



FOUNDATION™ Fieldbus technology Introduction



Business environment leads to needs

◆ Lower installation cost

- ◆ Multiple instruments on a single pair of wires
- ◆ Faster commissioning - loop check
- ◆ Multi-variable transmitters

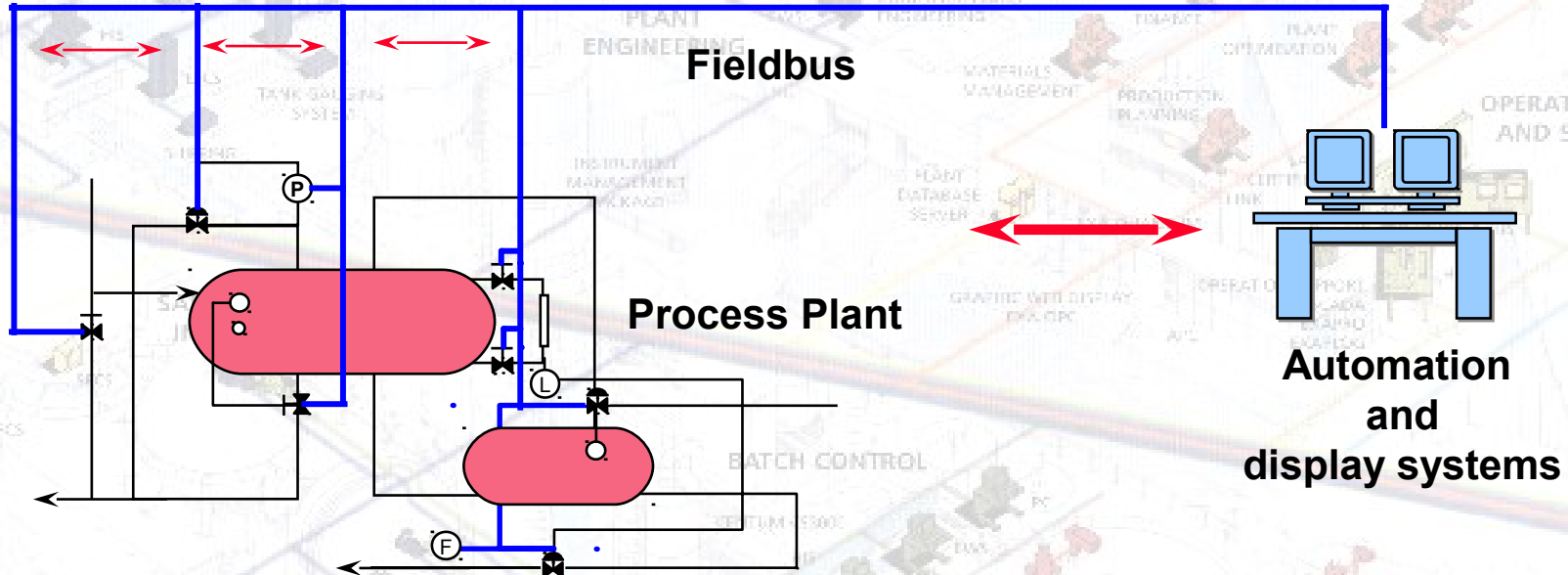
◆ Operational improvements

- ◆ More real time information “about” the process
- ◆ Measurement validation - quality - safety
- ◆ Tighter control by distribution of control functions
- ◆ Mechanism for continuous innovation

◆ Lower maintenance cost - predictive ...

- ◆ Remote access - unified tools
- ◆ Advanced process and device diagnostics
- ◆ Integrated plant asset management functions

What is fieldbus

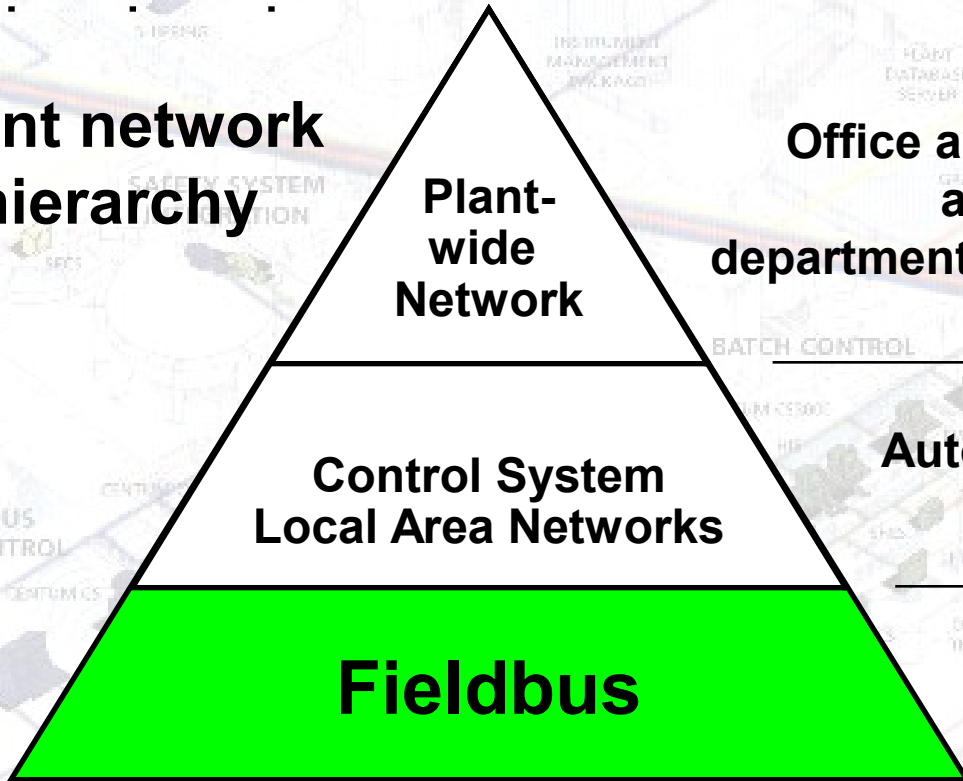


- ◆ **Open, digital, bi-directional communications network**
- ◆ **Among field measurement and control devices and automation/display systems**
- ◆ **It replaces the traditional point-to-point connections**



Local Area Network for field instrumentation

Plant network hierarchy



Office automation and departmental computers

**Control System
Local Area Networks**

Automation and display systems

Fieldbus

Network for field instrumentation



Networks for field devices - 3 types

Process Control

Logic Control

Fieldbus
Block level

Devicebus
Byte level

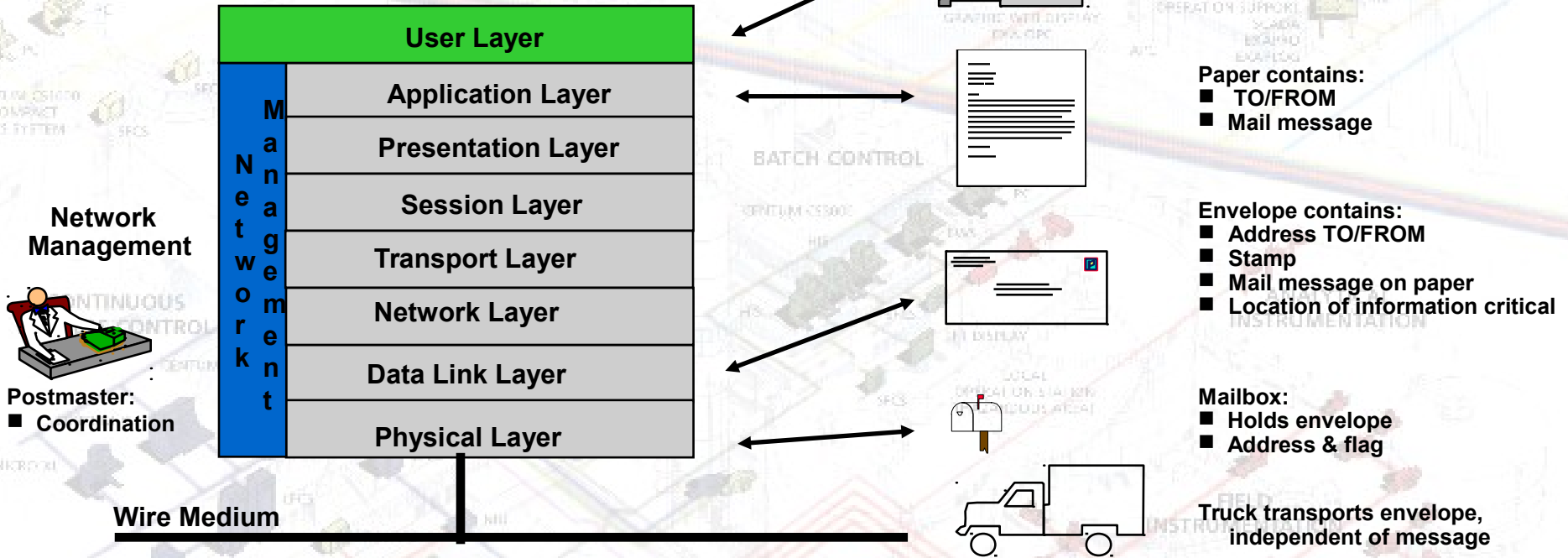
Sensorbus
Bit level

Simple Devices

Complex Devices

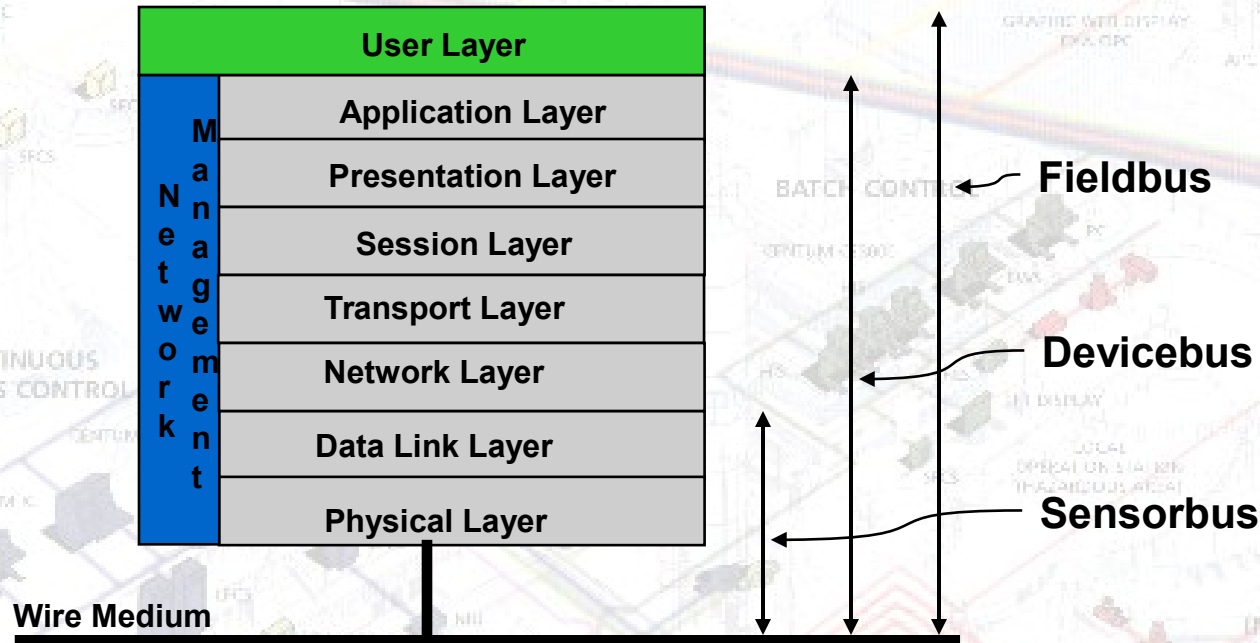
The OSI model

◆ For meaningful communications between fieldbus devices and host systems a common language must be used



The OSI model

- ◆ Layers 1-4 handle the communications between processors
- ◆ Layers 5-7 handle the communications between applications
- ◆ The user layer is not defined by the ISO-OSI model



Sensorbus - What is it?

◆ Simple, low cost implementation

◆ High speed, bit level communication

◆ Simple discrete devices

◆ Push buttons

◆ Limit switches

◆ Optical sensors

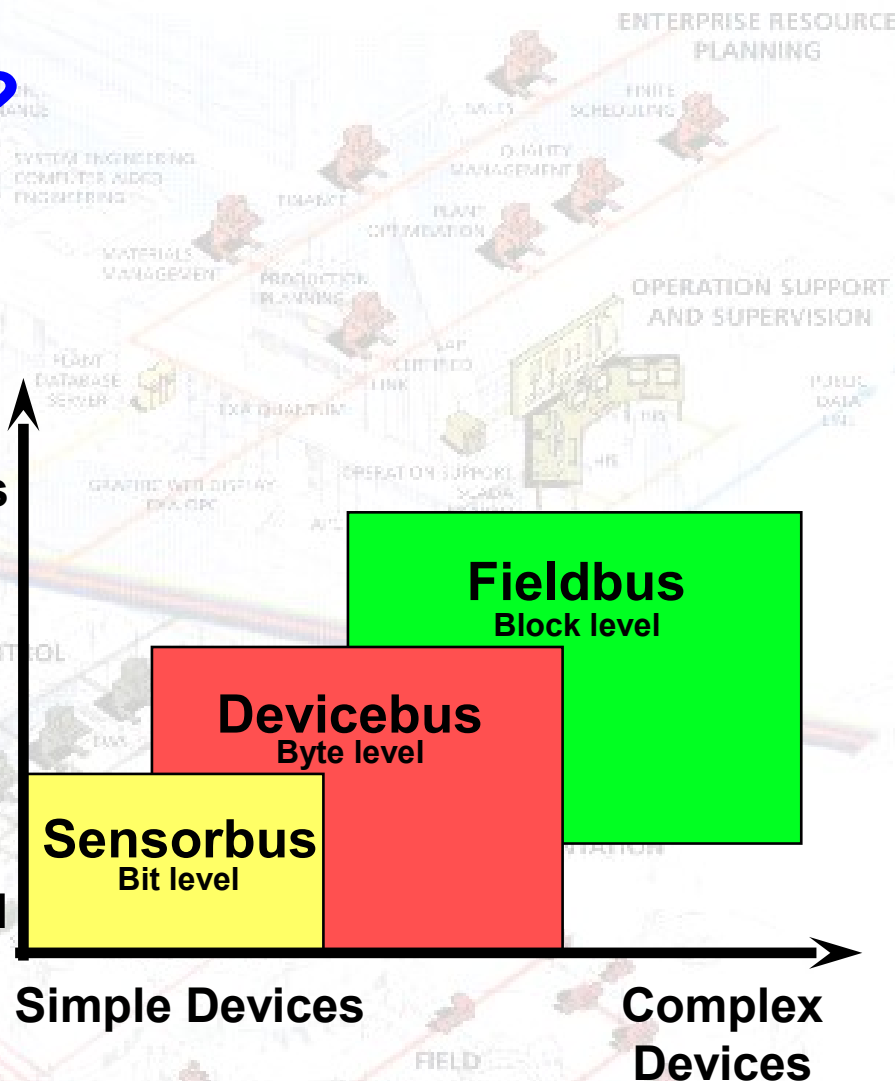
◆ Implementations:

◆ AS-i bus

◆ Seriplex

Process Control

Logic Control



Simple Devices

Complex Devices

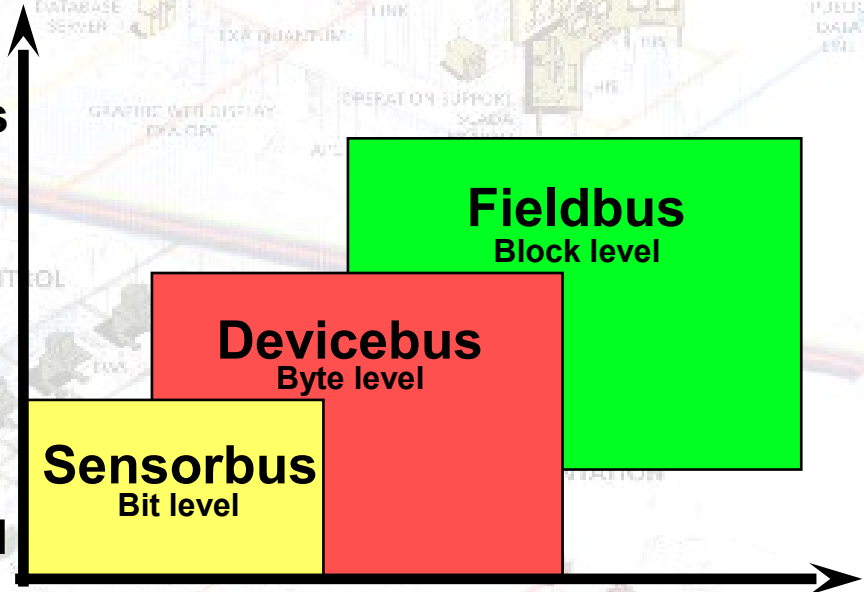


Devicebus - What is it?

- ◆ High speed, byte-level communication
- ◆ Focus on Factory Automation
- ◆ More complex discrete devices
 - ◆ PLC and remote I/O sub-systems
 - ◆ Weighing systems
 - ◆ Electric drive sub-systems
- ◆ Implementations:
 - ◆ DeviceNet
 - ◆ Profibus DP

Process Control

Logic Control



Simple Devices

Complex Devices

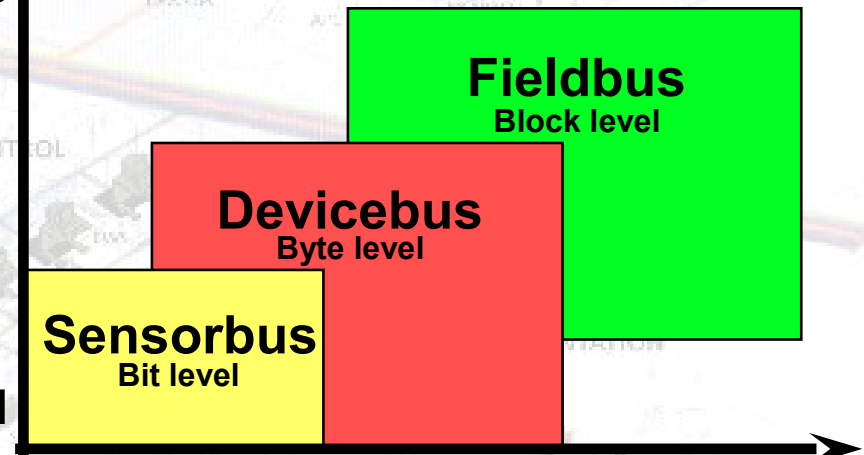


Fieldbus - What is it?

- ◆ Digital replacement of analogue 4-20 mA signal
 - ◆ Unlocking advanced functionality
- ◆ Focus on Process Control
- ◆ Simultaneous power and signal on the bus - 2-wire
- ◆ Supports intrinsic safety
- ◆ Implementations:
 - ◆ Profibus PA
 - ◆ FOUNDATION™ Fieldbus

Process Control

Logic Control



Simple Devices

Complex Devices



FOUNDATION™ Fieldbus

How does it work?



