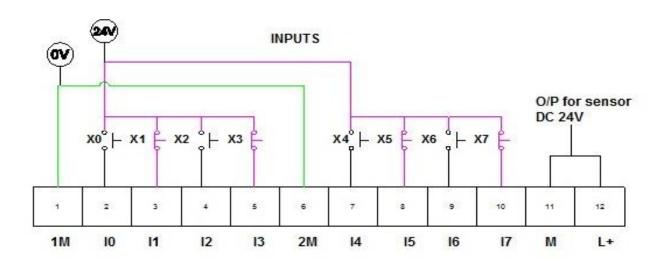
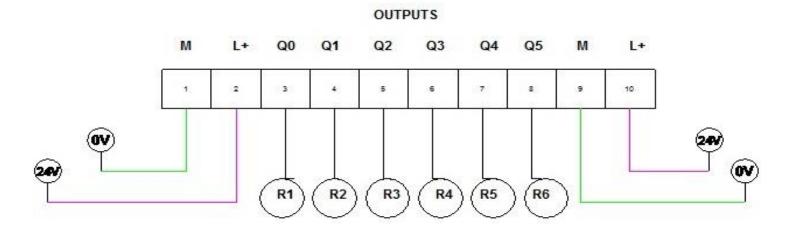


PLC Siemens S7 200



## S7 200 PLC Wiring Diagram





## PLC Programming Software Step 7



Works best with Windows XP only

## Input/ Output Addressing

Digital Input Addressing (I 0.0 ~ I 15.7)

First Input

I 0.1 Second Input

I 0.0

Digital Output Addressing (Q 0.0 ~ Q 15.7)

Q 0.0 First Output

Q 0.1 Second Output

Analog Input Addressing (AIW0 ~ AIW30)

AIW0 First Input

AIW2 Second Input

Bit Memory (M)

 $M 0.0 \sim M31.7$ 

Local Memory (L) - Volatile

LB0 ~ LB63

Variable Memory (V) – Non Volatile

VB0 ~ VB2047

Special Memory (SM)

SM0.0~ SM299.7

Analog Output Addressing (AQW0 ~ AQW30)

AQW0 First Output

AQW2 Second Output

#### Timers, Counters & Other Addressing

| Time Base | ON/OFF Timer             | Retentive Timer       |
|-----------|--------------------------|-----------------------|
| 1 ms      | T32, T97                 | TO, T64               |
| 10 ms     | T33 ~ T36, T97 ~ T100    | T1 ~ T4<br>T65 ~ T68  |
| 100 ms    | T37 ~ T63<br>T101 ~ T255 | T5 ~ T31<br>T69 ~ T95 |

| Elements                     | Addresses    | Elements                         | Addresses |
|------------------------------|--------------|----------------------------------|-----------|
| Counters                     | C0 C255      | Interrupts                       | 0 ~ 127   |
| High Speed Counters          | HC0 ~ HC25   | Positive/ Negative<br>Transition | 256       |
| Sequential Control<br>Relays | S0.0 ~ S31.7 | PID Loops                        | 0 ~ 7     |
| Acc. Register                | AC0 ~ AC3    | Acc. Register                    | AC0 ~ AC3 |
| Jump/Label                   | 0 ~ 255      | Jump/Label                       | 0 ~ 255   |
| Call/ Subroutine             | 0 ~ 63       | Call/ Subroutine                 | 0 ~ 63    |

