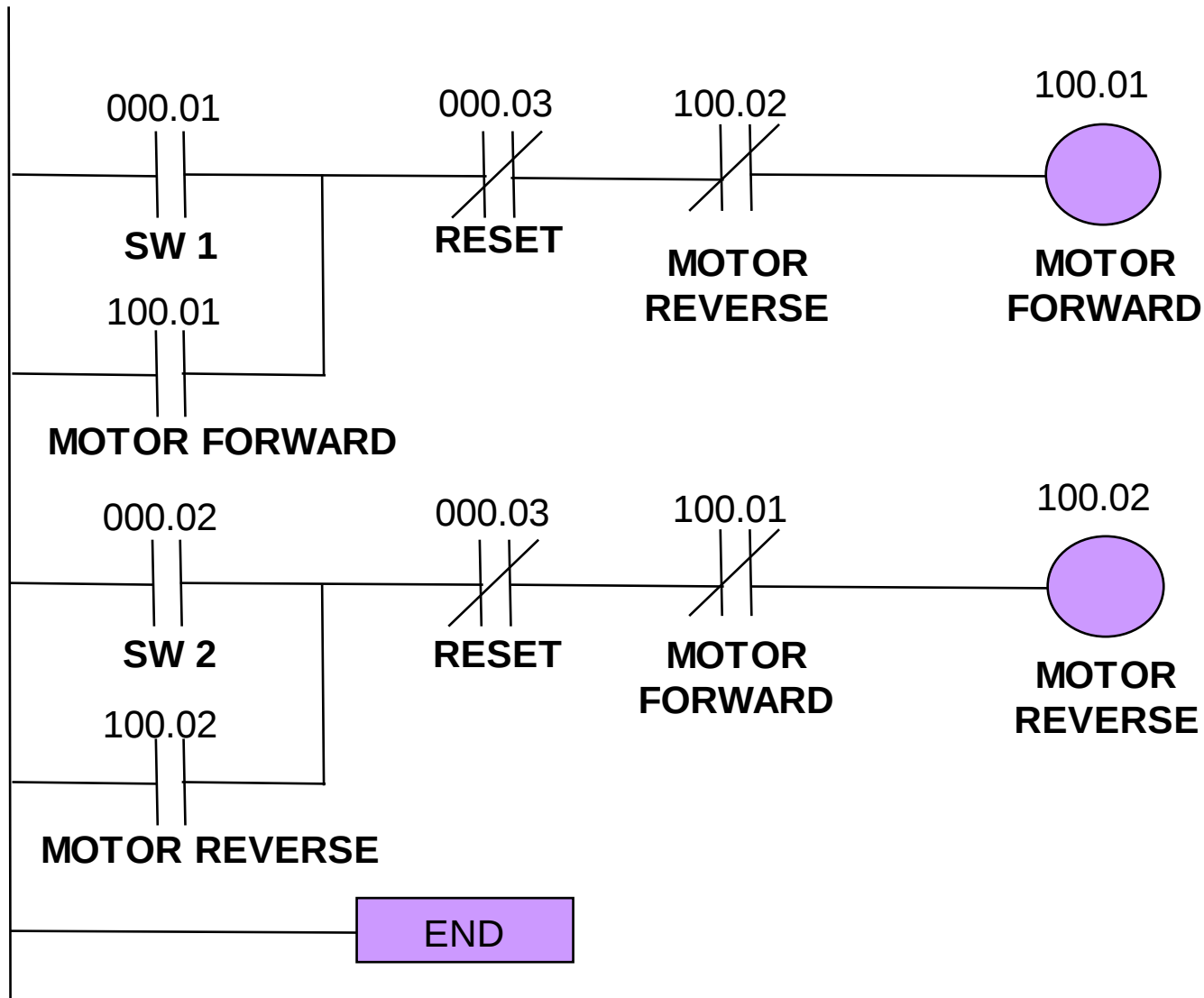
Holding Relay (HR)

- Maintains the ON/OFF state even when the power is cut off.