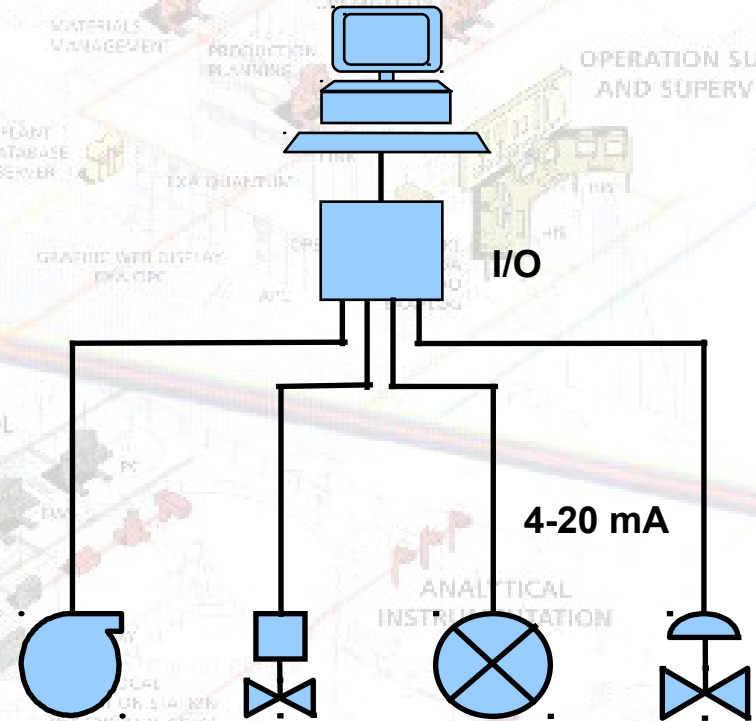
Past - Traditional instrumentation

Strengths

- ◆ OPEN, interoperable and interchangeable
- ◆ Broad range of equipment
- ◆ Multiple vendors
- ◆ Standard control system interfaces
- ◆ Standard support equipment

Weaknesses

- ◆ Limited information transmitted
 - ◆ One variable, one direction
- ◆ Point-to-point wiring



Traditional analogue (4-20 mA) and discrete instruments

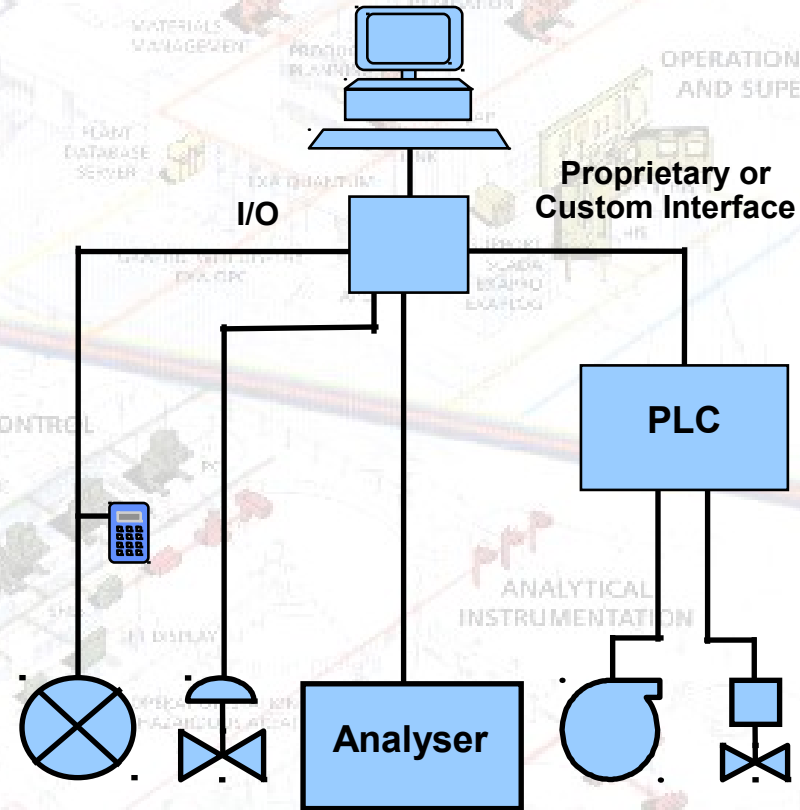
Present - Hybrid instrumentation

Strengths

- ◆ More information transmitted
- ◆ Bi-directional communications
- ◆ Improved performance and availability
- ◆ Faster commissioning - ease of configuration
- ◆ Improved maintenance through line diagnostics

Weaknesses

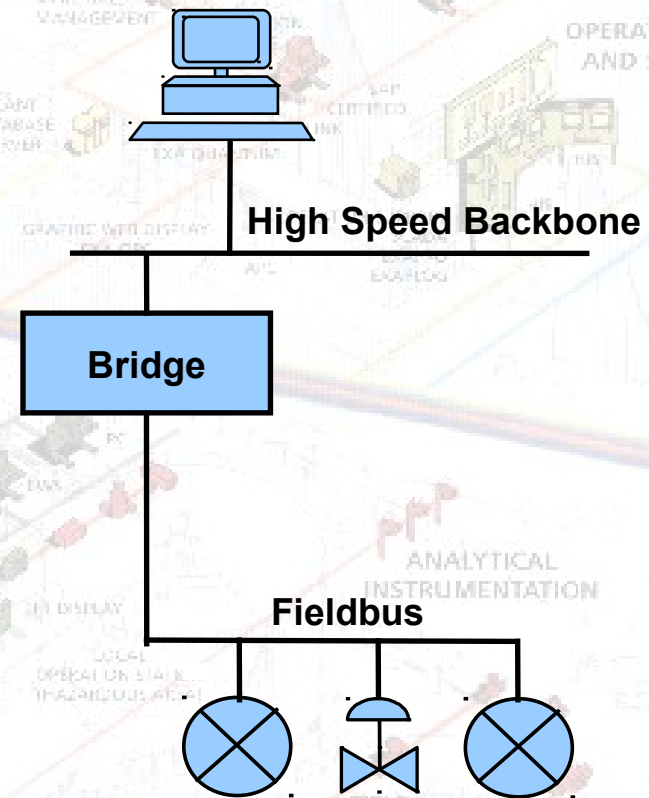
- ◆ Limited interoperability
- ◆ Manufacturer dependency
- ◆ Lack practical multi-drop capability
- ◆ Requires special DCS interfaces



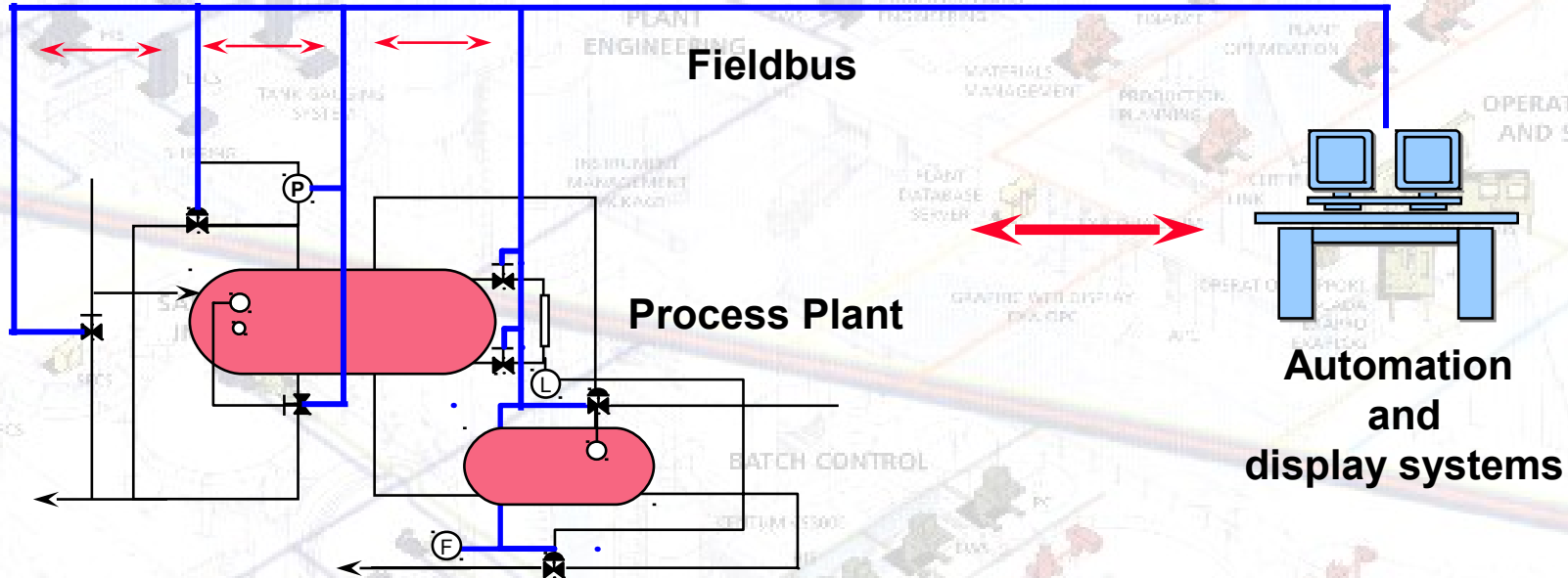
Hybrid Instruments or Intelligent Instruments with Custom Interfaces

Fieldbus - Customer expectations

- ◆ **Fieldbus is open and interoperable**
 - ◆ Supports interchangeability
 - ◆ Supports various bus topologies
 - ◆ Supports control and automation functions
- ◆ **Supported by multiple vendors**
 - ◆ Broad range of equipment
- ◆ **Standard control system interfaces**
- ◆ **Bi-directional communications**
 - ◆ More information transmitted - alarm reporting
 - ◆ Improved performance and availability
 - ◆ Improved maintenance - on-line diagnostics
- ◆ **Standard support equipment**
 - ◆ Ease of configuration - single tool
 - ◆ Faster commissioning



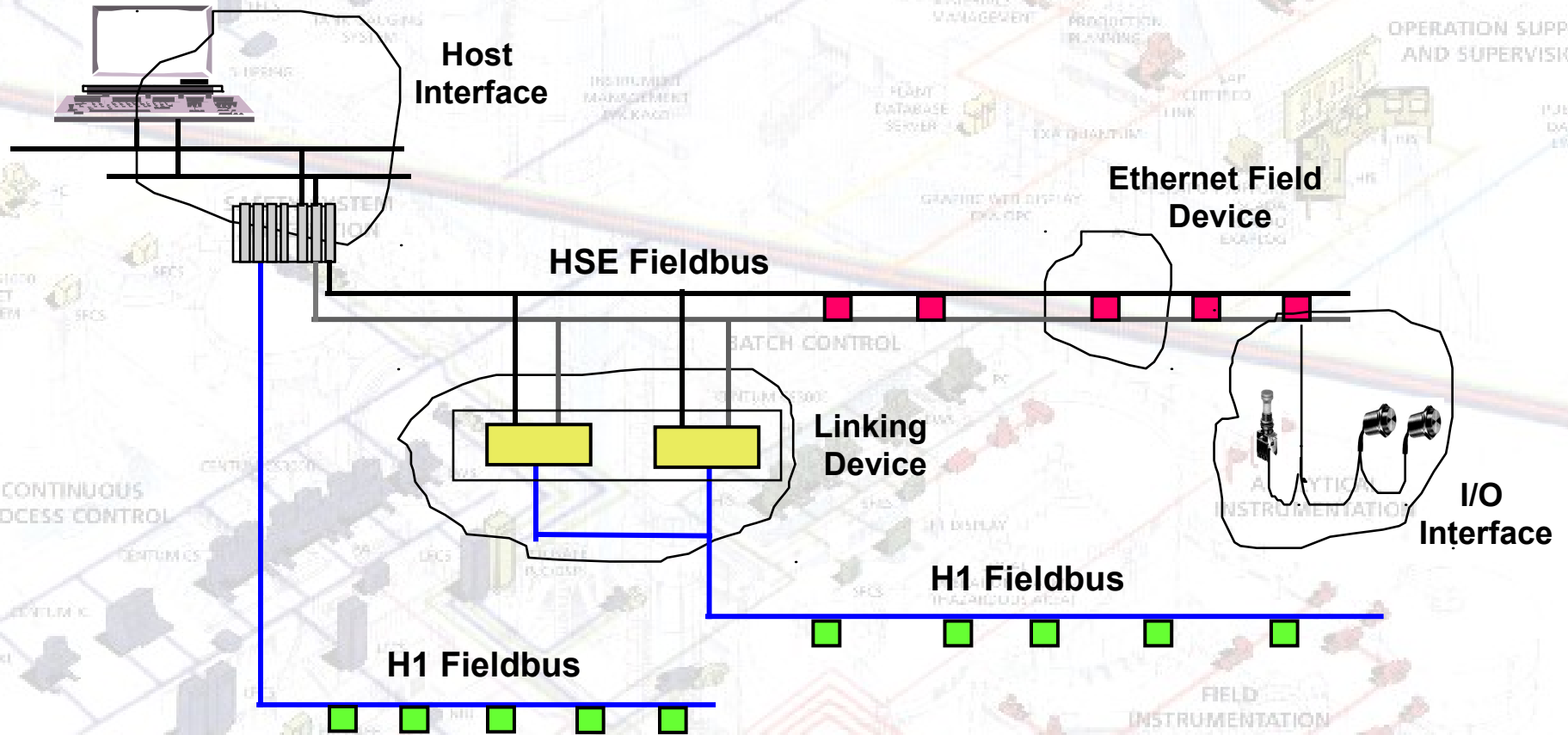
FOUNDATION™ Fieldbus is an “Enabler”



- ◆ **Designed for total plant automation - control and automation**
- ◆ **Vendor independent “Best in Class” solutions**
- ◆ **Innovation - seamless integration new device functionality**

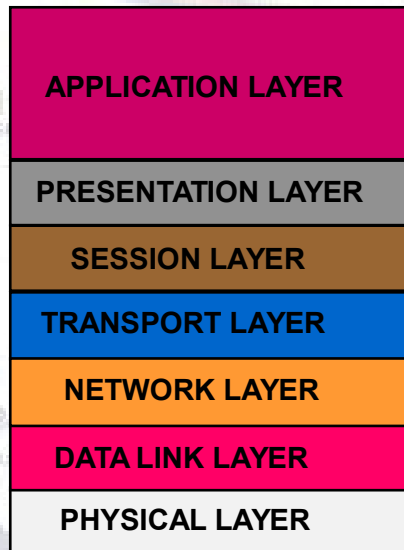


FOUNDATION™ Fieldbus topology

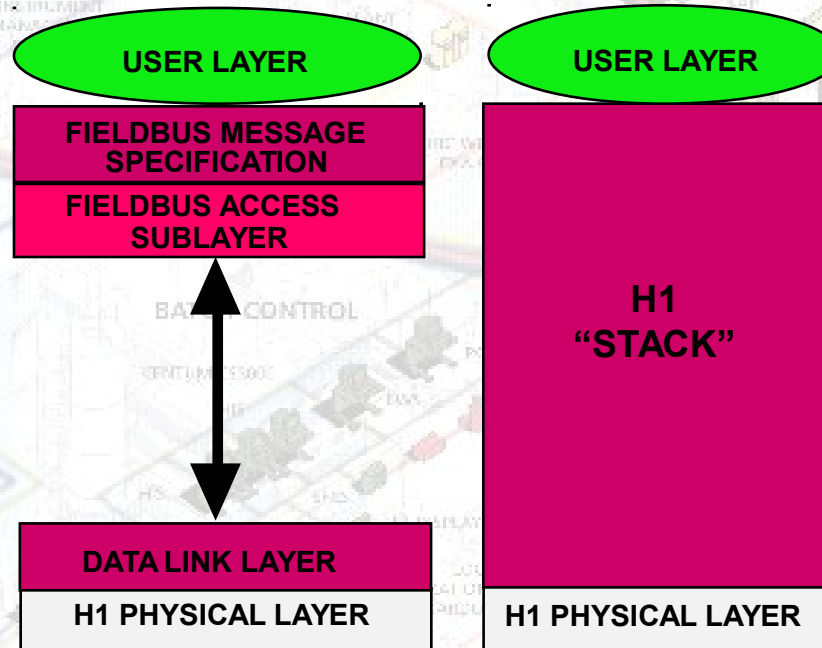


The H1 FOUNDATION™ Fieldbus model

OSI model based

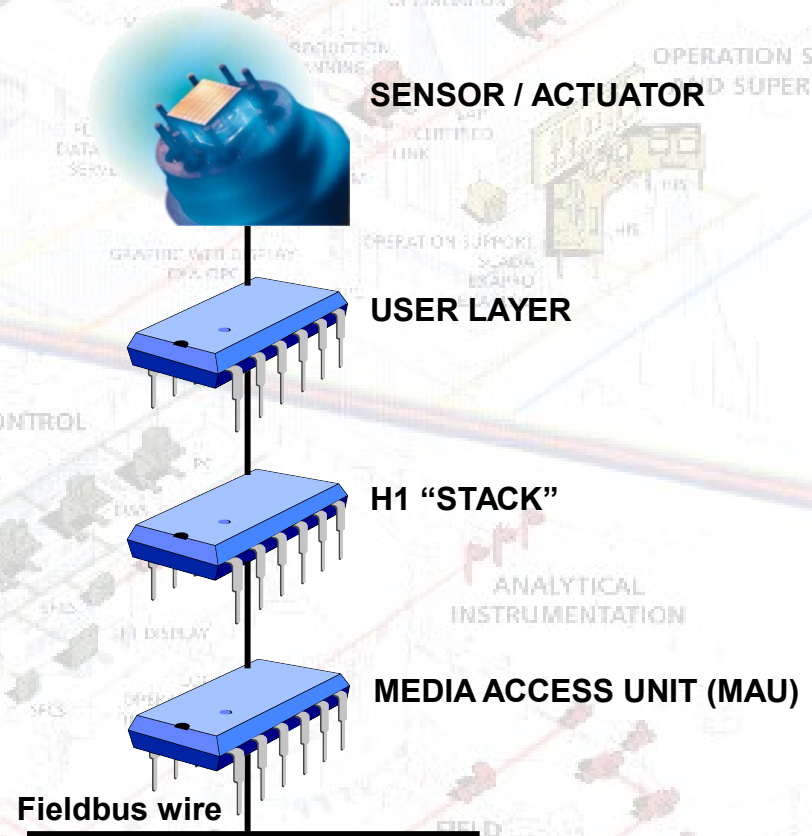
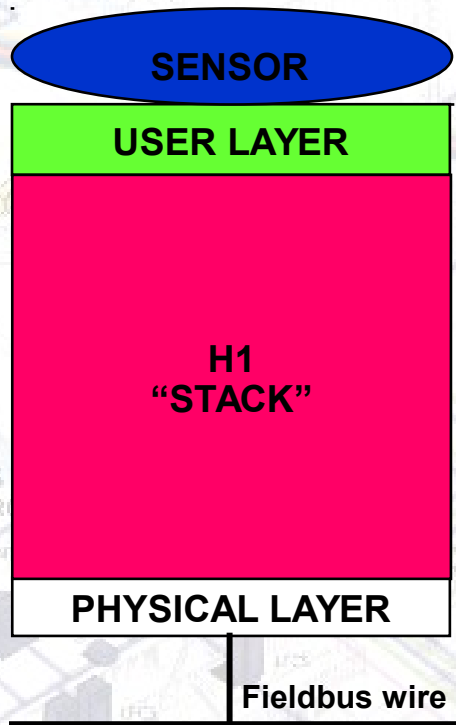


FOUNDATION™ Fieldbus H1 Model

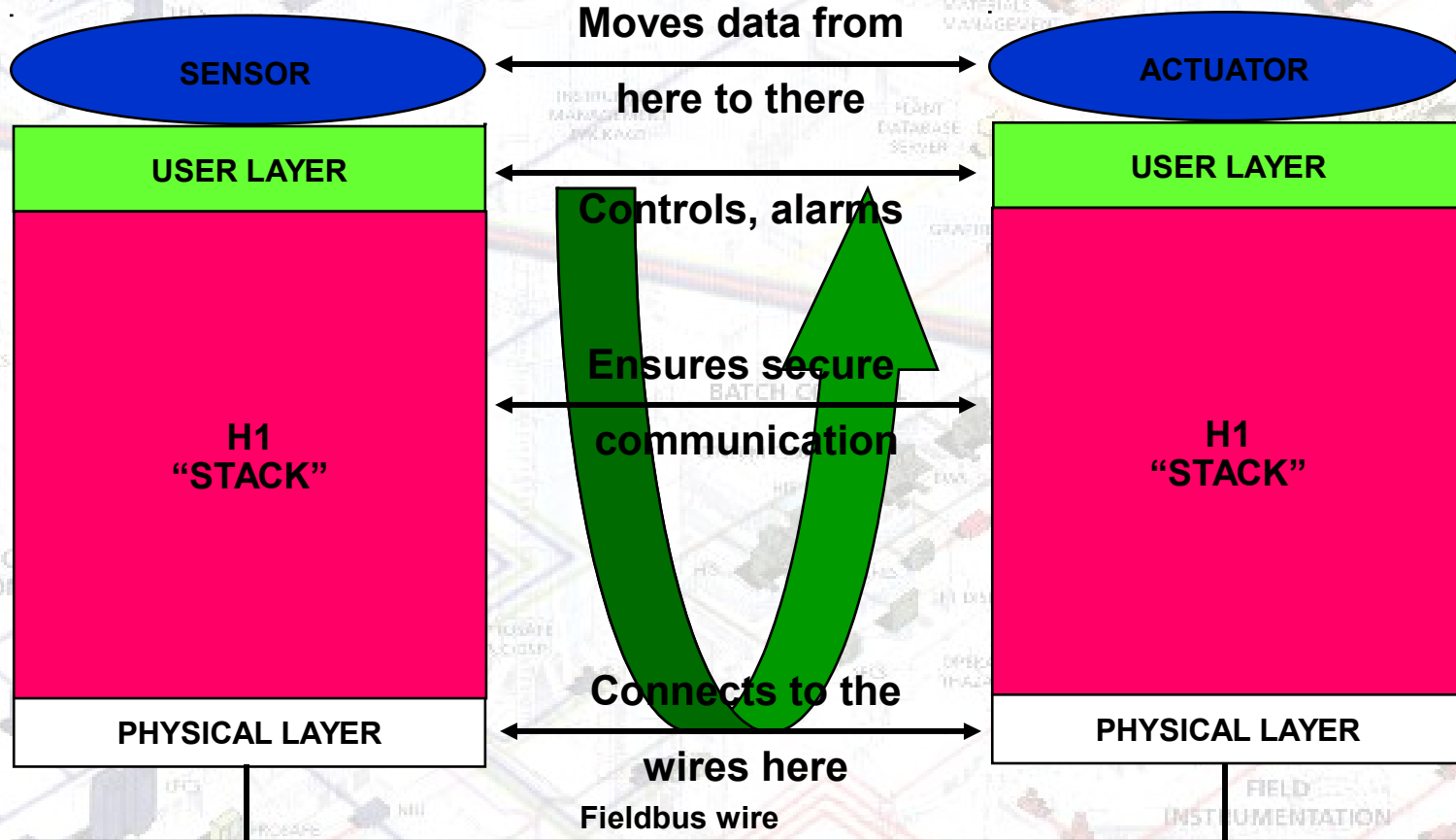


The User Layer is not defined by the OSI Model

H1 practical implementation



What does FOUNDATION™ Fieldbus do?