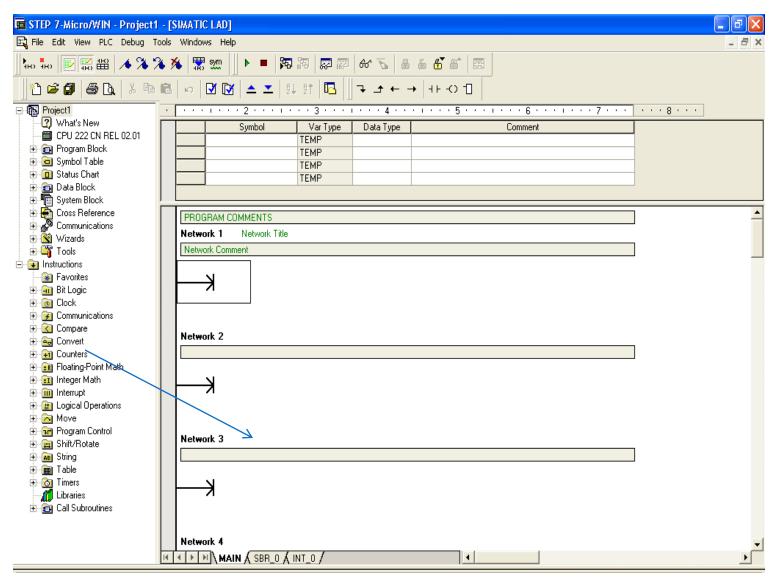
#### System Status Bits

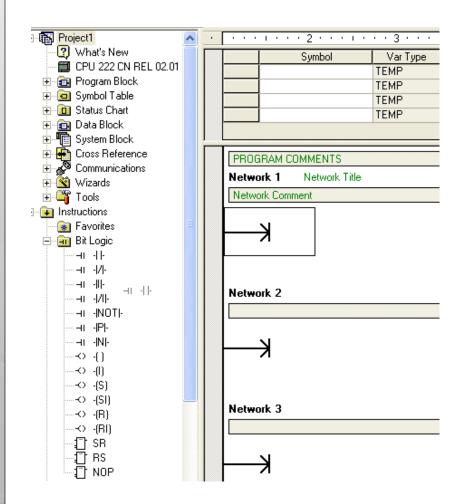
| SPECIAL<br>MEMORY BIT | DESCRIPTIONS   |
|-----------------------|--|
| SM 0.0                | Always ON  |
| SM 0.1                | First SCAN ON- On for only one scan cycle  |
| SM 0.3                | RUN Power Up – ON for 1 scan cycle when PLC goes to RUN mode                                 |
| SM 0.4                | 60s Clock Pulse – ON for 30 seconds & OFF for 30 seconds                                     |
| SM 0.5                | 1s Clock Pulse – ON for 0.5 second & OFF for 0.5 second                                      |
| SM 0.6                | Clock Scan – ON for 1st Scan & Off for 2nd Scan & so on                                      |
| SM 0.7                | Mode Switch – Indicate Current position of Mode Switch OFF = TERM Position ON = RUN Position |
| SM 4.7                | Force ON – Turn ON when any memory location is Forced  |
| SMW22                 | Word provide SCAN time of Last scan  |
| SMW24                 | Word provide min. SCAN time recorded since entering RUN Mode                                 |
| SMW26                 | Word provide max. SCAN time recorded since entering RUN Mode                                 |
| SMB28                 | Pot_0_Value = Stores the value entered with analog adjustment                                |
| SMB29                 | Pot_1_Value = Stores the value entered with analog adjustment                                |

## Range of Bits

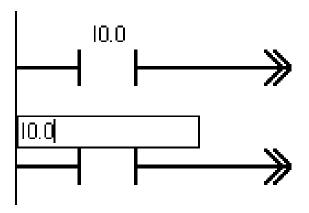
| Туре           | Range (Unsigned)              |  |
|----------------|-------------------------------|--|
| Byte, B        | 0 ~ 255; 0 ~ FF               |  |
| Word, W        | 0 ~ 65535; 0 ~ FFFF           |  |
| Double Word, D | 0 ~ 4294967295<br>0 ~ FFFFFFF |  |

## PLC software view

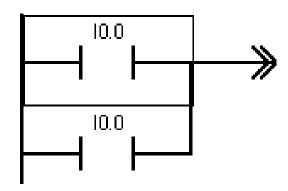




Dragging symbols



Symbols in parallel



Blocks are connected



## SIEMENS INSTRUCTIONS

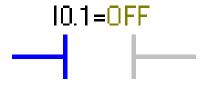
#### Inputs are written as:

- IO.0 first input, IO.1- second input and so on, for first card.
- I1.0 first input, I1.1 second input and so on, for 2<sup>nd</sup> card.

#### Outputs are written as:

Q0.0 – first output, Q0.1 – second output and so on, for first card.

Q1.0 - first output, Q1.1 - second output and so on, for  $2^{nd}$  card.