HR Application Example



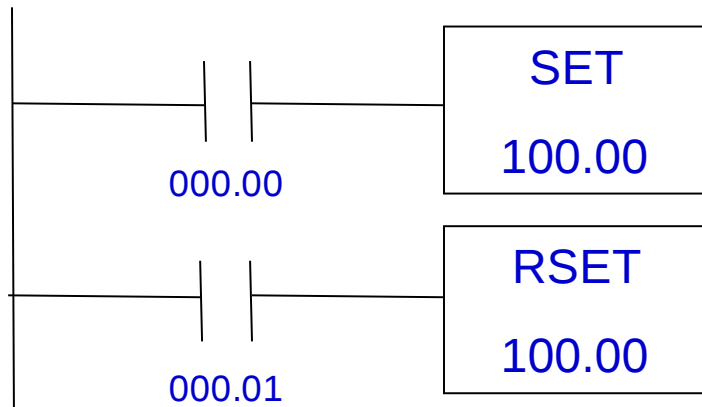
INTERLOCK CIRCUIT



Latch Instruction

– SET, RSET

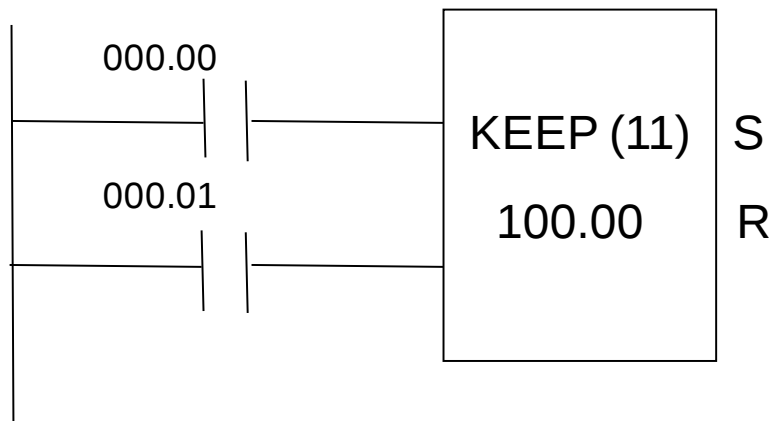
- Used momentary switches to latch and reset output.



Latch Instruction

– KEEP (11)

- Used momentary switches to latch and reset output.
- Operates like a latching relay that is set by S and reset by R.
- Remains ON or OFF state of a bit until one of its two inputs sets or reset.



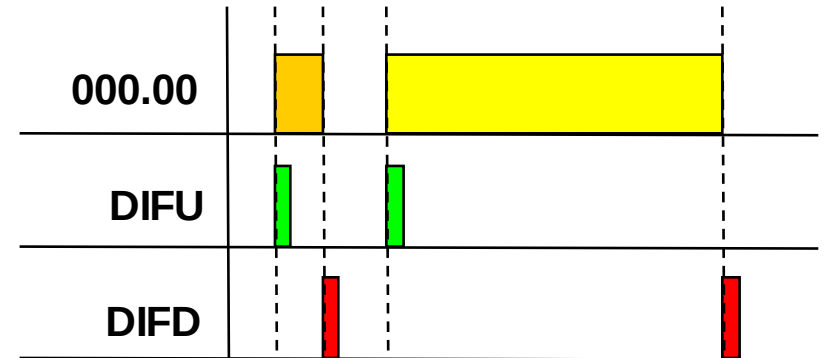
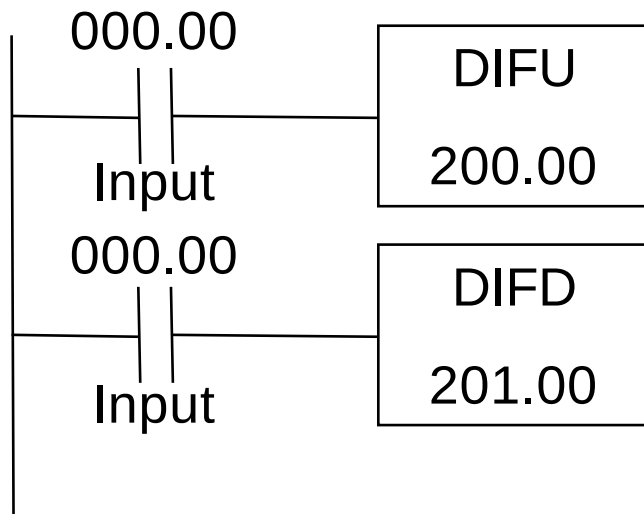
00	LD	000.00
01	LD	000.01
02	KEEP (11)	100.00
03	END (01)	

Differentiation Up & Down

DIFU (13) and DIFD (14)