H1 Physical Layer

- ◆ IEC 61158 compliant

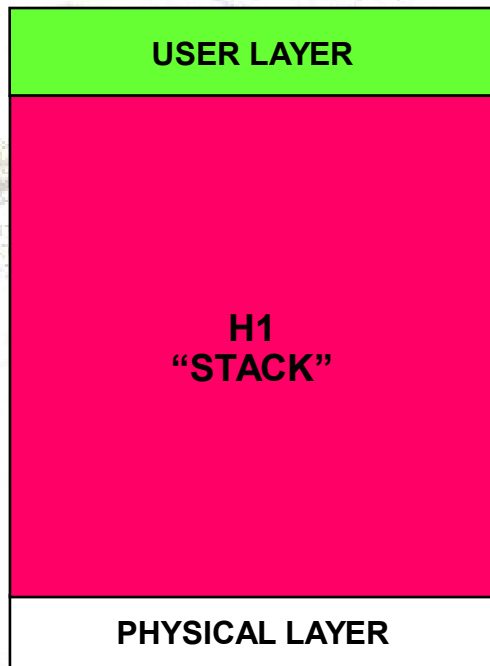
- ◆ Converts data from the “Stack” to physical signals on the “fieldbus”

- ◆ Transmission is “Synchronous Serial”; the clock is encoded in the signal using Manchester coding

- ◆ Signalling rate is 31.25 kbits/sec

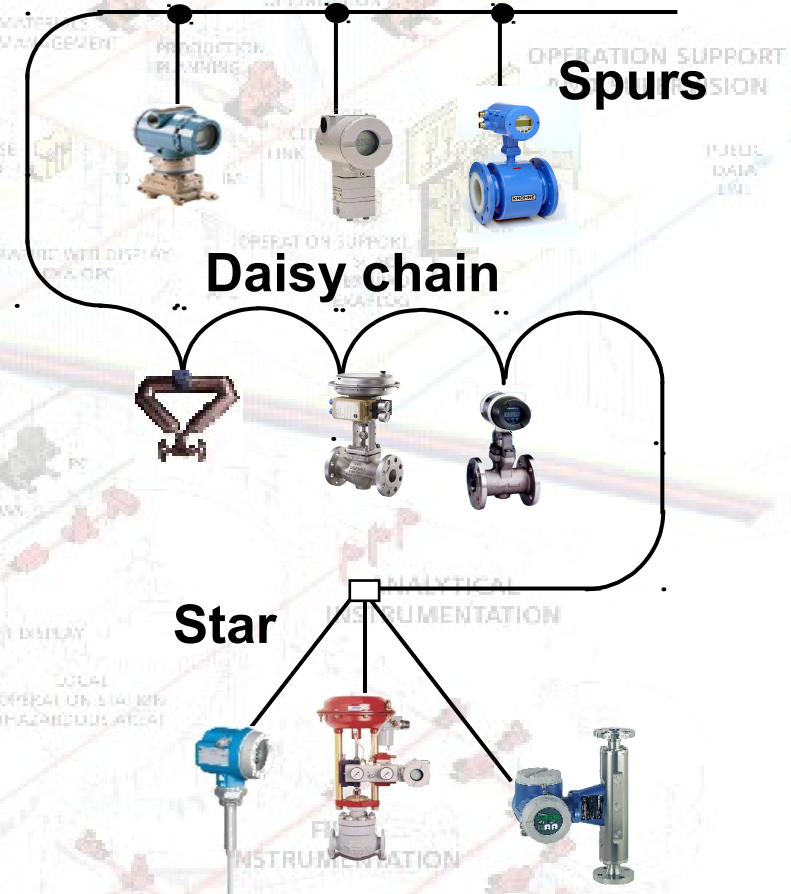
- ◆ Supports copper wire and optical fibres

- ◆ Supports Spur, Daisy chain and Chicken foot (star) bus topologies



H1 Physical Layer topology

- ◆ **Up to 32 devices per segment**
 - ◆ Depends on several factors
- ◆ **Uses (un-)shielded twisted pair cable**
 - ◆ Can use existing field wiring
 - ◆ Fibre optic cable is optional
- ◆ **Power down the bus**
- ◆ **Cable length up to 1900 m**
 - ◆ Depends on cable quality
 - ◆ Up to 9500 m using repeaters
- ◆ **Designed for intrinsic safety**





Number of devices on a H1 segment

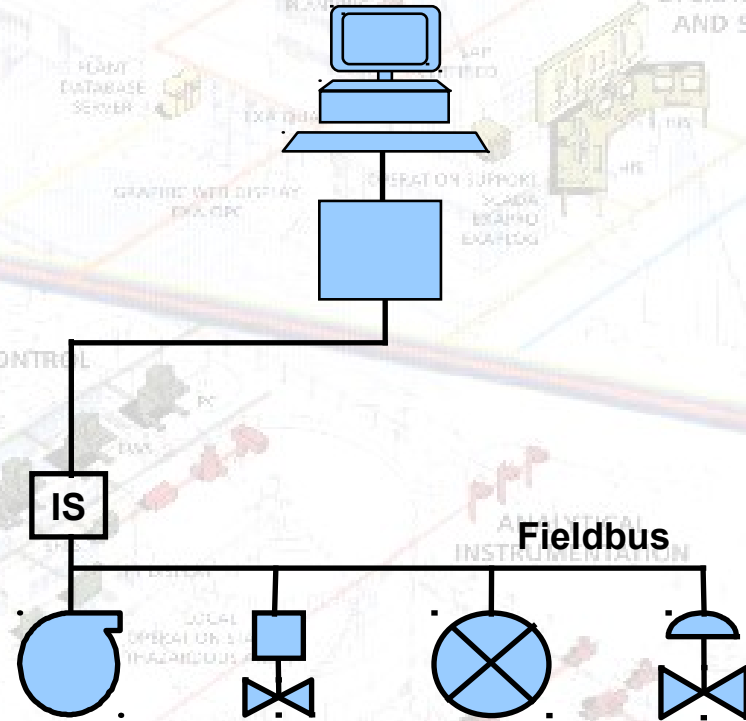
| | <u>Local Power</u> | <u>Non I.S.</u> | <u>I.S.</u> |
|---------------------|--------------------|-----------------|--------------|
| Rate | 31.25 kbit/s | 31.25 kbit/s | 31.25 kbit/s |
| Mode | Voltage | Voltage | Voltage |
| Topology | Bus/Tree | Bus/Tree | Bus/Tree |
| Power Supply | Separate | DC | DC |
| Devices recommended | 2 - 32 | 2 - 12 | 2 - 6 |

The maximum number of devices on a H1 fieldbus segment may be limited by the communication rates of the devices, the maximum number of addresses on a segment (240), or the available power.



Designed for intrinsic safety

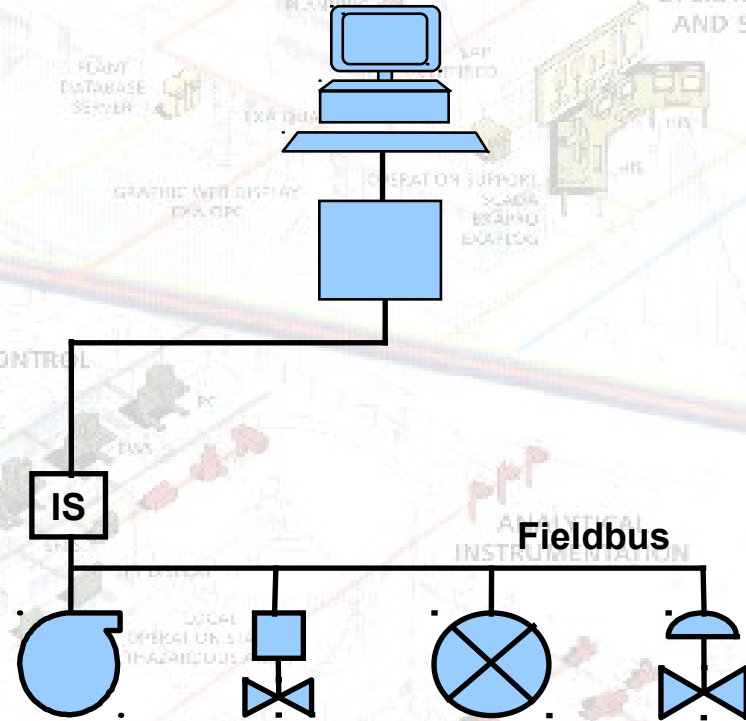
- ◆ Based upon “Entity” concept
- ◆ Bus power defined as 1.2 W max.
 - ◆ $U_s = 10.6 \text{ V}$
- ◆ Current available (cable type A)
 - ◆ 60 mA on a 1900 m segment
 - ◆ 90 mA on a 400 m segment
 - ◆ Gas group IIB or IIC
- ◆ Typically 4 devices on a segment
- ◆ Multi-barrier concept available



One IS barrier, one pair for many devices

Intrinsic safety - Future direction

- ◆ Based upon “FISCO” concept
- ◆ Bus power defined as
 - ◆ Gas group IIC - 1.9 W max.
 - ◆ Gas group IIB - 4.9 W max
 - ◆ $U_s = 12.6 V$
- ◆ Current available (cable type A)
 - ◆ 110 mA on a 750 m segment IIC
 - ◆ 200 mA on a 750 m segment IIB
- ◆ Typically:
 - ◆ 6 devices on a segment in IIC
 - ◆ 10 devices on a segment in IIB
- ◆ Multi-barrier concept available

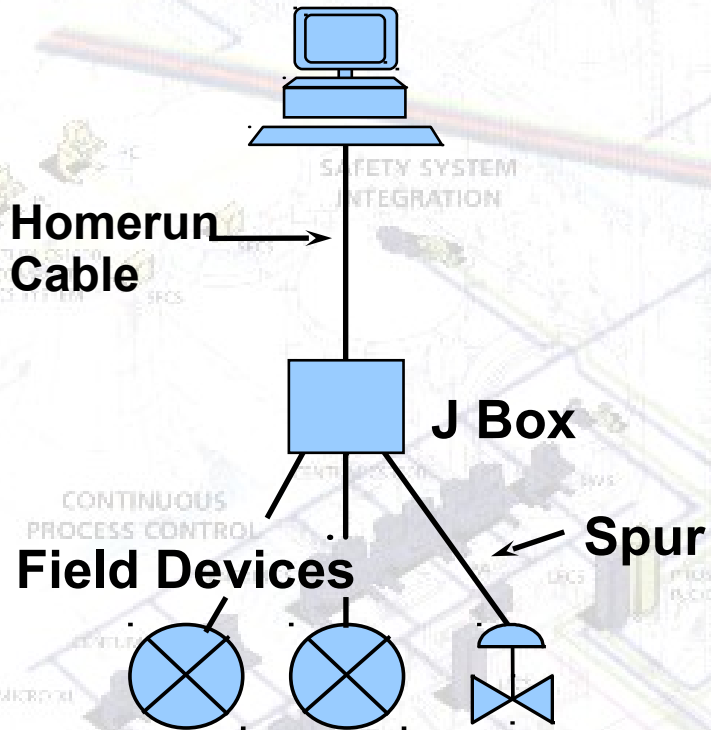


Cable type versus segment length

| <u>Cable Type</u> | <u>Gauge No.</u> | <u>Max. Length</u> |
|---|------------------|--------------------|
| A: Twisted-pair with Shield H1 (31.25 kbit/s) | #18AWG | 1900 m |
| B: Multi-twisted-pair with Shield H1 (31.25 kbit/s) | #22AWG | 1200 m |
| C: Twisted-pair without Shield H1 (31.25 kbit/s) | #22AWG | 400 m |
| D: Multi-core without Shield H1 (31.25 kbit/s) | #16AWG | 200 m |

Any existing, good quality #18 AWG twisted pair cable can be used for fieldbus.

H1 cable length calculation



| <u>Cable type</u> | <u>H1 total length *</u> |
|-------------------|--------------------------|
| A | 1900 m |
| B | 1200 m |
| C | 400 m |
| D | 200 m |

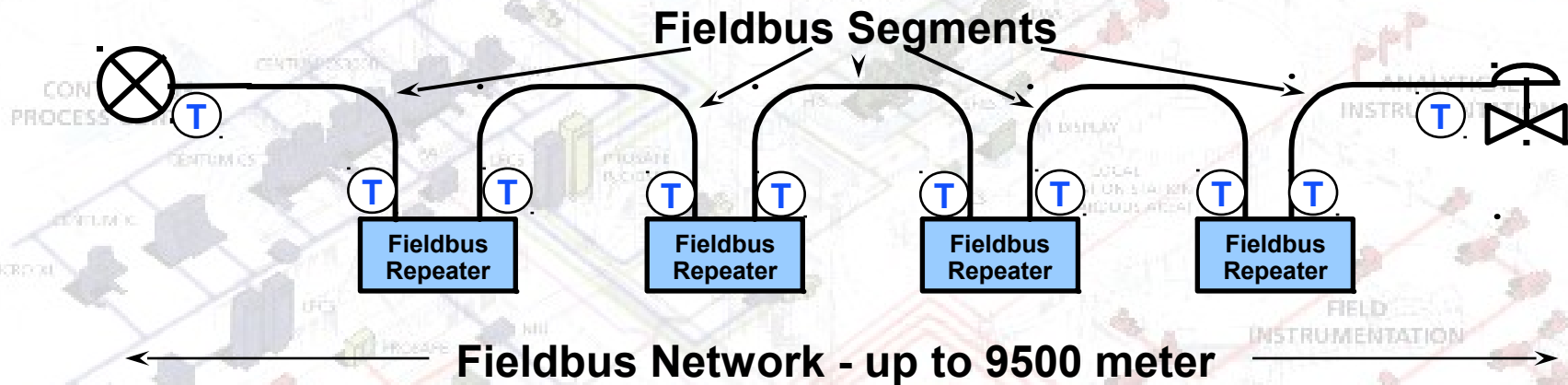
*** Total length including all spurs**

| <u># of devices</u> | <u>Total max Spur length **</u> |
|---------------------|---------------------------------|
| 25 - 32 | 1 m |
| 19 - 24 | 30 m |
| 15 - 18 | 60 m |
| 13 - 14 | 90 m |
| 2 - 12 | 120 m |

**** Maximum length of any spur**

Extending the length of a H1 segment

- ◆ Repeaters are used to extend the length of a segment
 - ◆ A repeater is an active device
- ◆ Up to 4 repeaters can be used on a segment
 - ◆ Maximum distance between any two devices on the network is 9500 meters



H1 communication stack

- ◆ IEC 61158 compliant

- ◆ Data Link Layer (DLL)

- ◆ Application Layer (AL)

- ◆ Establishes basic communication services between fieldbus devices

- ◆ Encoding and decoding of User Layer messages

- ◆ Deterministic control of message transmission

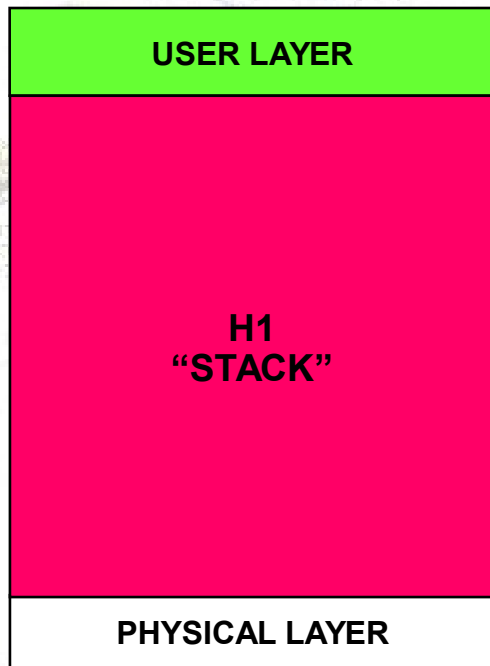
- ◆ Efficient and secure message transfer

- ◆ Supports scheduled messaging for time critical communication (Publisher/Subscriber)

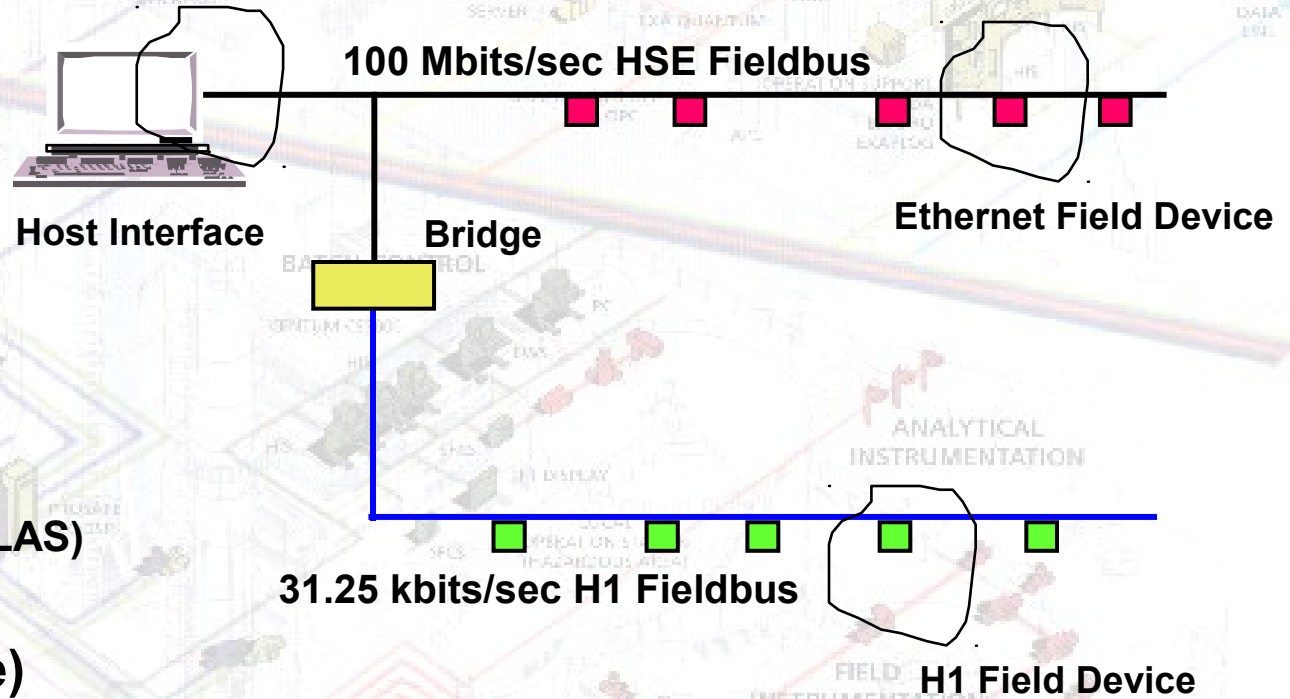
- ◆ Supports unscheduled messaging for request/response communication (Client/Server)

- ◆ Supports unscheduled messaging for Event Notification (multicast)

- ◆ Publishes the “time” on the bus



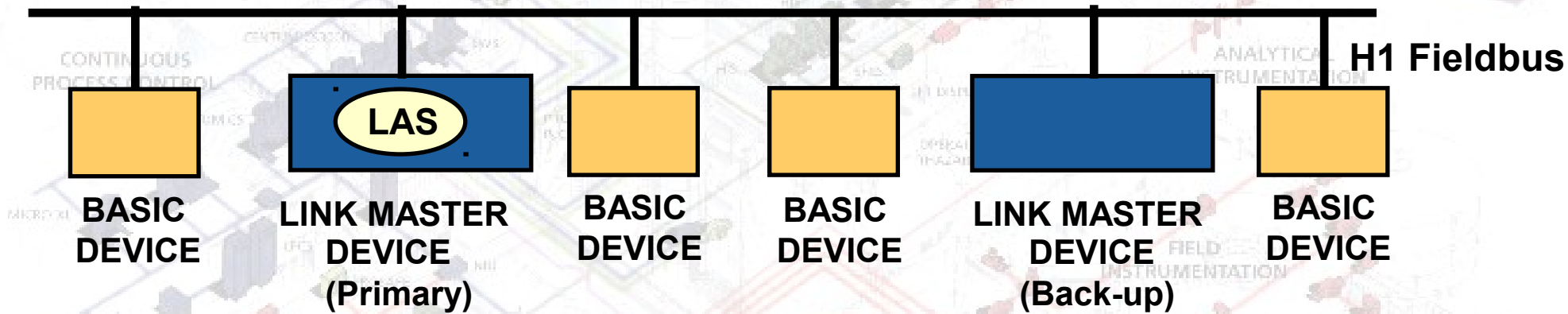
H1 device types



- ◆ Basic device
- ◆ Link Master device
 - ◆ Link Active Scheduler (LAS)
- ◆ Linking device (Bridge)

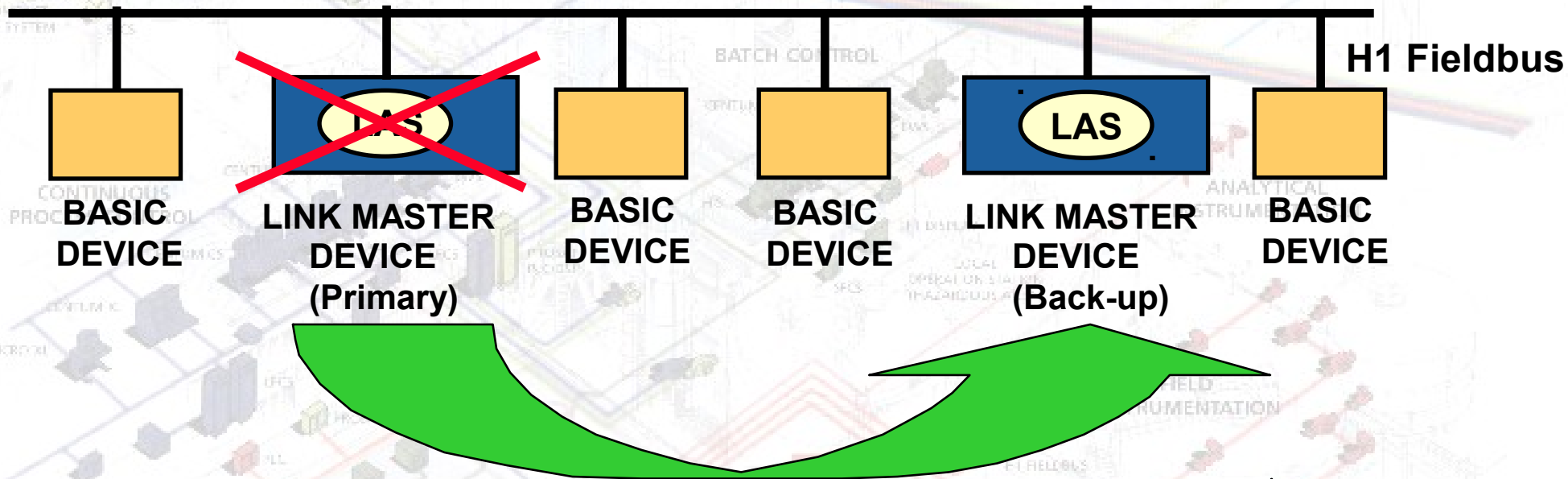
H1 Link Master - Link Active Scheduler (LAS)

- ◆ **Link Active Scheduler controls communication on the bus**
 - ◆ A device may send packets of information when permitted by the LAS
- ◆ **Maintains a list of all devices on the segment - “Live List”**
- ◆ **Distributes time to all devices on the segment**

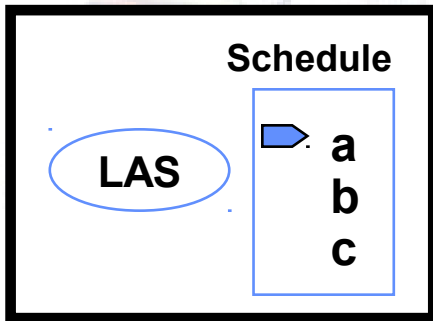


H1 Link Master redundancy - Back-up

◆ LAS function transferred when primary Link Mater fails!