NO, during off state

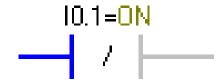


NO, during on state

#### NORMALLY CLOSED CONTACT



NC, during off state



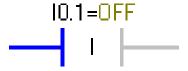
NC, during on state

#### **OUTPUT COIL**

O/P, during off state

O/P, during on state

#### NORMALLY OPEN IMMEDIATE contact:



NOI, during off state

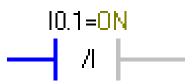


NOI, during on state

#### NORMALLY CLOSED IMMEDIATE contact:



NCI, during off state



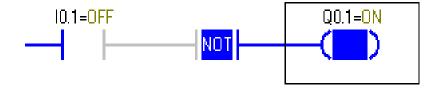
NCI, during on state

#### OUTPUT IMMEDIATE:

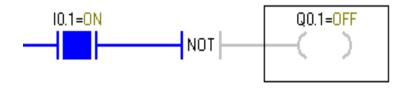
OPI, during off state

OPI, during on state

#### • NOT command:

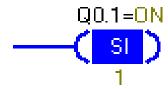


When button is not pressed

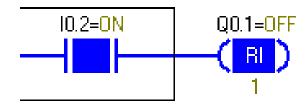


When button is pressed

#### • SET / RESET immediate:

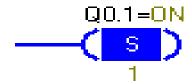


SI, during on state



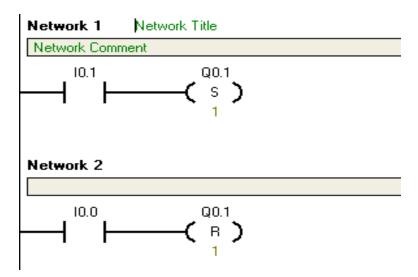
RI, when button is pressed

#### SET Command:



Set during active state

#### RESET command

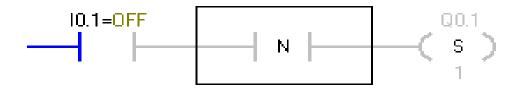


#### POSITIVE transition:



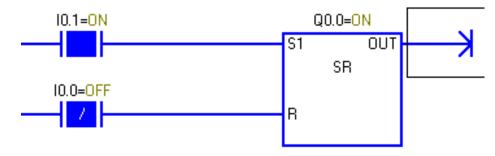
When button is pressed, it gives one pulse

#### • NEGATIVE transition:



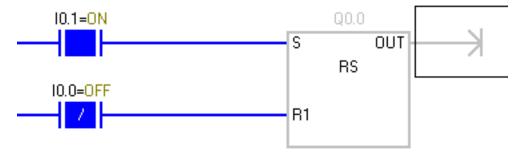
When button is released, it gives one pulse

#### SET RESET dominate bi stable:



When both buttons are pressed

#### RESET SET dominate bi stable:

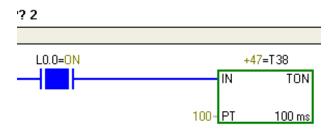


When both buttons are pressed

#### Timers:

#### ON delay timer





T38 is timer number, PT is preset timing value

| Timer Type | Resolution | Maximum Value | Timer Number       |
|------------|------------|---------------|--------------------|
| TONR       | 1 ms       | 32.767 s      | TO, T64            |
|            | 10 ms      | 327.67 s      | T1-T4, T65-T68     |
|            | 100 ms     | 3276.7 s      | T5-T31, T69-T95    |
| TON, TOF   | 1 ms       | 32.767 s      | T32, T96           |
|            | 10 ms      | 327.67 s      | T33-T36, T97-T100  |
|            | 100 ms     | 3276.7 s      | T37-T63, T101-T255 |