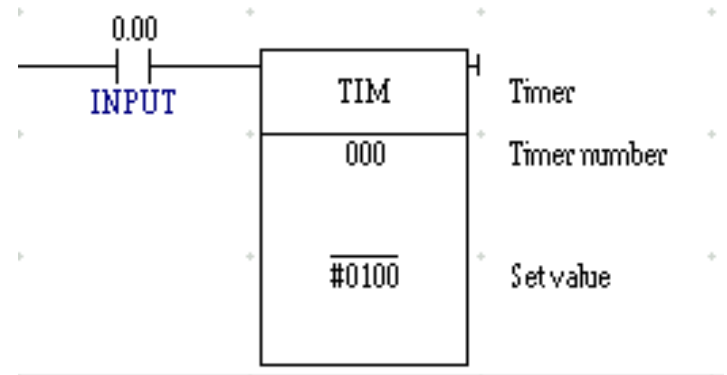
- DIFU turns its output ON when it detects an OFF > ON transition in its input signal.
- DIFD turns its output ON when it detects an ON > OFF transition in its input signal.

One Shot-DIFU (13) and DIFD (14)



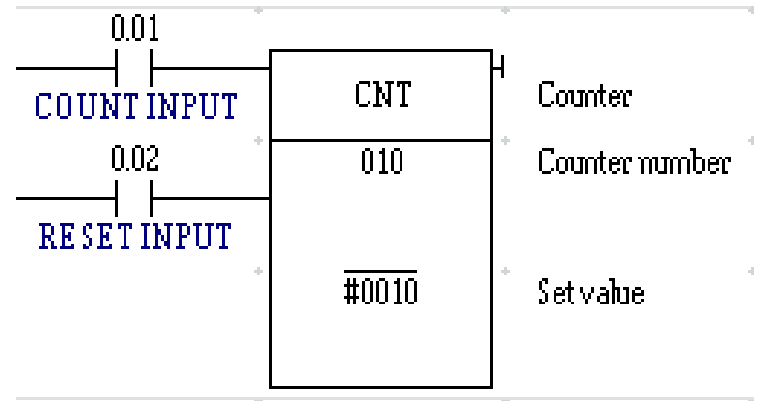
DIFU and DIFD only turns an output ON for only **one scan/pulse**.

Timer (TIM)



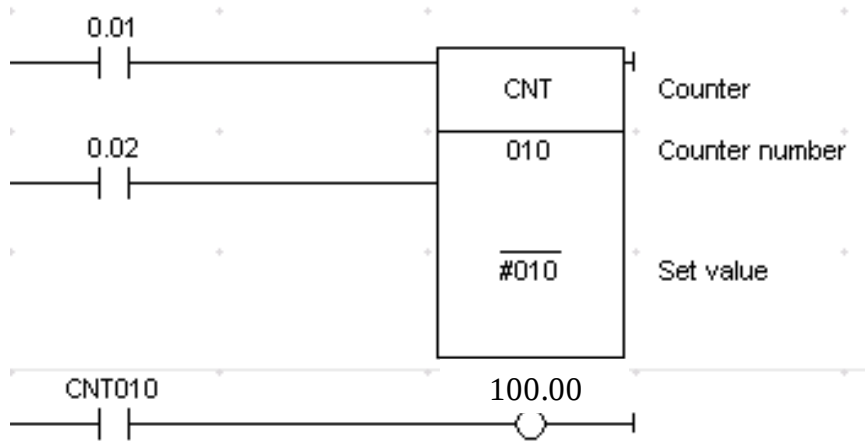
- Timer is an instruction normally used for time delay. It can be ON delay or OFF delay.
 - The timer is based on a decrement method.
 - On-Delay-Timer after our sensor (input) turns on we wait x-seconds before activating a solenoid valve (output).
- ** Timer number for CPM1A, T000 to T127
...Must not coincide with counter number
- Set value range from #0000 ~ #9999 (0 ~ 999.9 sec)
 - If the start input becomes OFF or the power is turned OFF during operations before time up (current value #0000), the current value will be reset to the value set.

Counter (CNT)



- CNT is a preset decrement counter.
 - It decrements one count every time an input signal goes from OFF to ON.
 - The counter must be programmed with a count input, a reset input, a counter number and set value.
 - **Set value range from #0000 ~ #9999**
- ** Counter number for CPM1A, C000 to C127**
...Must not coincide with timer number
- Its current value will not be reset even if the PC power supply is turned OFF. It will preserve the count until then.

COUNTER



LD	000.01
LD	000.02
CNT	010
	#010
LD	CNT01
OUT	100.00
END	(01)