Scheduled data transfer - step 1



LAS = Link Active Scheduler
P = Publisher
S = Subscriber
CD = Compel Data

Fieldbus Physical Medium

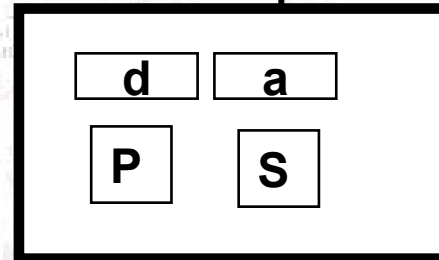
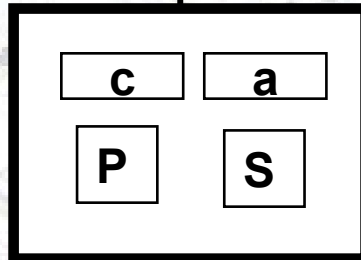
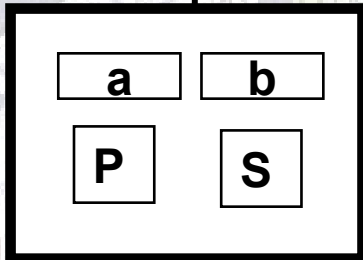
CD(x,a)



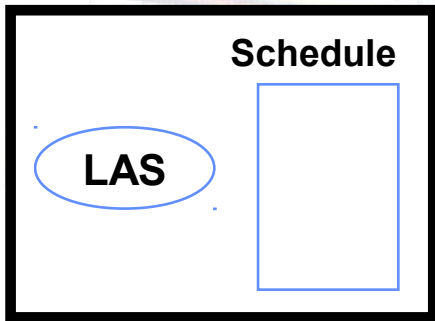
Device x

Device y

Device z

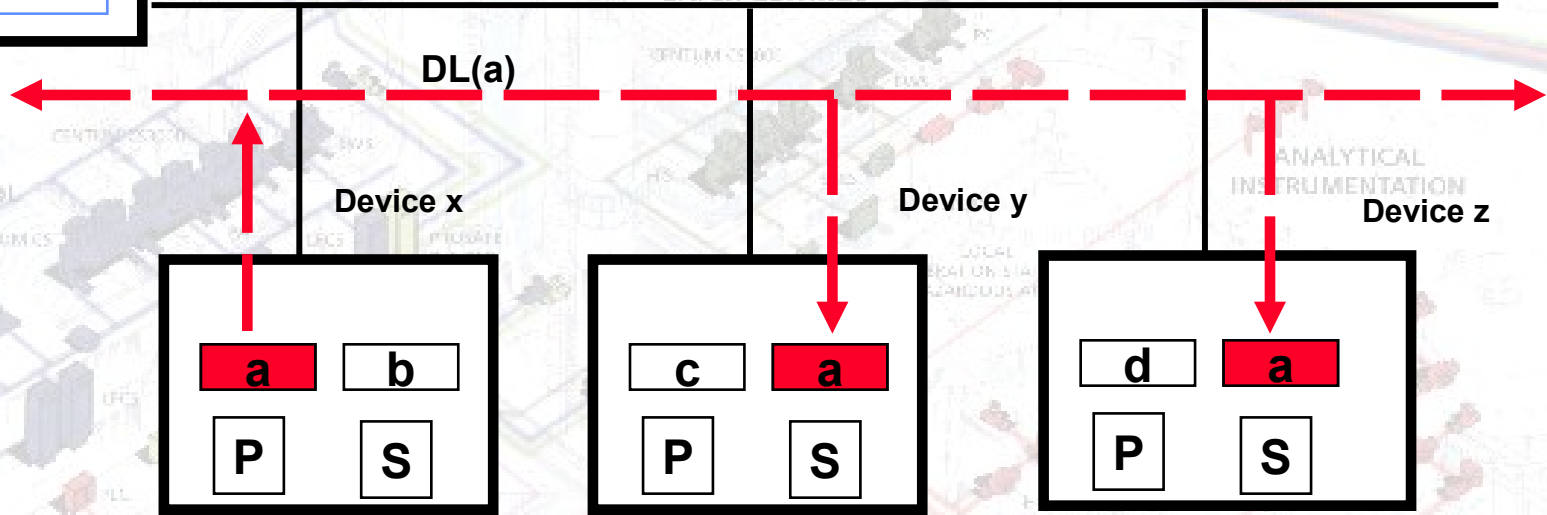


Scheduled data transfer - step 2

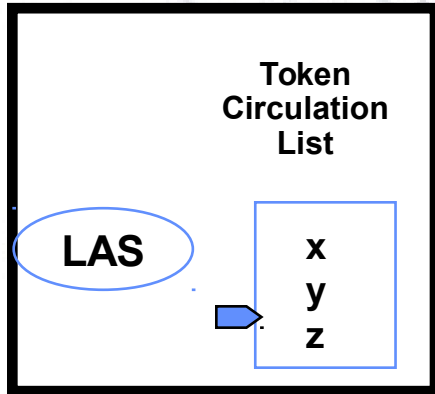


LAS = Link Active Scheduler
P = Publisher
S = Subscriber
DL = Data Link Packet

Physical Medium



Unscheduled data transfer step 1



LAS = Link Active Scheduler
P = Publisher
S = Subscriber
PT= Pass Token
M = Message

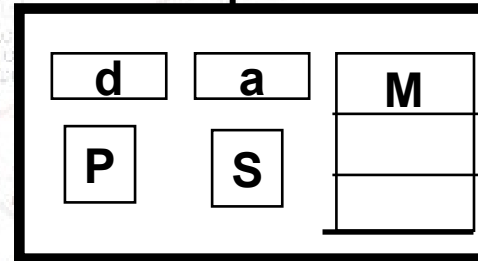
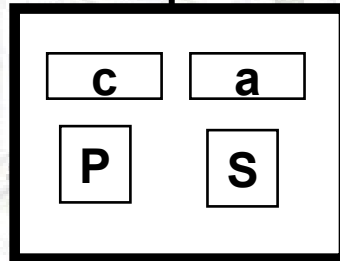
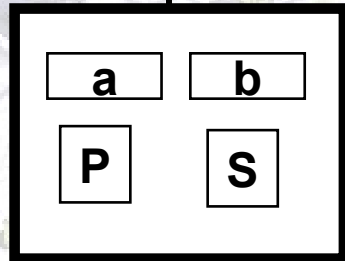
Physical Medium

PT(z)

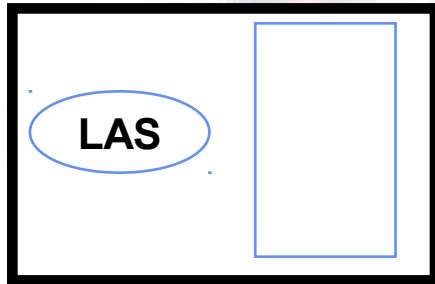
Device x

Device y

Device z

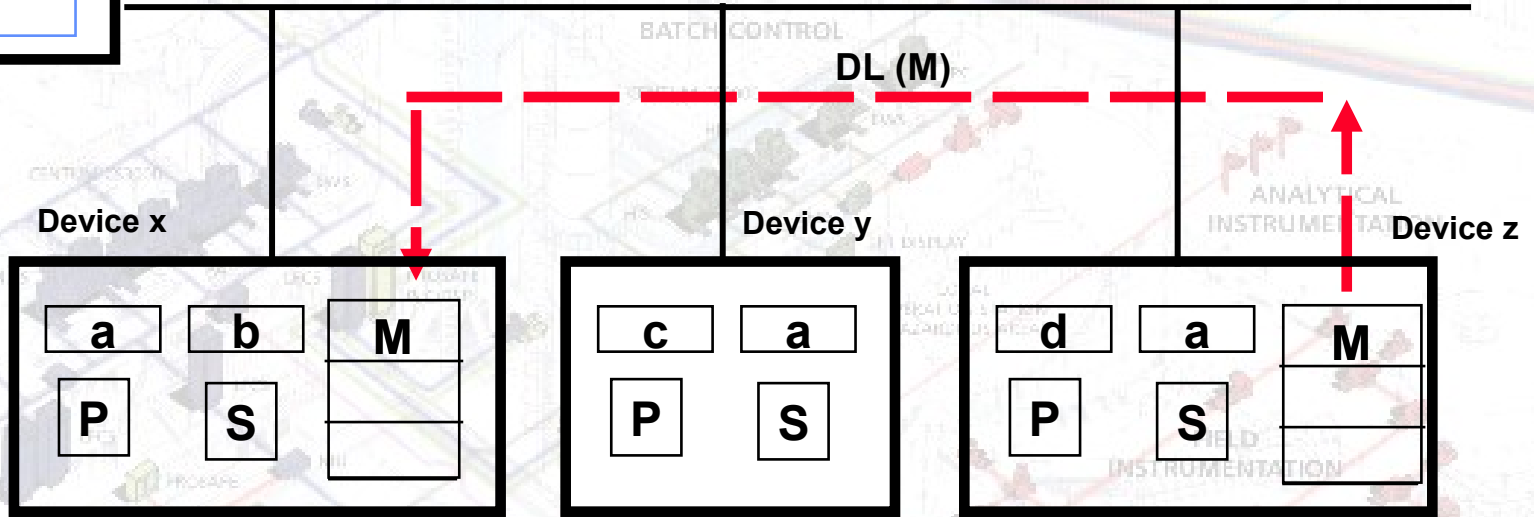


Unscheduled data transfer step 2

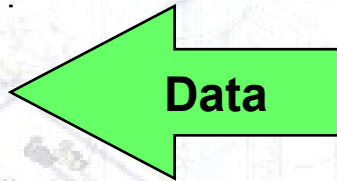
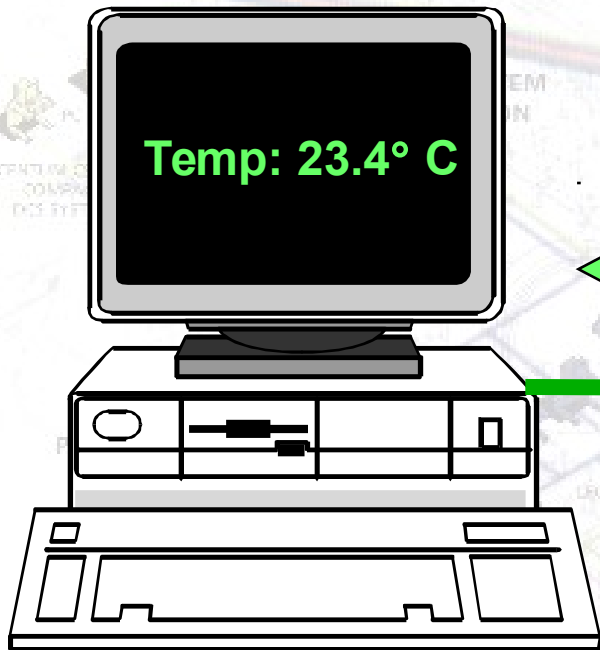


LAS = Link Active Scheduler
P = Publisher
S = Subscriber
PT= Pass Token
M = Message

Physical Medium



Publisher/Subscriber



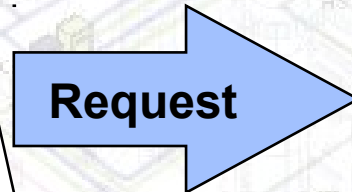
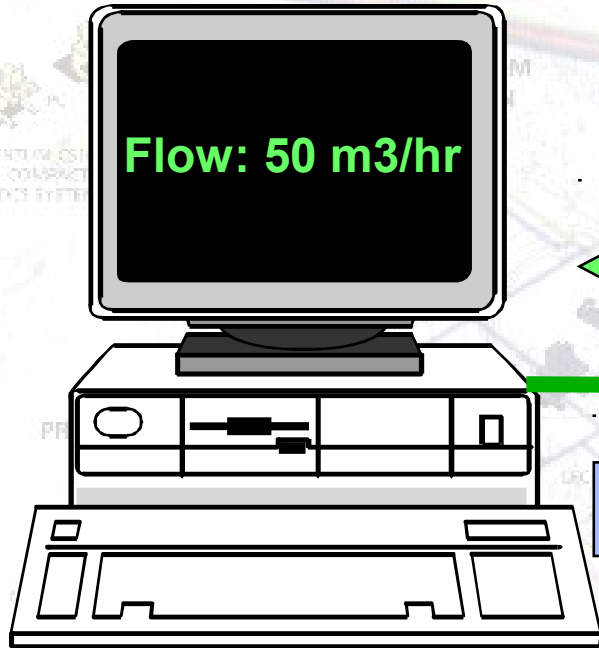
- ◆ Synchronous data transfer
- ◆ Network scheduled
- ◆ Deterministic - control
- ◆ One-to-many
- ◆ Unidirectional
- ◆ Used for publishing data



Compel Data



Client/Server



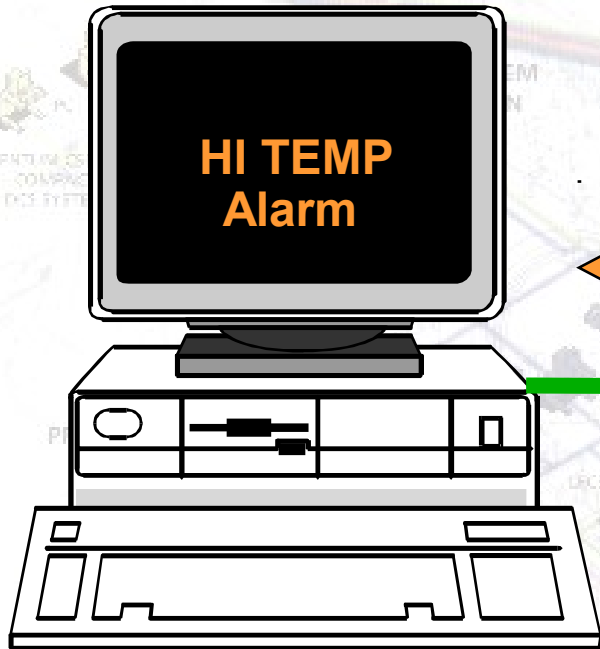
- ◆ Asynchronous data transfer
- ◆ Unscheduled
- ◆ One-to-one
- ◆ Bi-directional
- ◆ Used for operator messages



Pass Token

Event notification

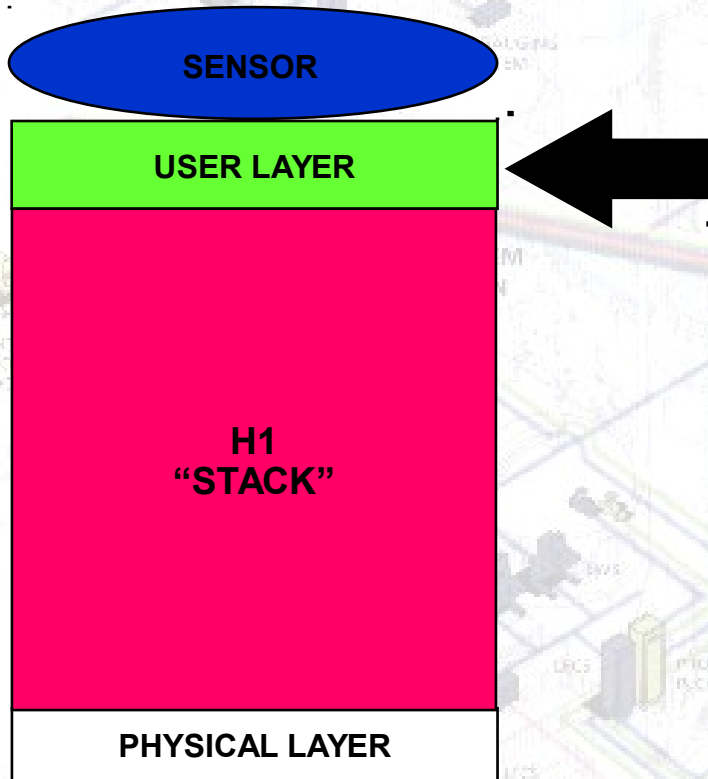
- ◆ Asynchronous data transfer
- ◆ Unscheduled
- ◆ One-to-many
- ◆ Uni-directional
- ◆ Used for event notification and trend reports



Pass Token



H1 User Layer - Unique differentiator



- ◆ Provides the interface with the process
 - ◆ and for user interaction with the host system
- ◆ Standard Function Blocks
 - ◆ Consistent definition of data for integrated and seamless distribution of functions in field devices from different manufacturers
- ◆ System Management
 - ◆ Deterministic scheduling of function blocks
- ◆ Device descriptions
 - ◆ Host system to operate the device without the need for custom programming
- ◆ Common File Format
 - ◆ Off-line "system" configuration by host system

Minimum 3 blocks reside in a device

◆ The Resource Block

- ◆ Describes the characteristics of a device
- ◆ Contains manufacturer information

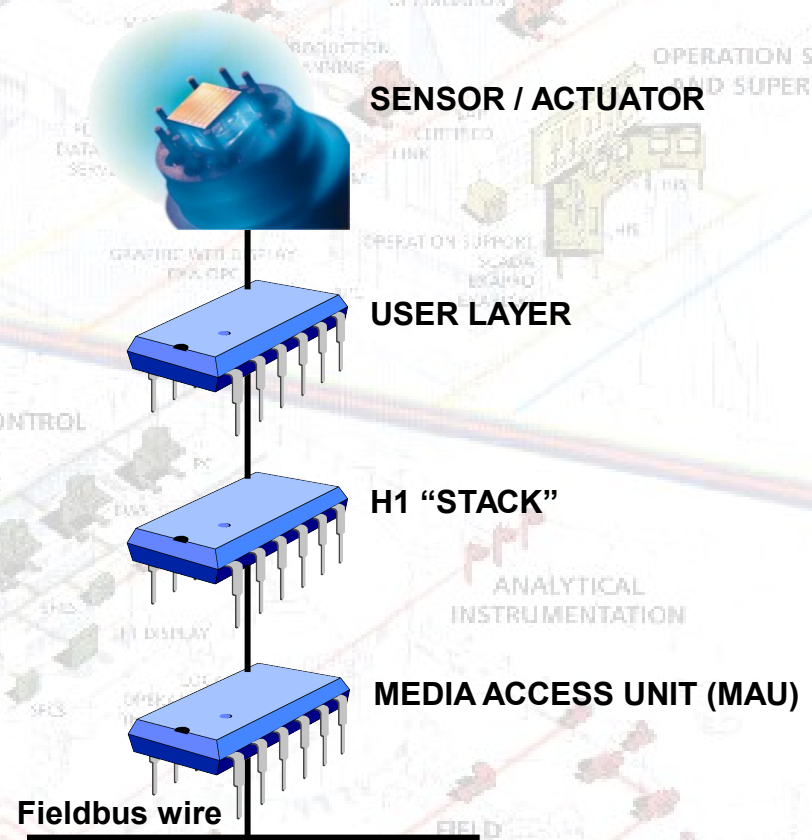
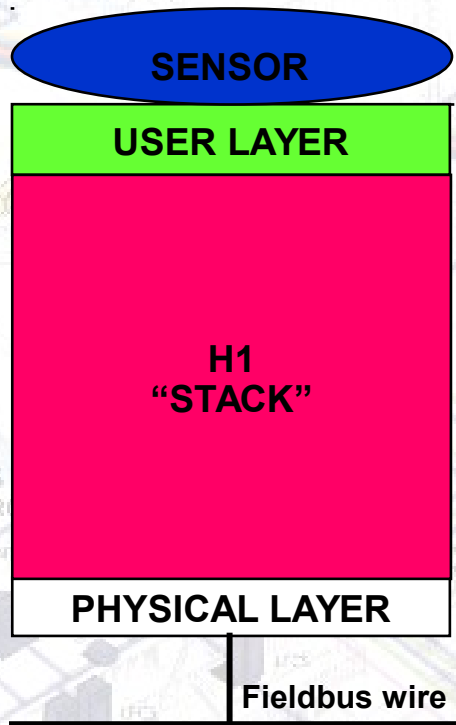
◆ The Transducer Block

- ◆ Physical I/O interface with the actual sensor or actuator
- ◆ Performs A/D conversions, square root extraction, linearisation etc.
- ◆ Transmits/receives information to/from Function Blocks
- ◆ The Transducer Block is the window to the process - diagnostics

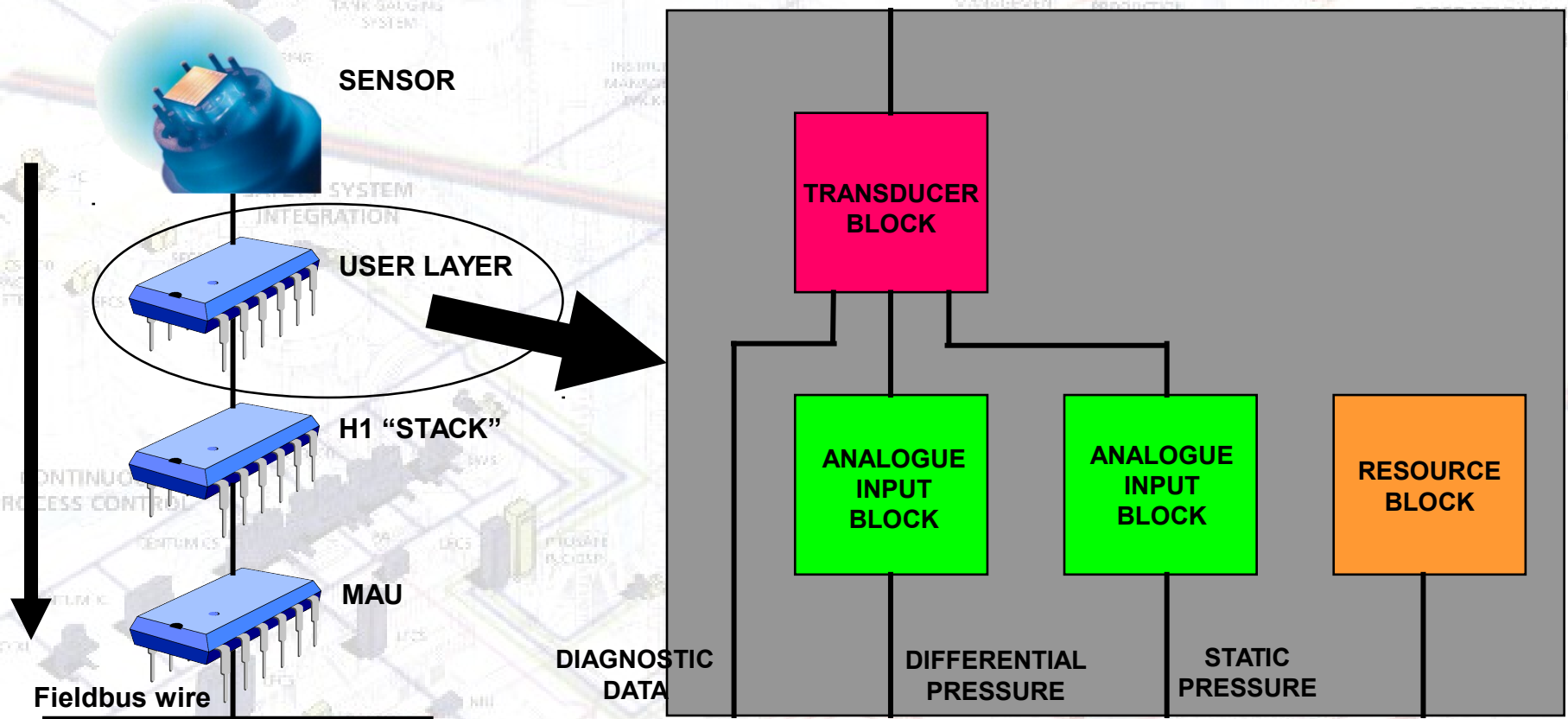
◆ Function Blocks

- ◆ Similar to the function blocks in today's DCS and PLC systems
- ◆ Mandatory is at least one Function Block depending on the type of device