#### OFF delay timer:



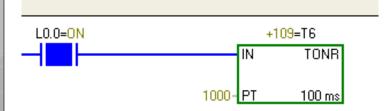
#### ? 2



#### RETENTIVE timer:



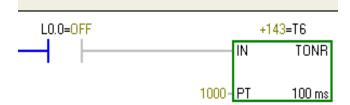




When PLC is on

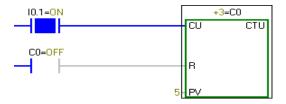


#### ?? 2



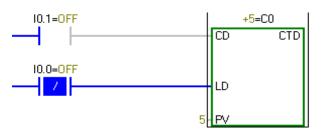
When PLC is stopped

#### COUNTERS:



## CD=OFF Q0.0 S

#### **UP** Counter





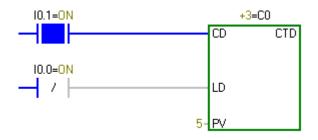
```
C0=OFF Q0.0=OFF
```

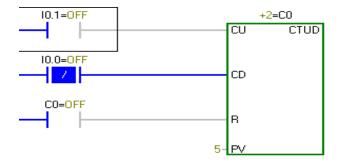
Down counter, loading contact



Down counter, counting reverse

#### **UP-DOWN** Counter:







UP counter is active



DOWN counter is active

#### • INC/DEC command:



|   | ??  | ??  |   |
|---|-----|-----|---|
| 1 | VB0 | ??? | 6 |
| 2 |     | ??? |   |
| 2 |     | 222 |   |

Button is pressed

Data register is incremented

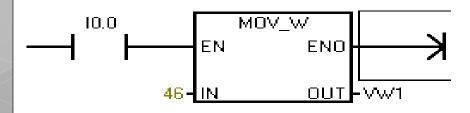


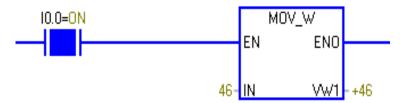
| ??  | ??  |   |
|-----|-----|---|
| VB0 | ??? | 3 |
|     | ??? |   |
|     |     |   |

Button is pressed

Data register is decremented

#### MOVE Command:



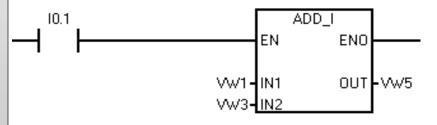


Before execution

After execution

#### • ARITHMATIC Commands:

#### **ADD**



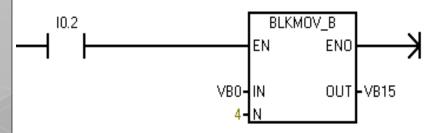
10.1=0N ADD\_I EN EN0 +46- VW1 VW5-+96 +50- VW3

Before execution

After execution

Similarly for SUB, DIV and MUL.

BLOCK MOVE command:



Before execution

| ∨B0<br>∨B1         | ??? | 5  |
|--------------------|-----|----|
| VB1                | ??? | 10 |
| VB2<br>VB3<br>VB15 | ??? | 15 |
| VB3                | ??? | 20 |
| VB15               | ??? | 5  |
| VB16               | ??? | 10 |
| VB16<br>VB17       | ??? | 15 |
| VB18               | ??? | 20 |

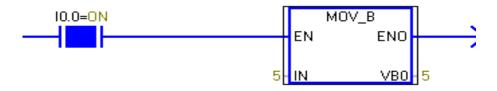
After execution

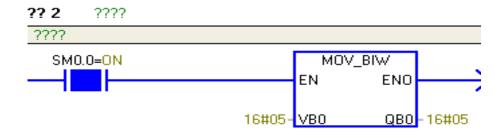
#### • MOVE byte immediate read:



7 shows, 1<sup>st</sup> 2<sup>nd</sup> 3<sup>rd</sup> inputs are ON

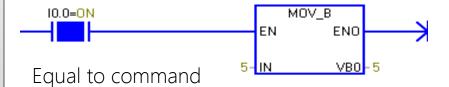
MOVE byte immediate write:

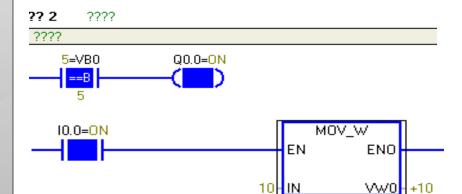




5 shows, 1st and 3rd outputs are ON

#### COMPARE instructions:



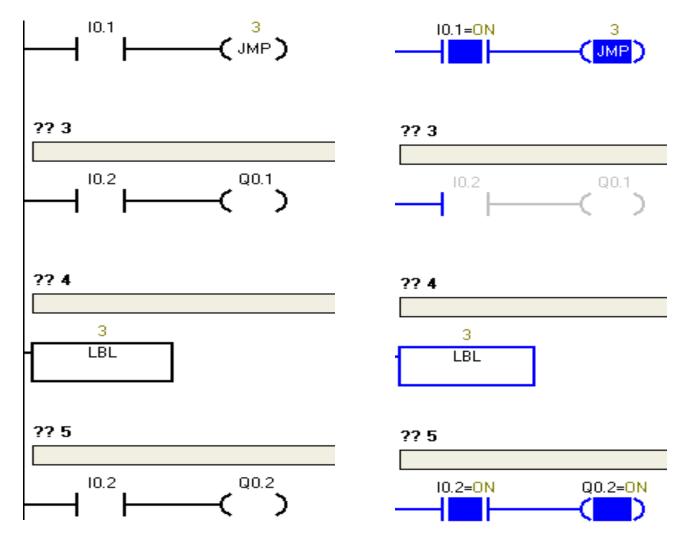




Greater than command

Similarly for Less than, Not equal to and Less or Greater than equal to.

#### • JUMP LABEL instruction:



# Thanks

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