H1 practical implementation



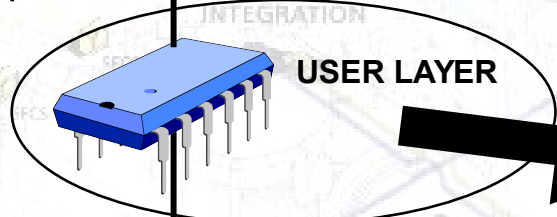
Differential pressure transmitter - example



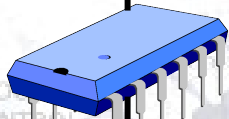
Valve positioner - example



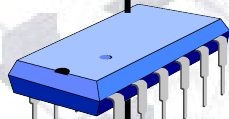
ACTUATOR



USER LAYER



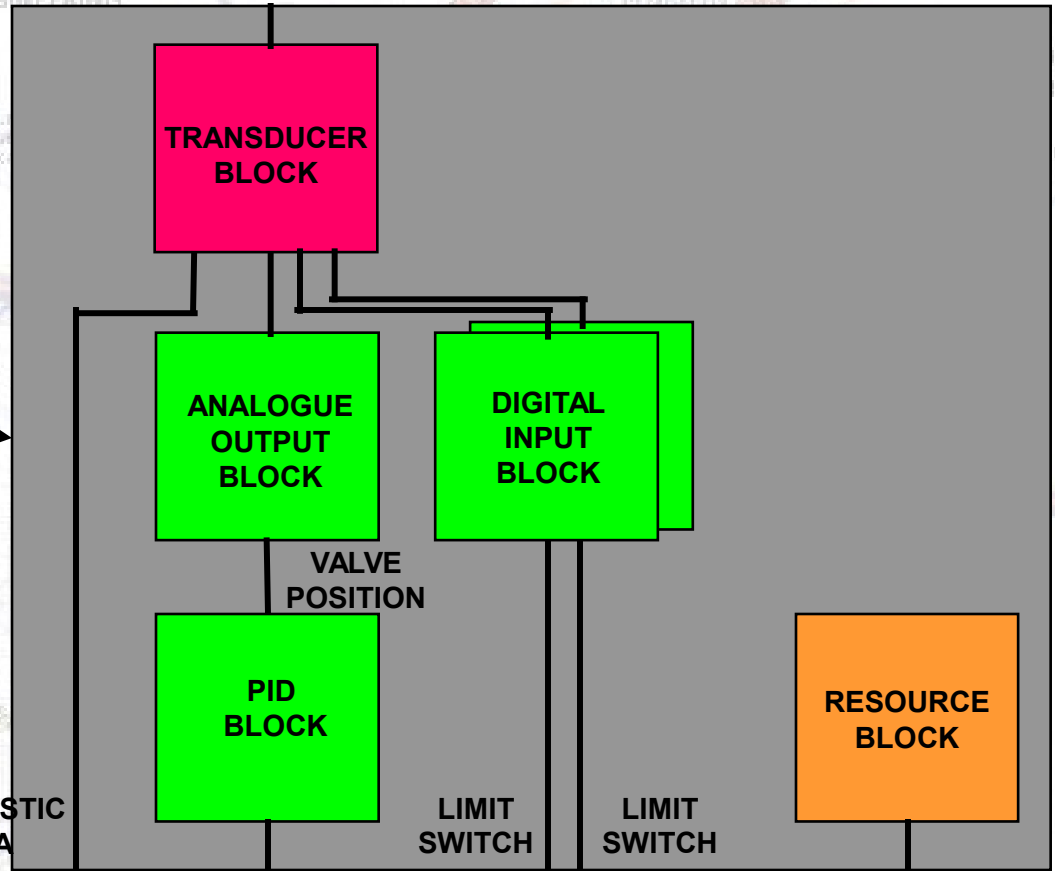
H1 "STACK"



MAU

Fieldbus wire

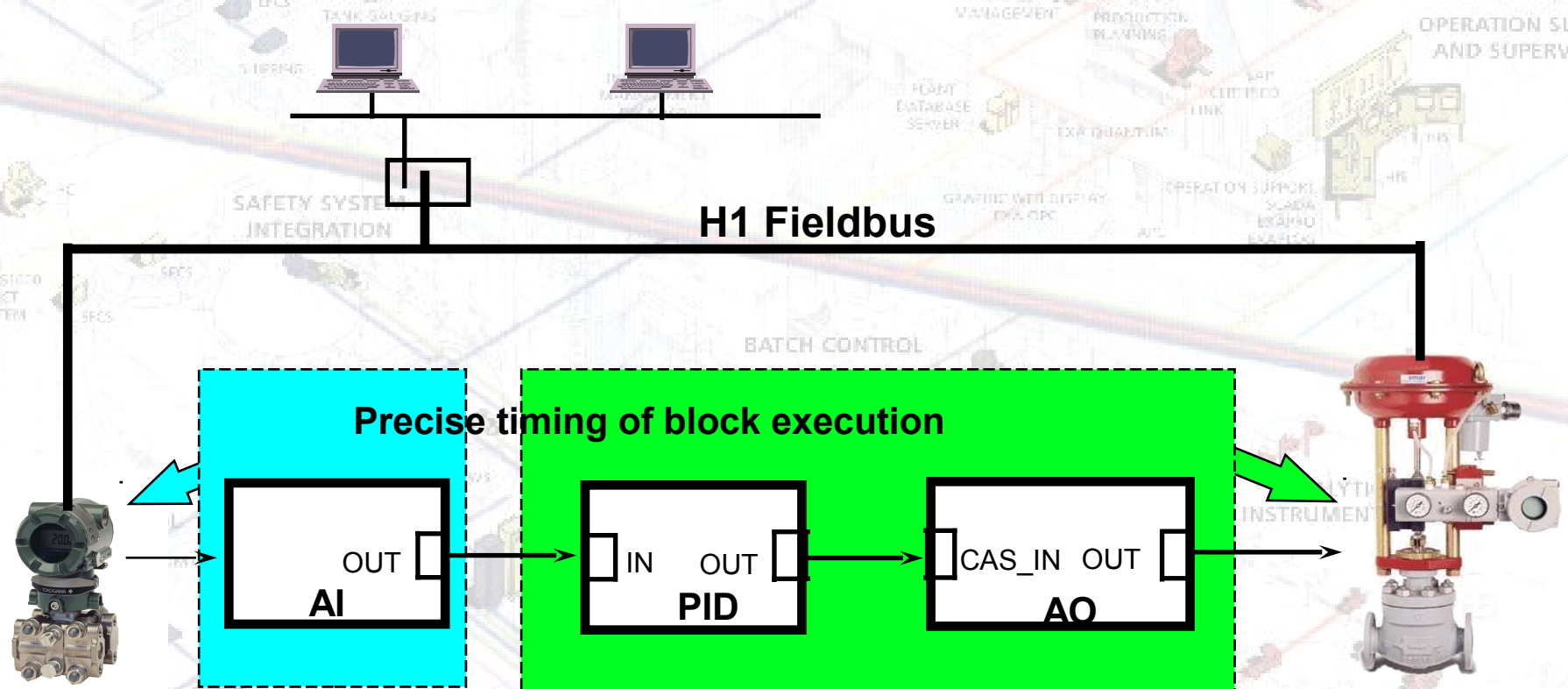
DIAGNOSTIC DATA



Function Blocks

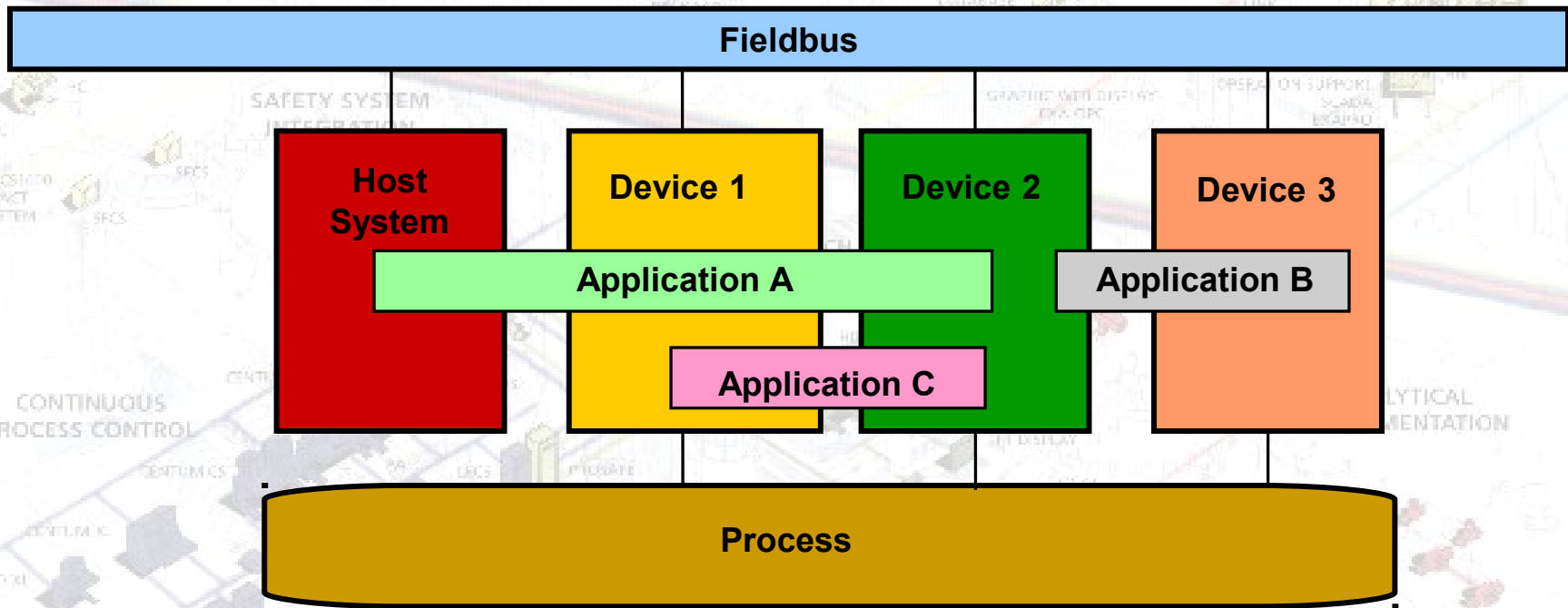
- ◆ **Monitor and control process applications**
 - ◆ Input blocks - AI, DI
 - ◆ Output blocks - AO, DO
 - ◆ Control blocks - PID, Ratio, Signal Characteriser, Lead/Lag etc.
- ◆ **Reside in any field device and/or host system**
 - ◆ Simple control functions may migrate into field devices
- ◆ **Form deterministic control schemes**
 - ◆ Interconnect over the bus to implement an integrated control strategy
 - ◆ Interconnect to blocks in the host as part of an advanced control scheme
- ◆ **Execute periodically - cyclically**

Control functions migrate into the field





Distributed control applications



Function Block structure

◆ Block appearance is standardised

◆ Algorithms are vendor specific

◆ Room for “differentiation”

◆ Consistent, easy, block configuration

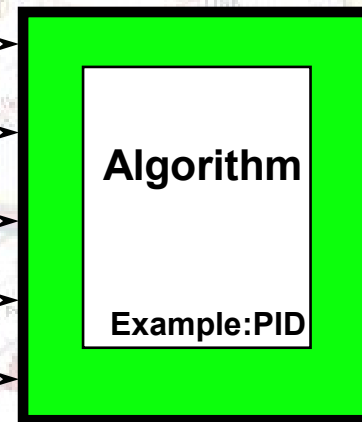
◆ Consistent definition of information being communicated

◆ Standardised status indication

◆ Common set of modes

◆ Standard method of mode propagation

oriented
Inputs

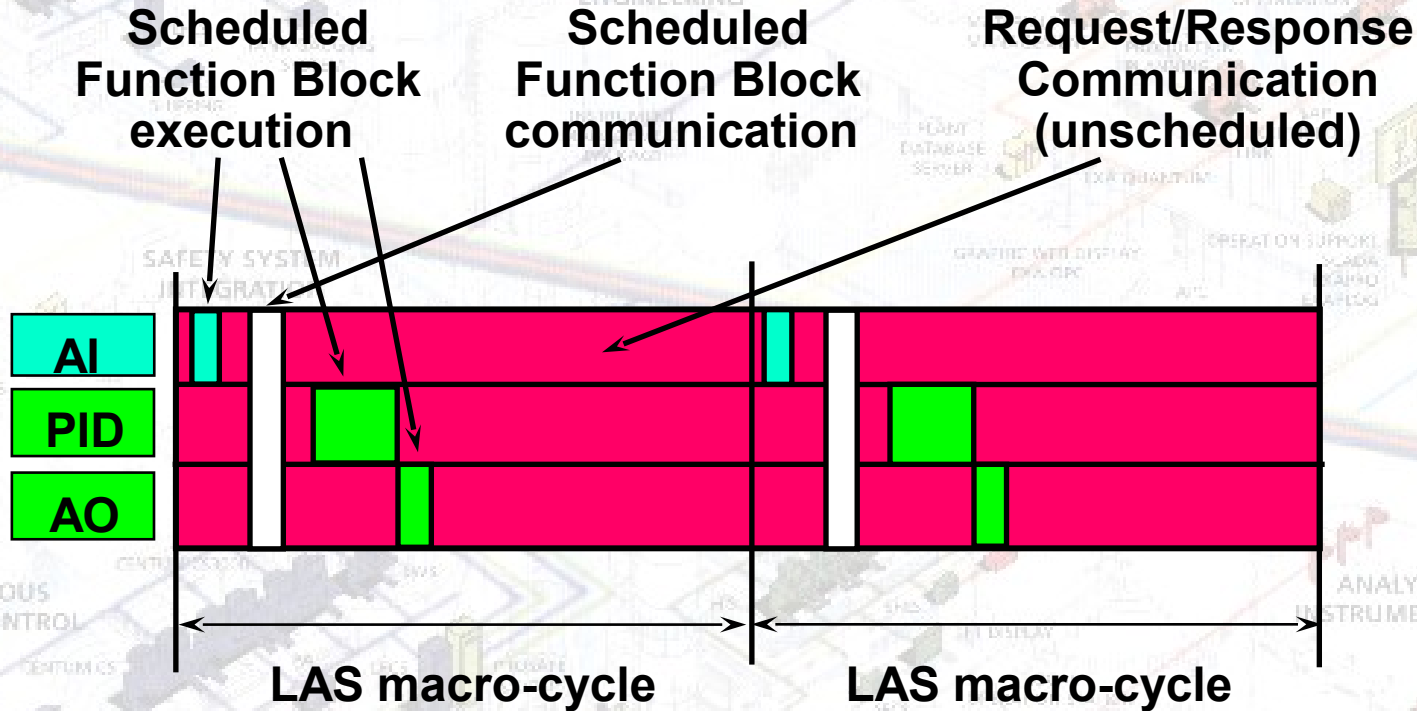


Alarm Subsystem

Mode Structure
(Manual, Auto, etc.)

Event Subsystem

H1 Function Block execution scheduling



- ◆ Precise timing of block execution - cyclic
- ◆ Function Block communication over the bus is immediate



Device Descriptions (DD's)

- ◆ Extended description of the capability of a field device
- ◆ Written in a standard Device Description Language (DDL)
- ◆ DDL technology implements the FF interoperability concept
- ◆ Interpreted by host system and provide the information needed by the host to see and use field devices
 - ◆ Provided on CD or floppy or may be uploaded from the field device
- ◆ Standard and Incremental DD's
 - ◆ Standard DD's for standard Fieldbus Foundation device profiles, including Function Blocks and Transducer Blocks
 - ◆ "Incremental" DD's to define manufacturer-specific extensions





Common File Format (CFF)

- ◆ Describes the functions and capabilities of a field device
- ◆ In conjunction with Device Descriptions allows data exchange among device manufacturers, system builders and end-users
 - ◆ Capabilities File
 - ◆ Electronic form of device specification - used for device configuration
 - ◆ Value File
 - ◆ Data to be downloaded
 - ◆ Uploaded data from devices
 - ◆ Both are standard ASCII text files for human readability
- ◆ Enable a host system to configure the system off line
 - ◆ Yokogawa complies - Yokogawa's main contribution to FF specifications



What is “Interoperability”?

- ◆ The ability to implement control strategies on a system implemented with devices from multiple vendors
- ◆ Delivered by:
 - ◆ Standard Physical Layer
 - ◆ Standard communication protocol (Stack)
 - ◆ Standard function blocks
 - ◆ Device descriptions
 - ◆ Common File Format
- ◆ Freedom for end-users to chose “Best in Class” solutions
- ◆ The ability to substitute a field device from one vendor for that of another vendor without loss of functionality

Interoperability fulfils the expectations of ...

◆ Basic interfacing

- ◆ Interconnectivity

◆ Support for innovation

- ◆ Seamless integration of new device features

◆ Substitution

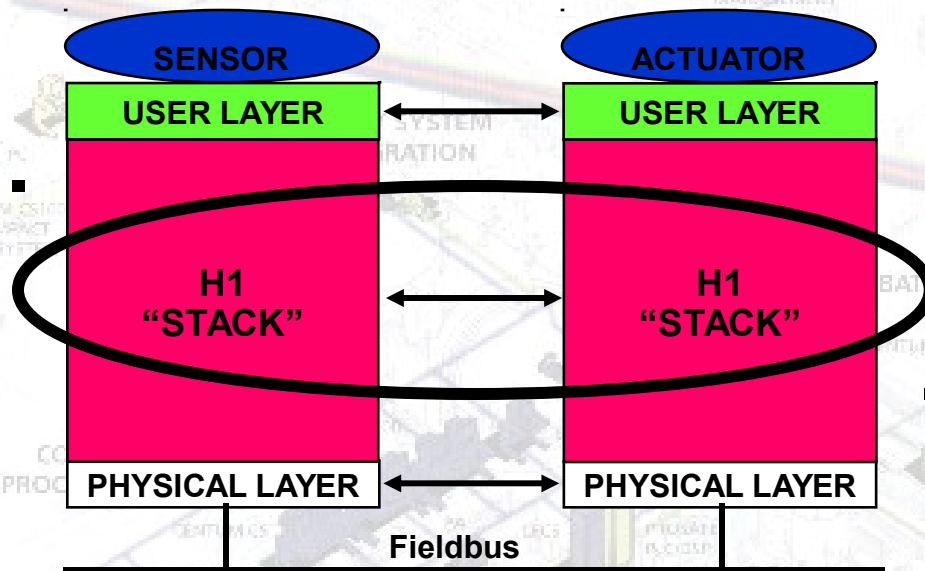
- ◆ Replacement of similar devices from different manufacturers
- ◆ Expectation established by the analogue 4-20 mA standard
- ◆ Substitution requires re-configuration

◆ All layers of the OSI model **plus** User Layer must interoperate

- ◆ Physical Layer, Communication Stack and User Layer

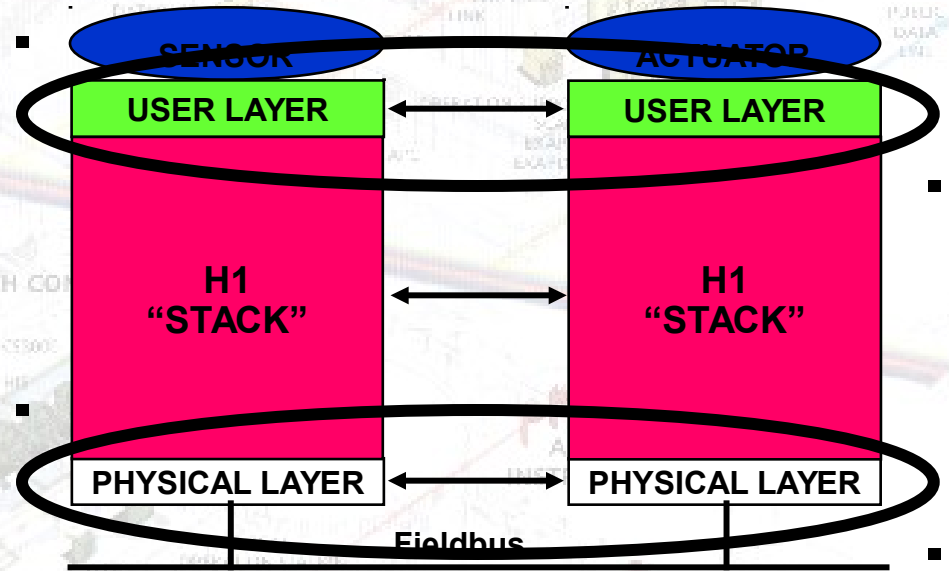
Conformity and Interoperability test procedure

Stack conformity testing



- ◆ Stack registration
- ◆ 20 different stacks registered
 - ◆ Basic and Link Master devices

Device interoperability testing



- ◆ Device registration
- ◆ 100 different devices registered
 - ◆ Key to interoperability

Will “interoperability” improve

- ◆ Not all layers interoperate - tighten the specification
- ◆ Capabilities File imperfections - vendors to fix
 - ◆ Response time; device expects to have a response within “x” seconds
- ◆ Bug’s in stack conformity tester - to be fixed
- ◆ Lack of capability - parameters not in non-volatile RAM
 - ◆ Problem reoccurs at power up; requires down load - vendors to fix
- ◆ Host System testing being debated
- ◆ Common File Format is key to interoperability
 - ◆ Yokogawa complies - Yokogawa’s main contribution to FF specifications



FOUNDATION™ Fieldbus High Speed Ethernet

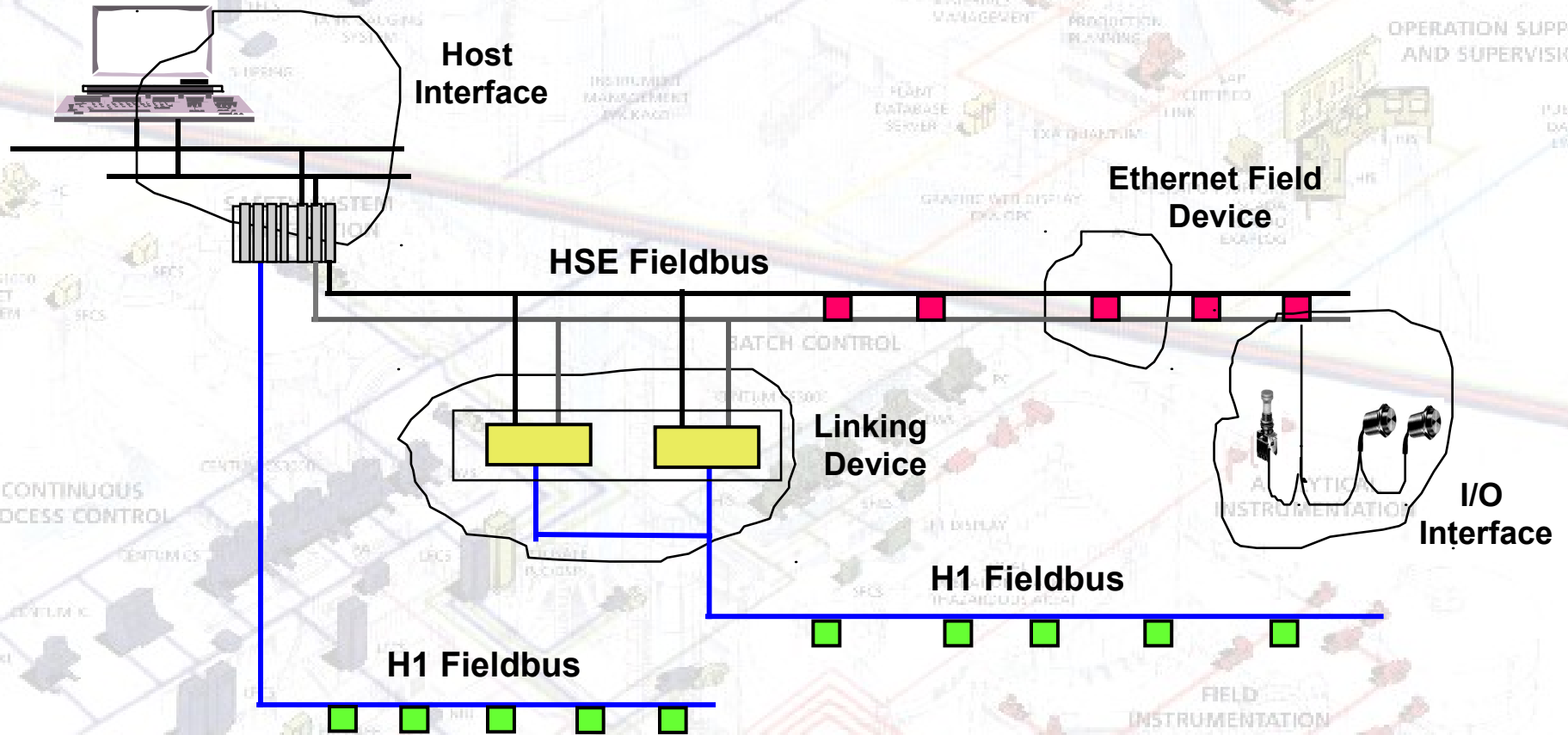


**THE PATH TO
FIELDBUS**





FOUNDATION™ Fieldbus topology

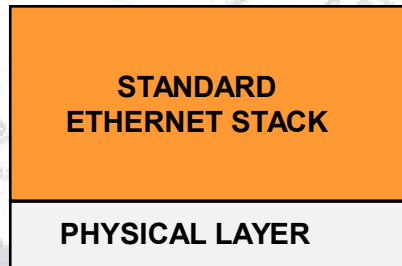




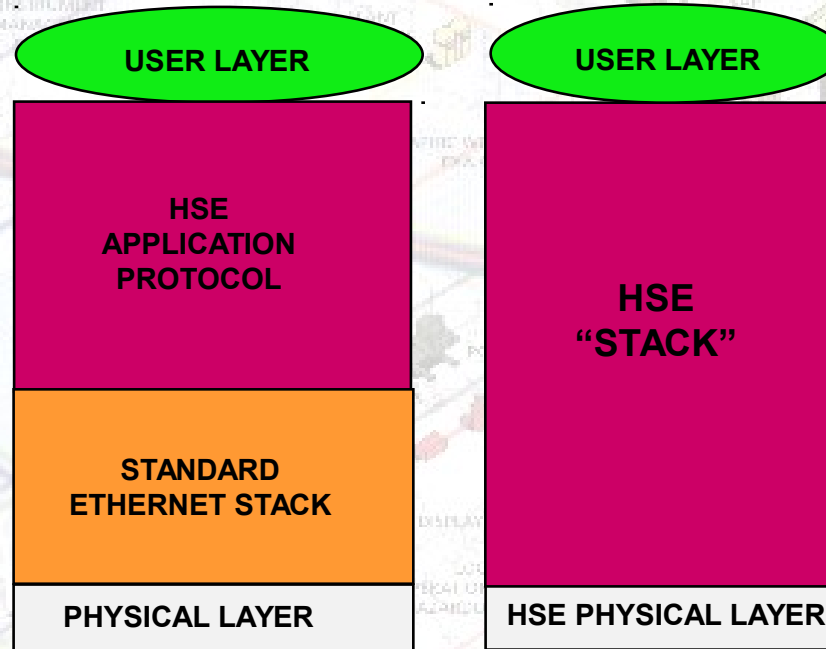
The HSE FOUNDATION™ Fieldbus model

OSI model based

COTS
Commercial Of The Shelve
Ethernet equipment



FOUNDATION™ Fieldbus HSE Model

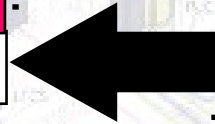
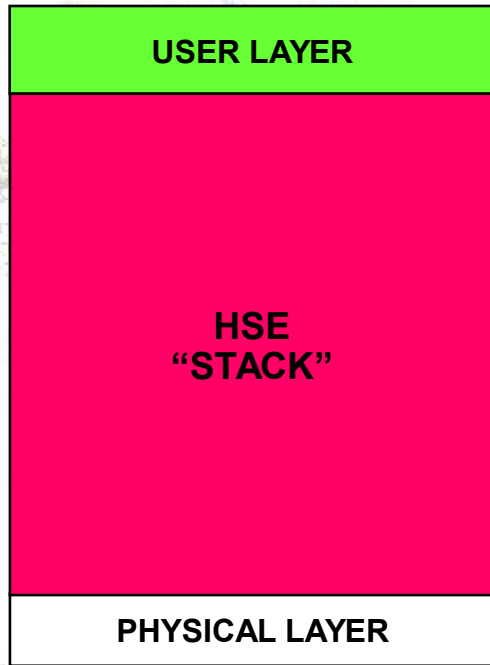


The Application Layer is not defined in Ethernet



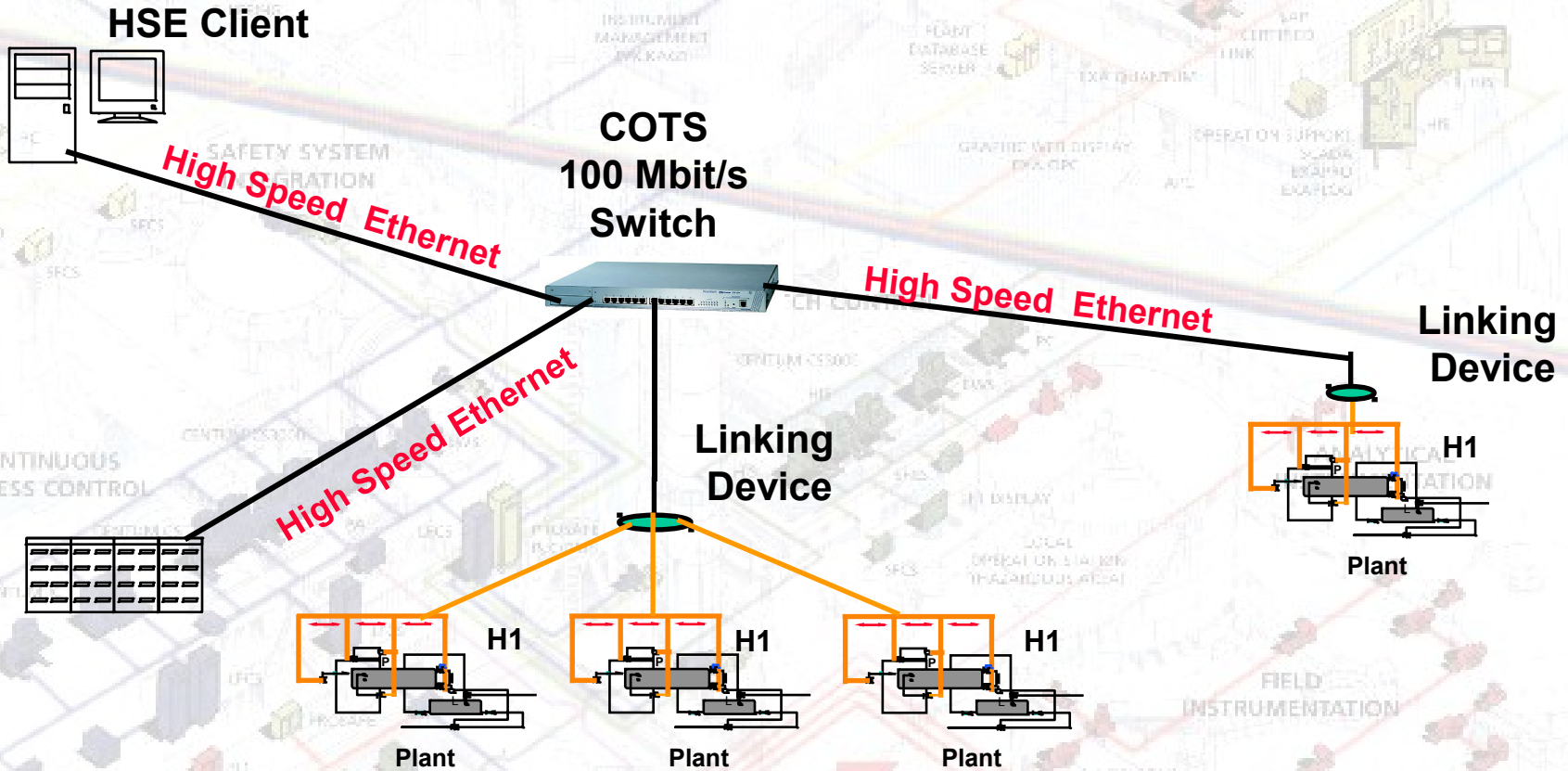
HSE Physical Layer

- ◆ High speed backbone
- ◆ Converts data from the “Stack” to physical signals on the “fieldbus”
 - ◆ Uses standard Ethernet electronics
 - ◆ Supports redundant media and devices
 - ◆ Provides interface to other protocols
- ◆ Transmission is TCP/IP
 - ◆ Collision detection
- ◆ Signalling rate is 100 Mbits/sec
- ◆ Supports copper wire and optical fibres
 - ◆ Up to 100 m using shielded twisted pair cable
 - ◆ Up to 2000 m using optical fibres





FOUNDATION™ Fieldbus integrated network

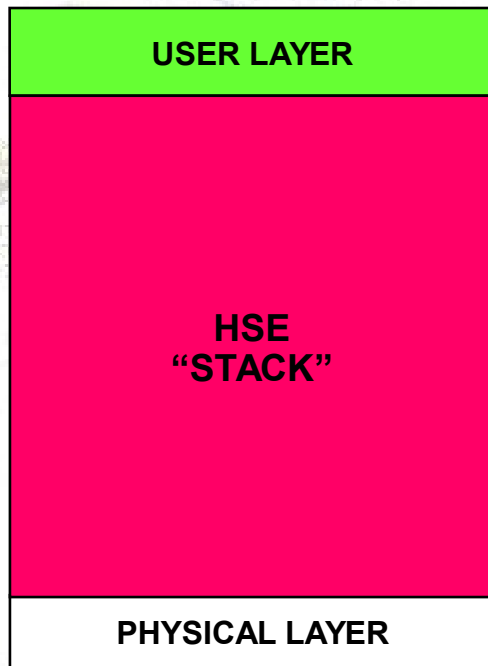


HSE communication stack

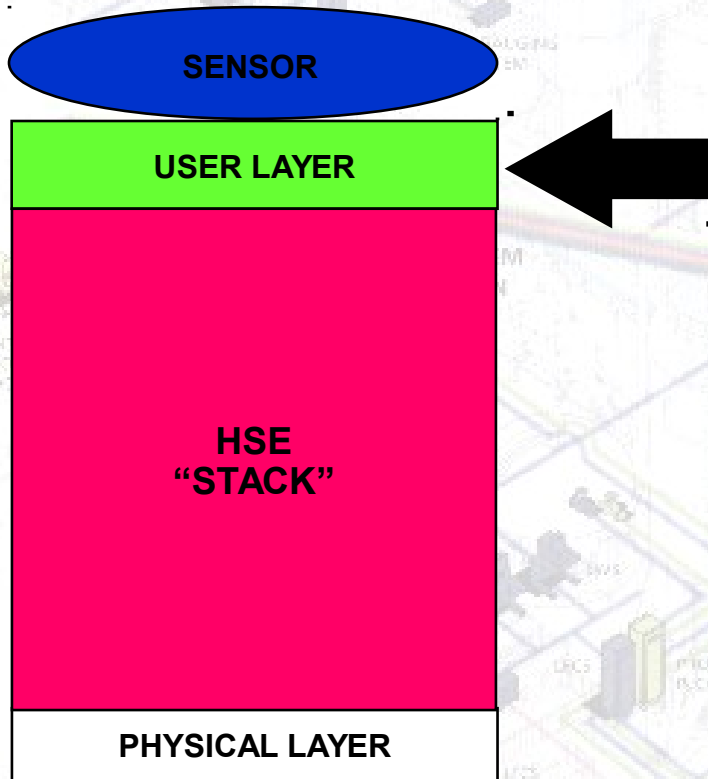
- ◆ HSE stacks consists of
 - ◆ Standard Ethernet stack
 - ◆ FF-HSE Application Protocol

- ◆ Establishes basic communication services between Ethernet devices

- ◆ Encoding and decoding of User Layer messages
- ◆ Deterministic control of message transmission
- ◆ Efficient and secure message transfer
- ◆ Supports scheduled messaging for time critical communication (Publisher/Subscriber)
- ◆ Supports unscheduled messaging for request/response communication (Client/Server)
- ◆ Supports unscheduled messaging for Event Notification (multicast)
- ◆ Provides Bridging and Redundancy



HSE User Layer - Unique differentiator



- ◆ Provides the interface with the process
 - ◆ and for user interaction with the host system
- ◆ Standard Function Blocks
 - ◆ Consistent definition of data for integrated and seamless distribution of functions in Ethernet (field) devices from different manufacturers
- ◆ System Management
 - ◆ Deterministic scheduling of function blocks
- ◆ Device descriptions
 - ◆ Host system to operate the device without the need for custom programming
- ◆ Common File Format
 - ◆ Off-line "system" configuration by host system

Flexible Function Blocks

◆ Extends the Function Block model into Discrete Manufacturing

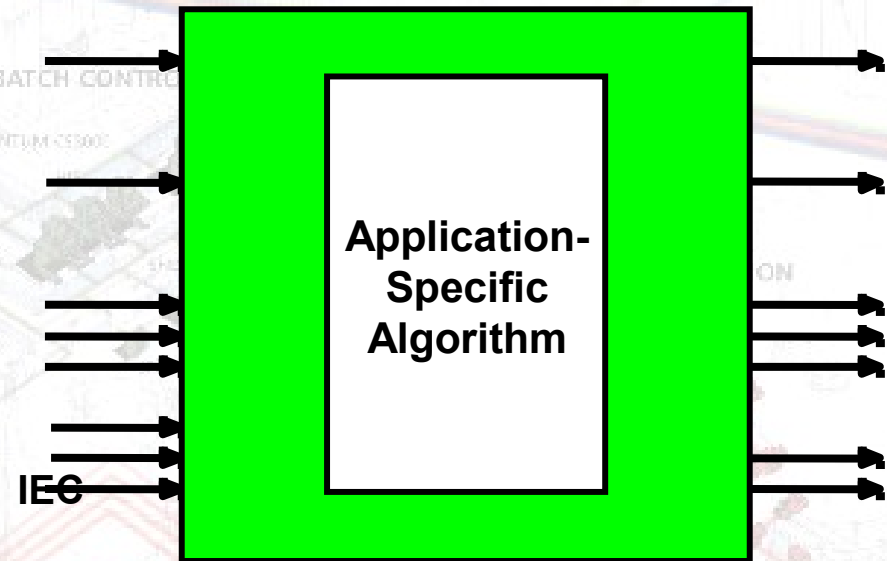
◆ Multiple I/O (MIO) Blocks

- ◆ 8 channels per block
- ◆ Multiple Analogue Input
- ◆ Multiple Analogue Output
- ◆ Multiple Discrete Input
- ◆ Multiple Discrete Output

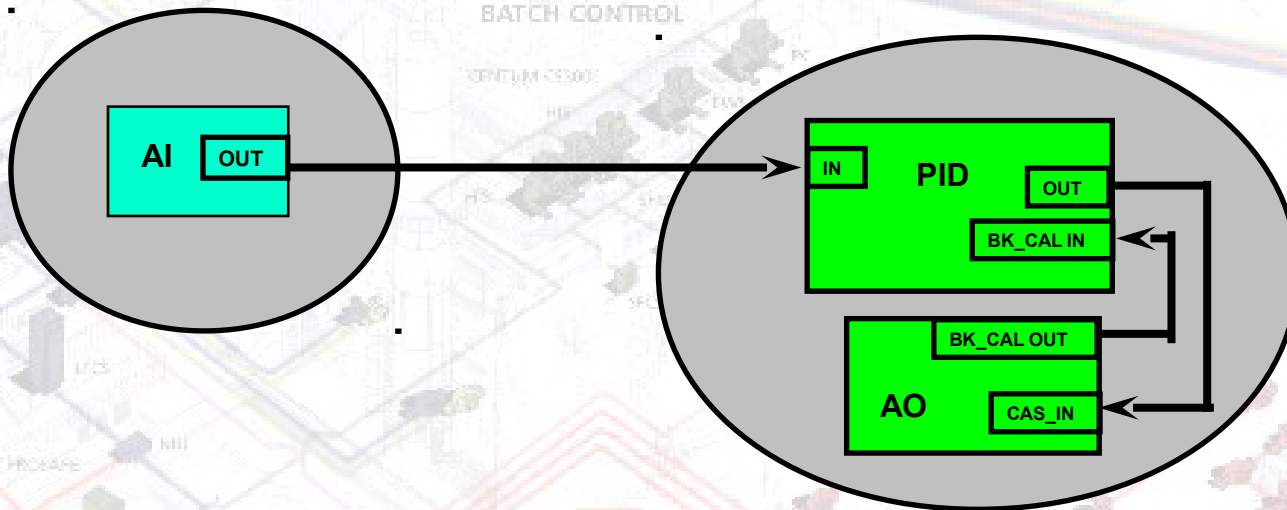
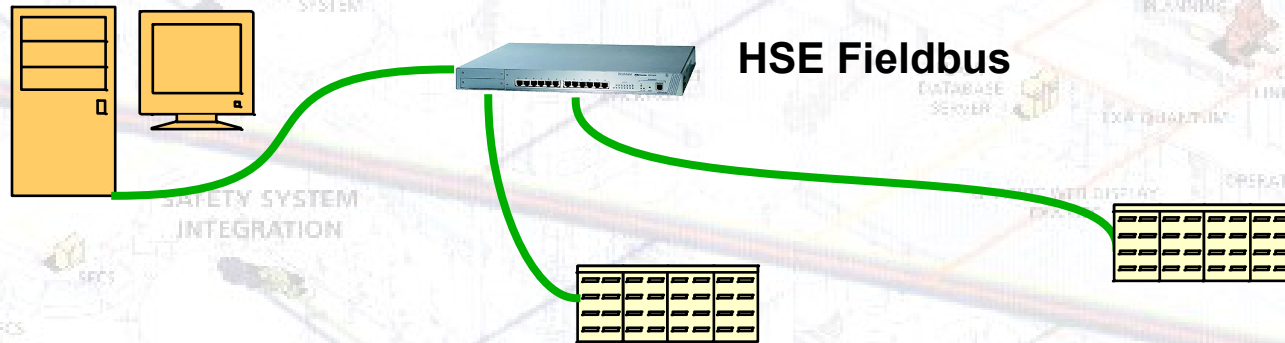
◆ Flexible Specific Blocks

- ◆ Application specific algorithm
- ◆ 61131 compliant

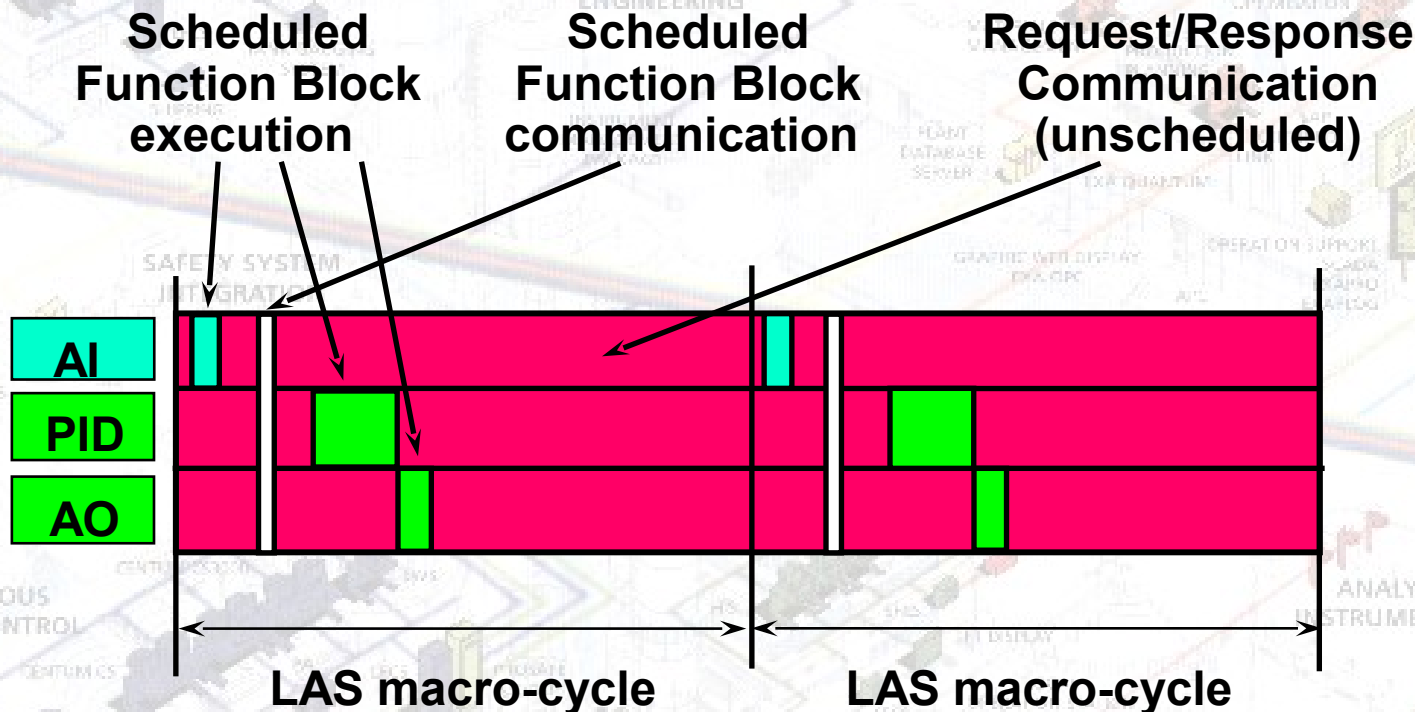
FFB is a “Wrapper” for an Application-specific Algorithm



Distributed control functions



HSE Function Block execution scheduling

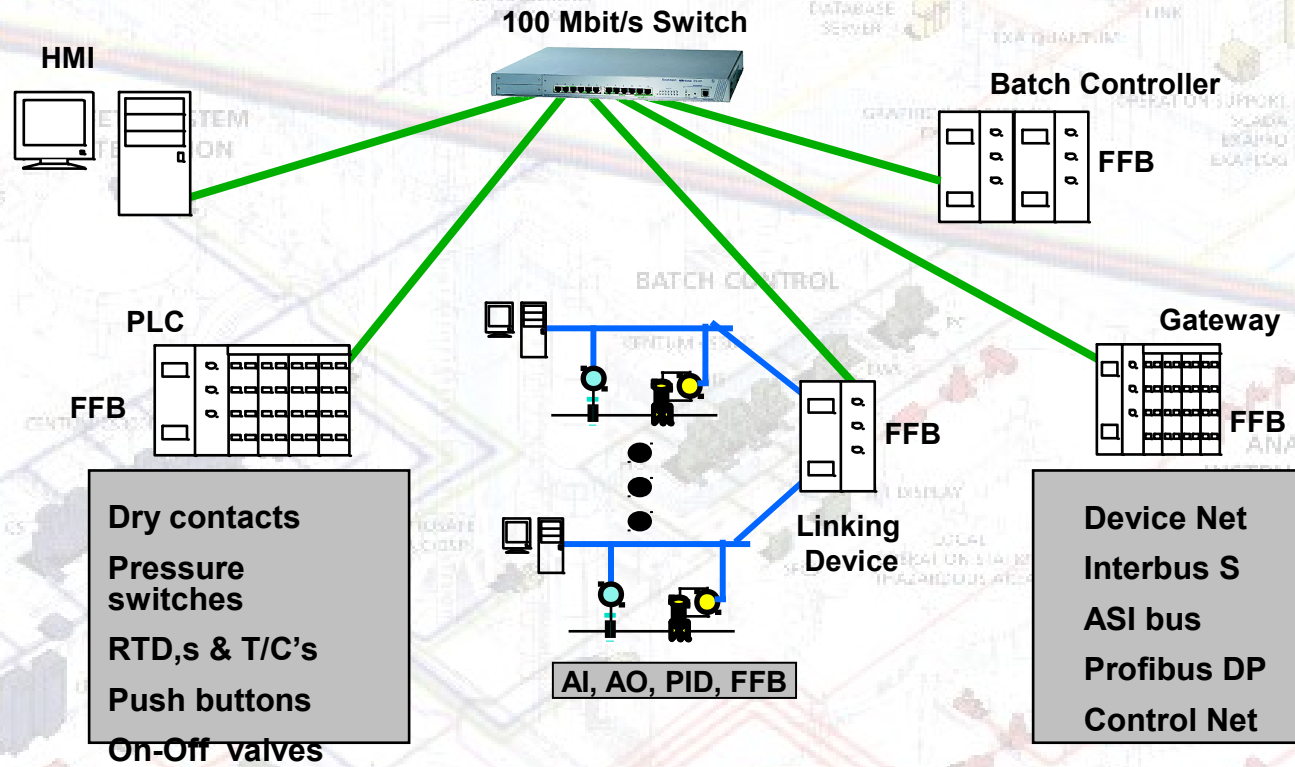


- ◆ Precise timing of block execution - cyclic
- ◆ Function Block communication over the bus is immediate



FOUNDATION™ Fieldbus

◆ Designed for total plant automation - control and automation





High Speed Ethernet (HSE) - summary

- ◆ **Cost-effective, high-speed, plant-wide backbone**
- ◆ **Standard Ethernet technology running at 100 Mbit/s**
 - ◆ Availability of standard Ethernet equipment
 - ◆ Flexible Function Blocks
 - ◆ HSE field device running standard function blocks
- ◆ **Fault tolerant communications and linking devices**
- ◆ **Bridging of multiple H1 networks on a linking device**
- ◆ **Interface to other protocols through gateways**

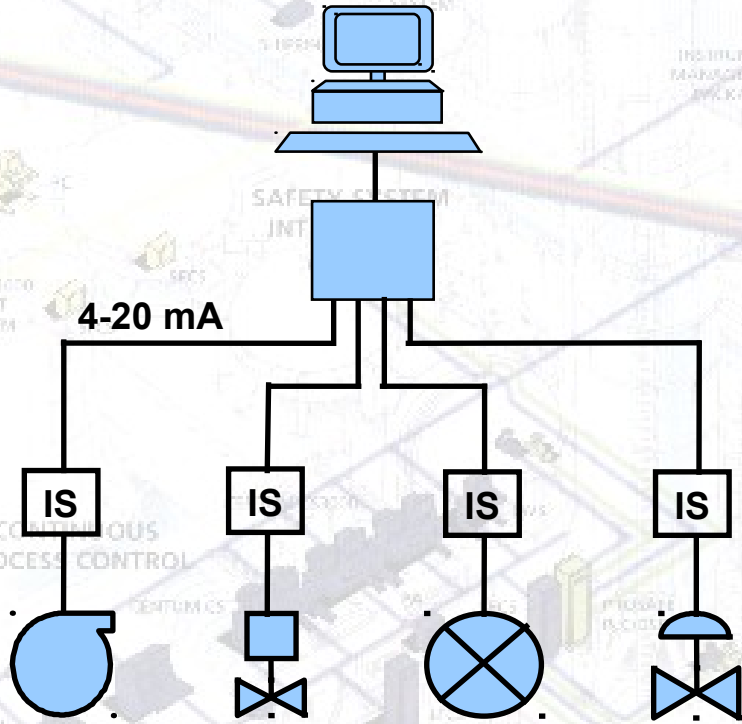




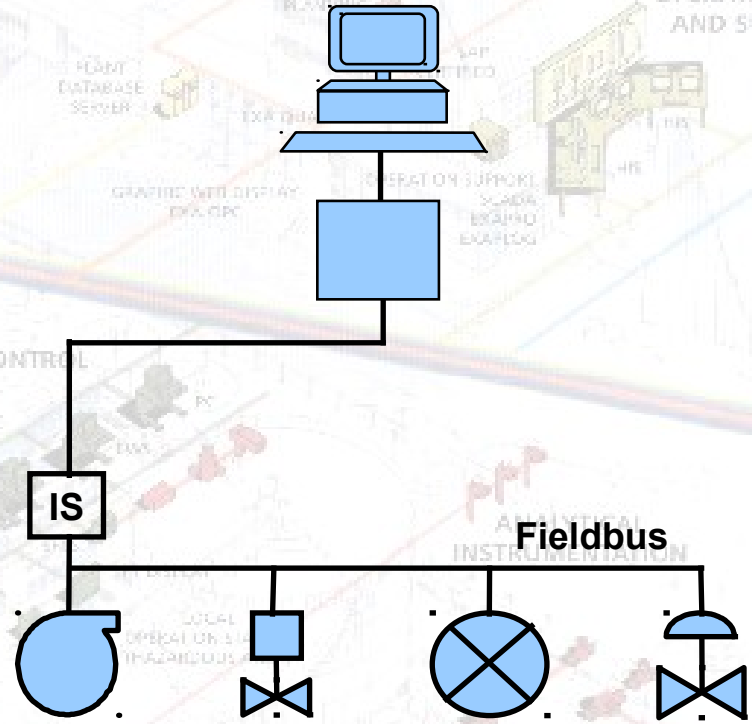
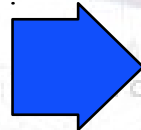
FOUNDATION™ Fieldbus Impact on Engineering and Installation



Simplified engineering and installation

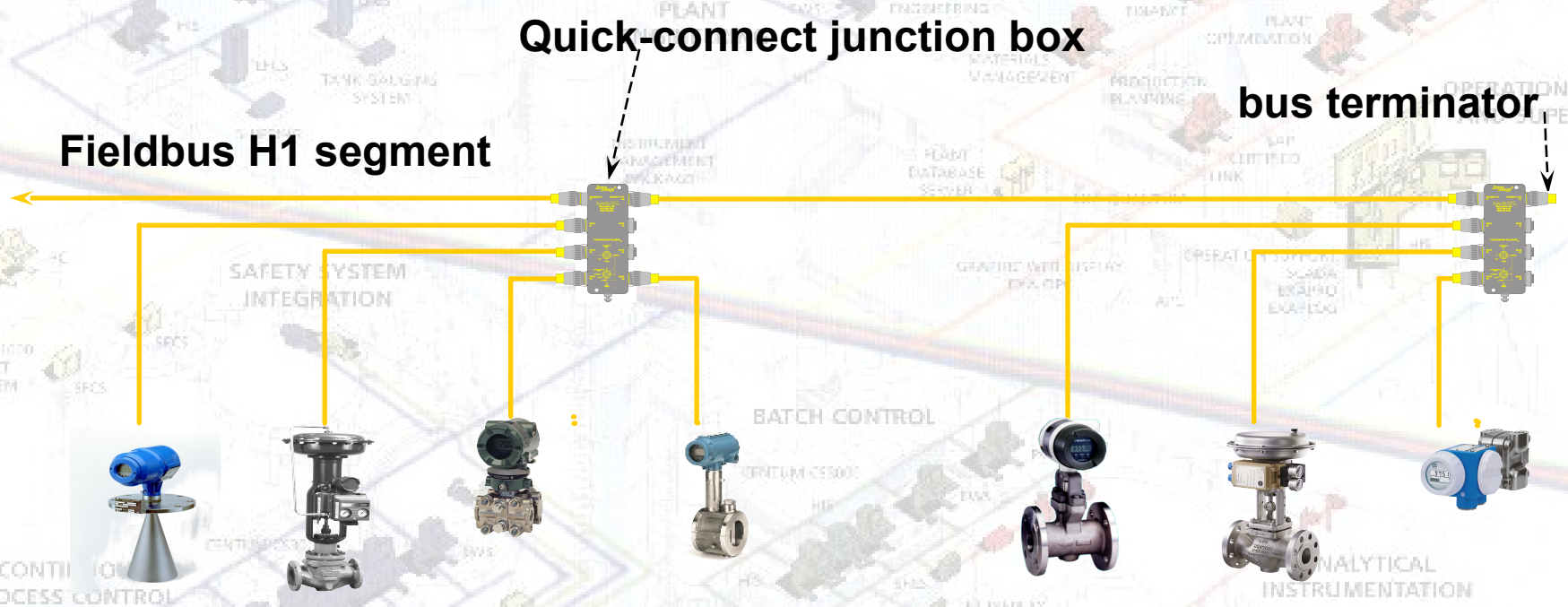


Traditional 4-20 mA wiring,
one IS barrier, one pair
for each device



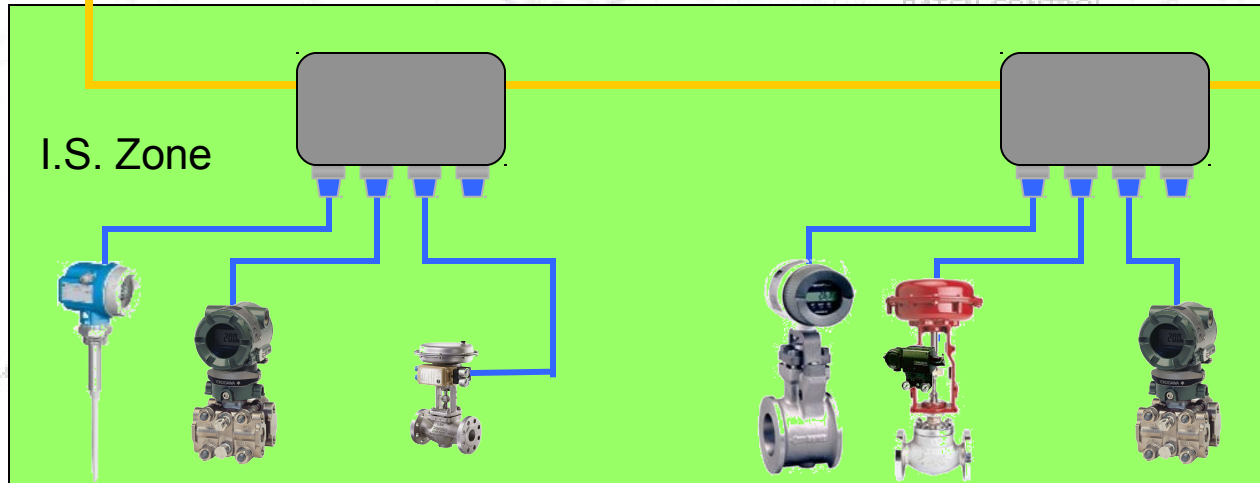
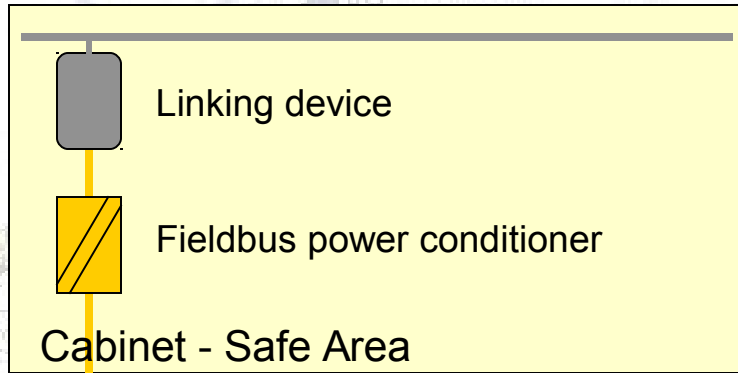
One IS barrier, one pair
for many devices

Fieldbus cabling concept



- ◆ Provides flexibility in “Plug and Play”
 - ◆ General purpose and Intrinsic Safe concepts
 - ◆ Monitors bus voltage and current
 - ◆ Detects short circuits and other wiring problems

Multi-barrier concept by Turck



- ◆ Multiple EEx-e / EEx-i barriers for improved solutions for Zone 1 hazardous areas
- ◆ Up to 4 devices per barrier
- ◆ Typically up to 12 devices per segment



Impact on Engineering and Installation

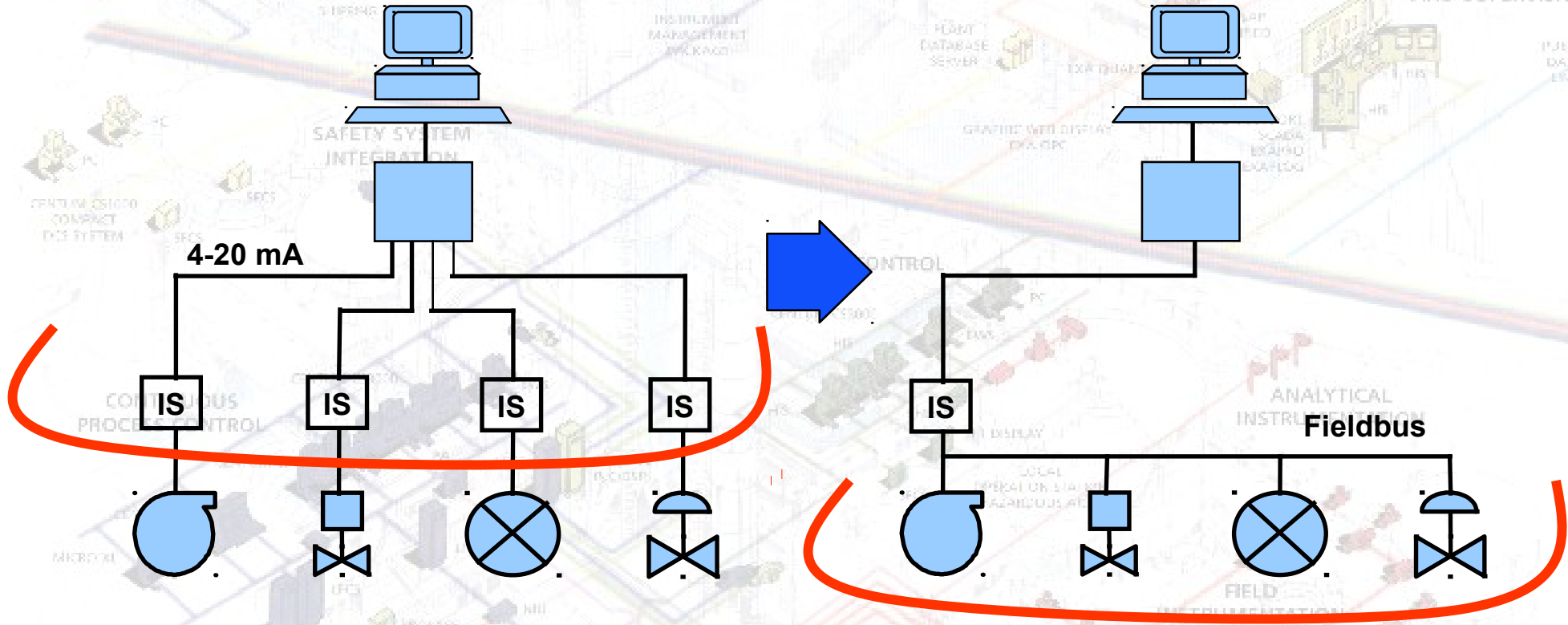
- ◆ **Increased capabilities due to full digital communications**
 - ◆ Less devices required - less process intrusions
 - ◆ Reduced wiring and wire terminations - multiple devices on one wire
 - ◆ Less engineering and cabling check-out
- ◆ **Increased freedom in selecting suppliers - interoperability**
 - ◆ Unified configuration and device management tools - self-documenting
 - ◆ Download off-line configured network/device configuration
 - ◆ Simpler and significantly faster commissioning
- ◆ **Reduced loading on control room equipment**
 - ◆ Distribution of some control and input/output functions to field devices
 - ◆ Smaller control room footprint
 - ◆ Simpler engineering effort



FOUNDATION™ Fieldbus Impact on Operations



Expanding the view of the process

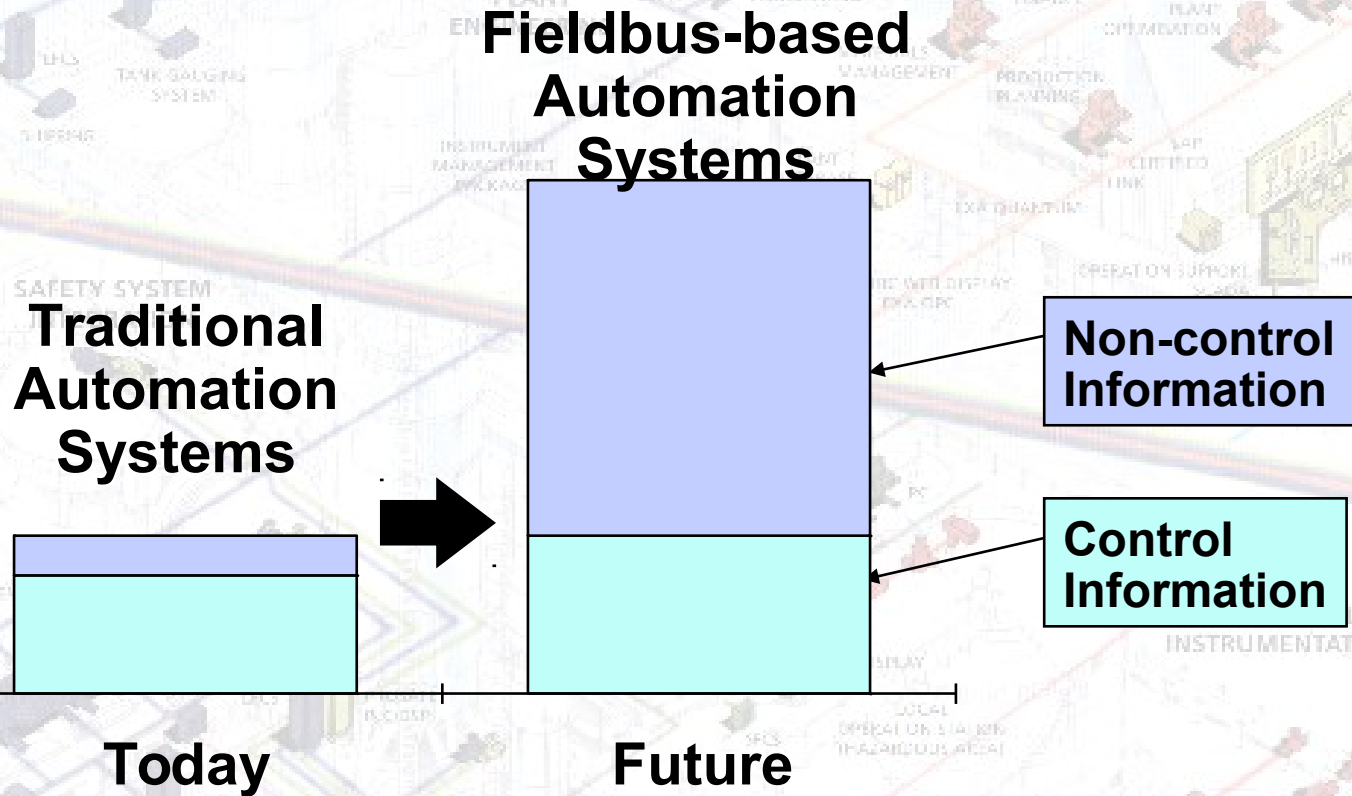


Utilising the intelligence of the field device

- ◆ On-board computing power enables step changes in functionality
- ◆ Become the window to the process
- ◆ Become “information servers” in the field based architecture
- ◆ Become an integral part of the “system”

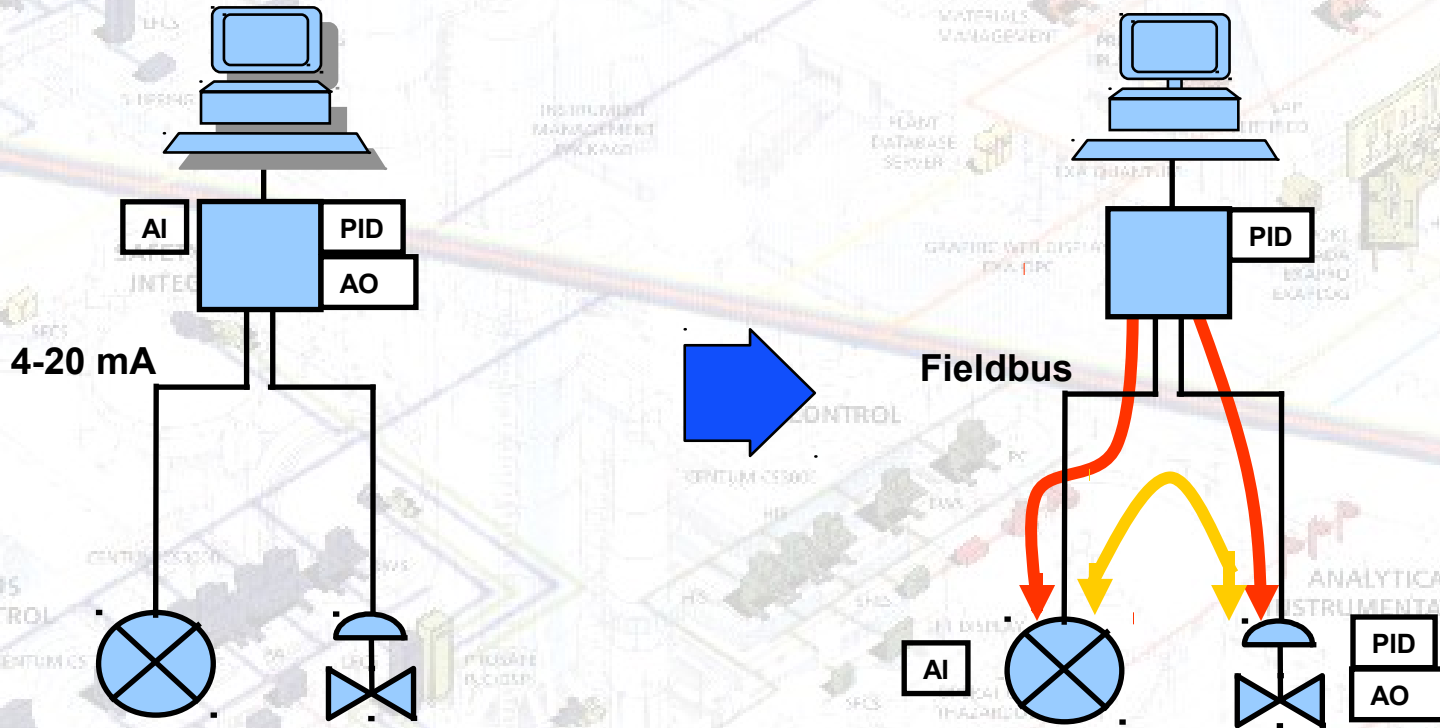


Increased process information



◆ **Path to integrated Plant Resource Management**

Control functions migrate into the field

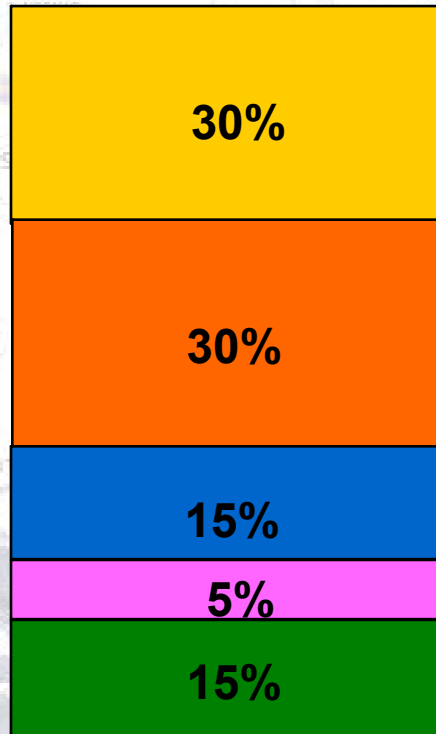


In today's systems, control functions reside in central controllers.

all Fieldbus enables control and I/O functions to be distributed to field instruments.

Sources of process variability

All control loops



Causes of variability:

Poor tuning

Poor field device performance

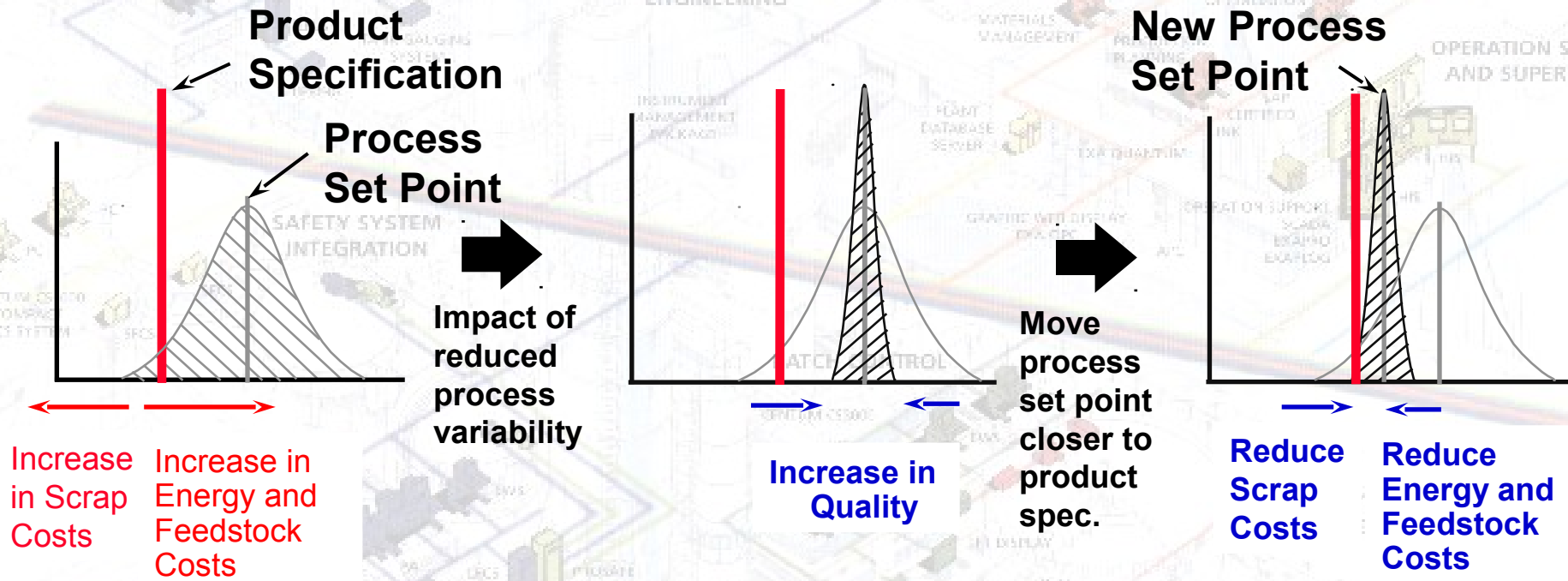
Control strategy design

Poor process design

Running properly

Source: Entech - Results from audits of over 300 DCS installations

Cost savings through improved stability



- ◆ Significant feedstock reduction; virtually no scrap costs
- ◆ Improved plant productivity
- ◆ Higher, more consistent final product quality



Impact on Operations

- ◆ **Improved process performance**

- ◆ Improved accuracy of measurement

- ◆ **“Control Anywhere”**

- ◆ Tighter control, improved responsiveness and reduced process variability
- ◆ Reduced raw materials usage - less wastage
- ◆ Stabilised product quality

- ◆ **Expanded view of the instrumentation**

- ◆ Real time process data includes status information
- ◆ Improved process availability
- ◆ Unified Device Management Tools
 - ◆ Consistent device configuration and calibration

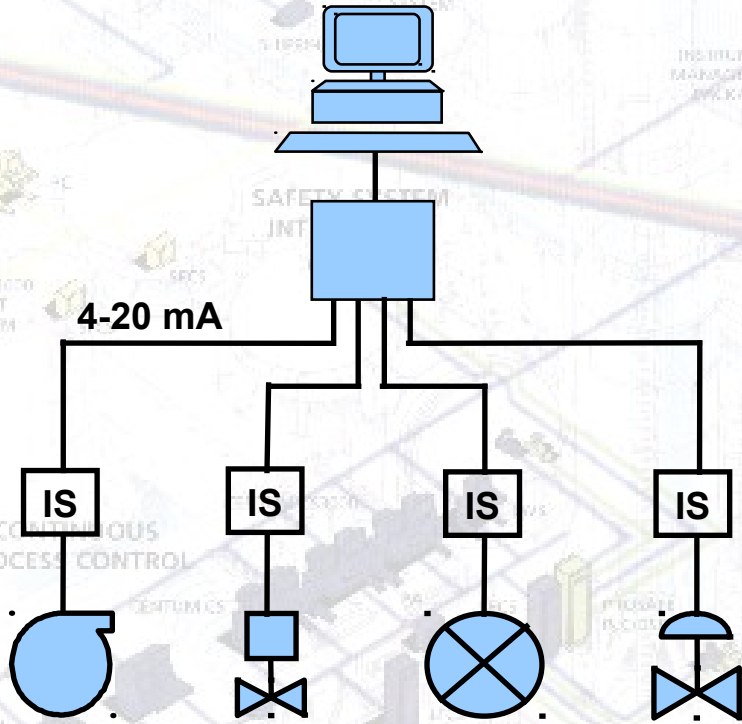




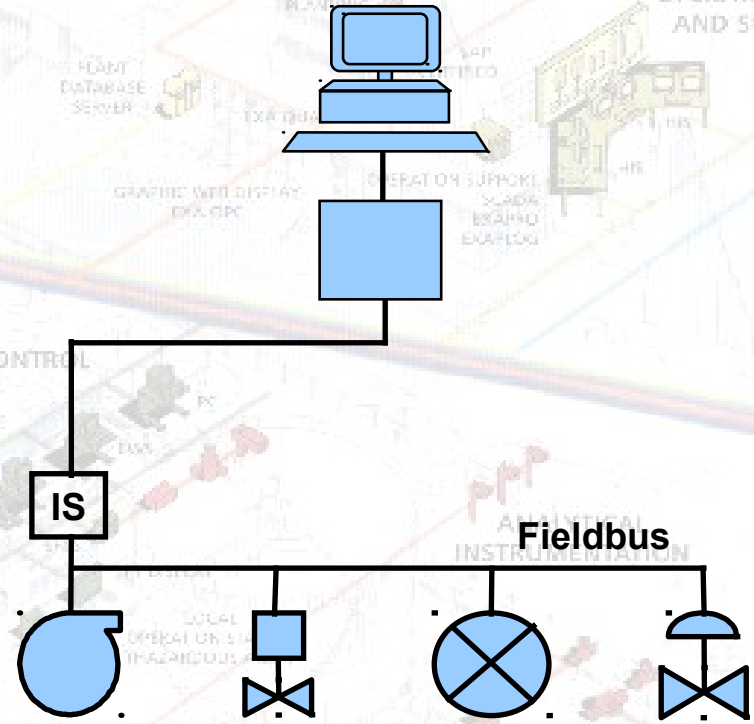
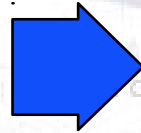
FOUNDATION™ Fieldbus Impact on Maintenance



Simplified maintenance



Traditional 4-20 mA wiring, one Process Value

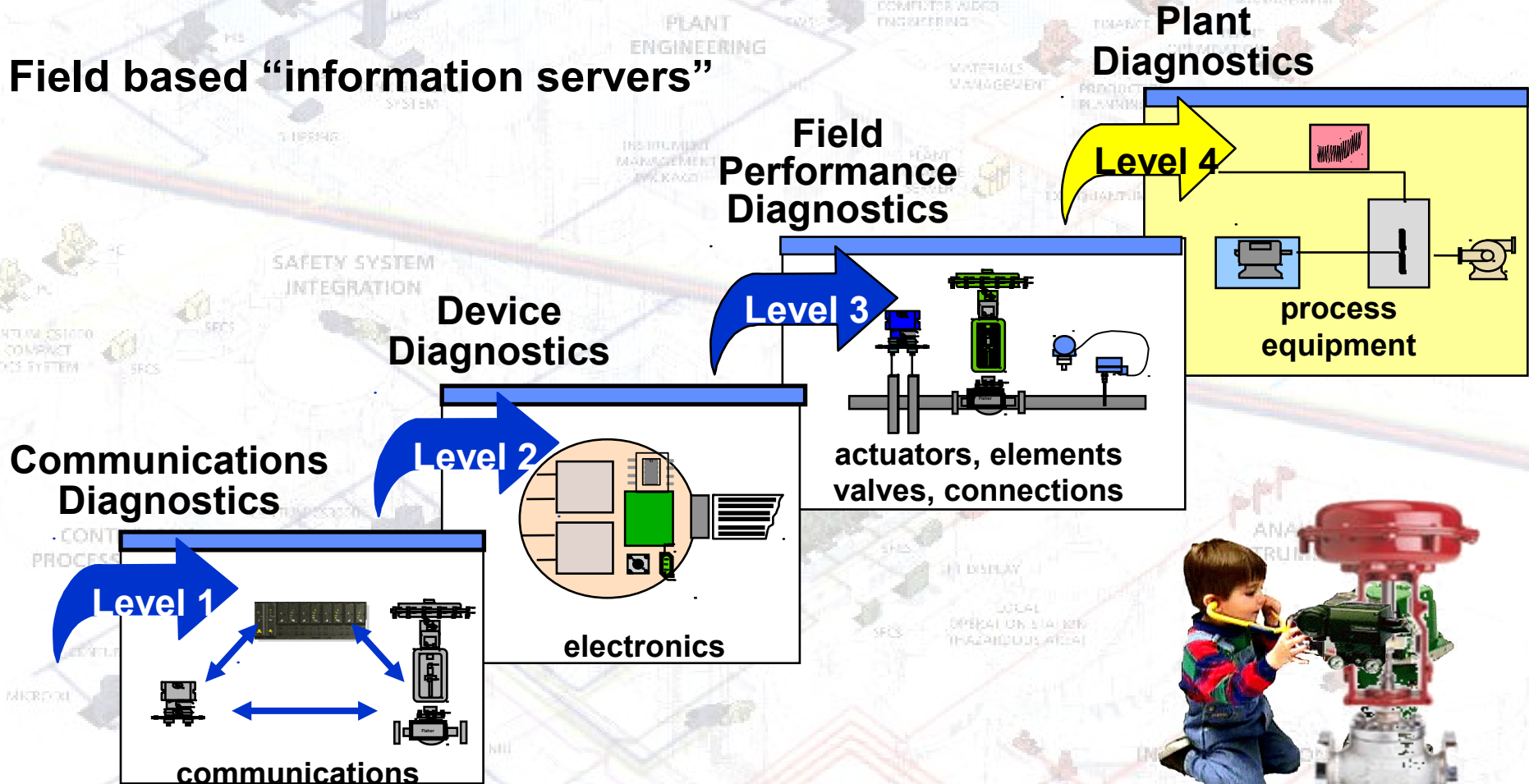


Mode, Value, Status, Alarms, Trends



Path to Plant Resource Management

Field based "information servers"



Field based information server

- ◆ **Auto-tuning function**
 - ◆ “Matches” positioner with the valve
- ◆ **Actual valve position feedback**
 - ◆ Tight shut-off
 - ◆ Limit switches
- ◆ **Valve travel accumulation**
 - ◆ Valve travel alerts
 - ◆ Prevents packing leakage's
- ◆ **Air supply pressure monitoring**
- ◆ **Maintenance history**
- ◆ **25:1 “data explosion” in HART® environment**
- ◆ **200:1 “data explosion” in Fieldbus environment**



Impact on Maintenance

◆ Field device has on-board diagnostics

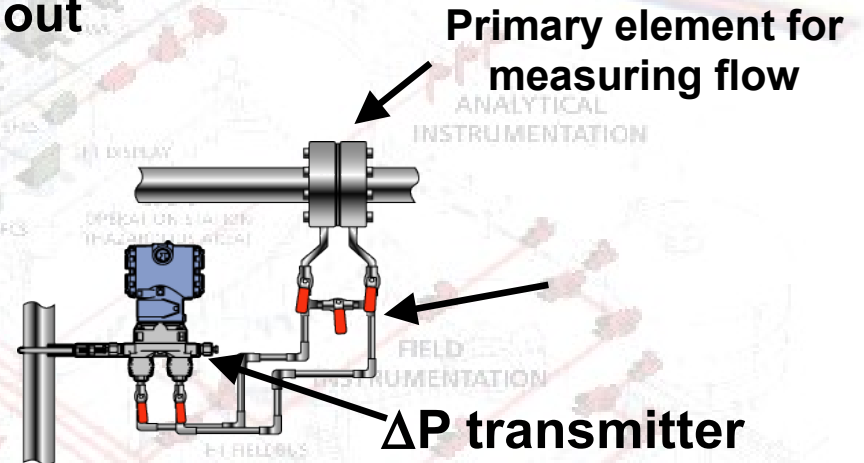
- ◆ Increased measurement reliability and availability
- ◆ Eliminates unscheduled downtime

◆ Trouble shoot field devices from central work station

- ◆ Eliminates unnecessary trips to the field
- ◆ Problem identification before getting out
- ◆ Reduced effort for field calibration

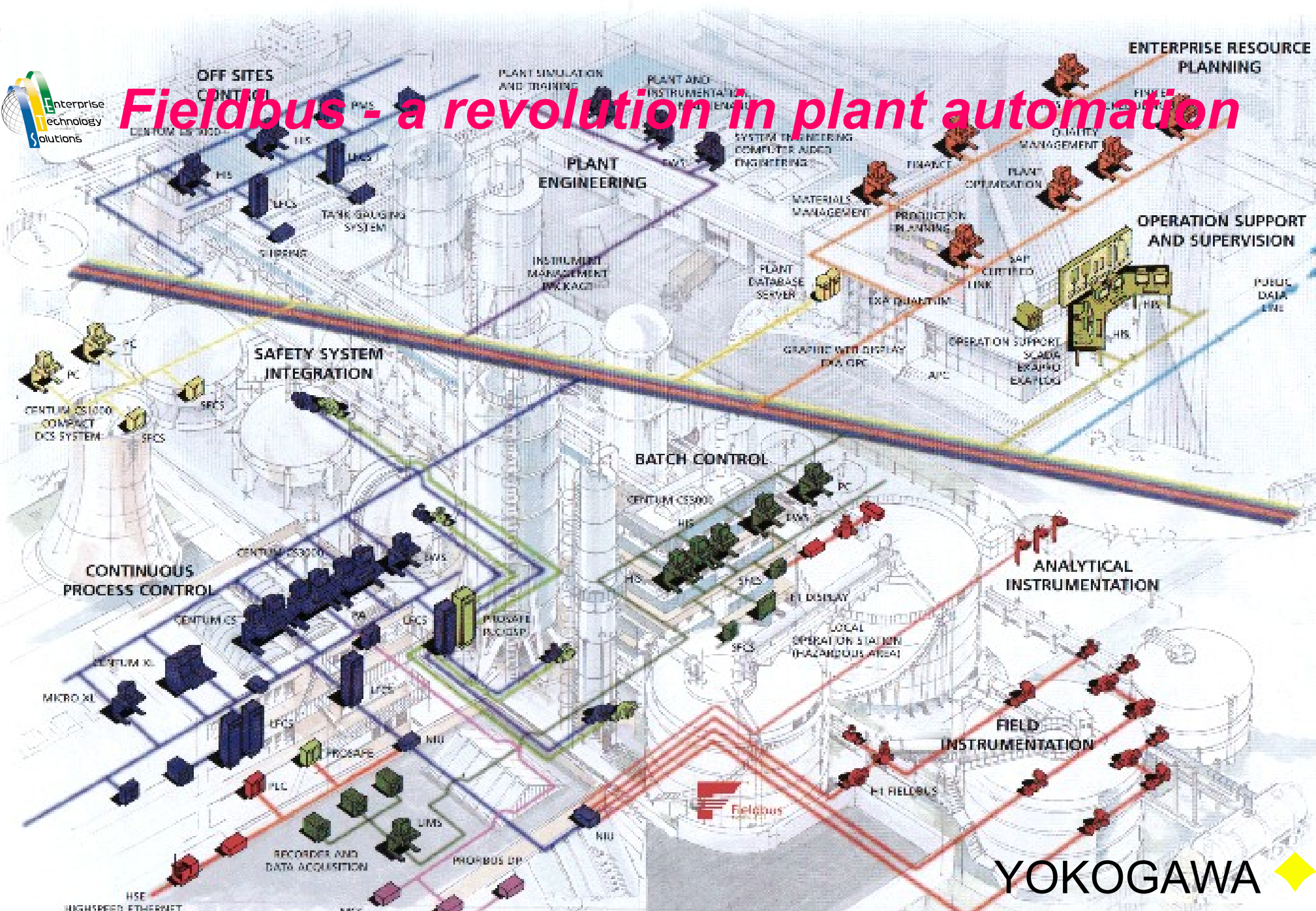
◆ Advanced diagnostics

- ◆ Clogged impulse line detection
- ◆ Transducer Block implementation





Fieldbus - a revolution in plant automation



YOKOGAWA 